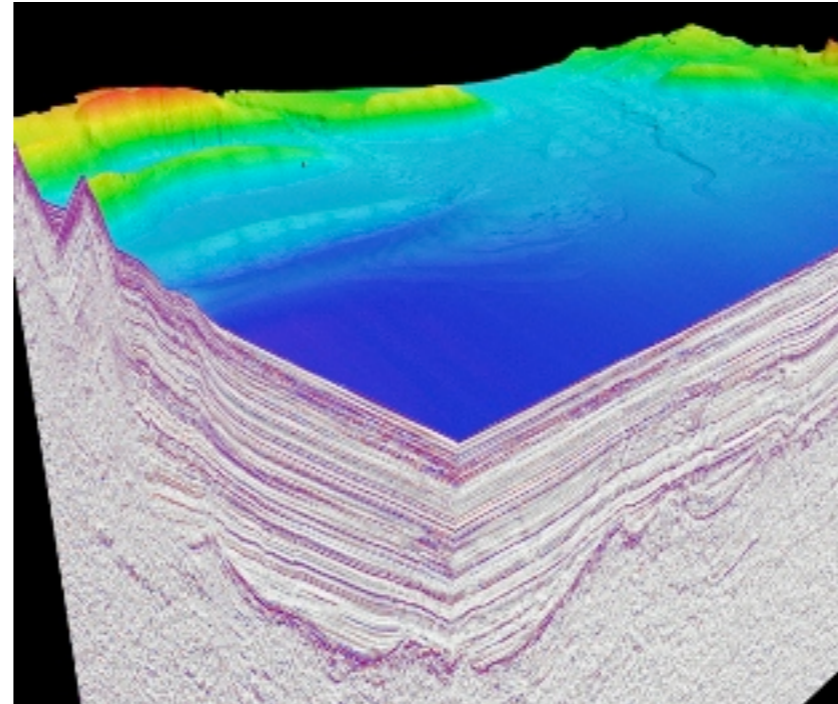
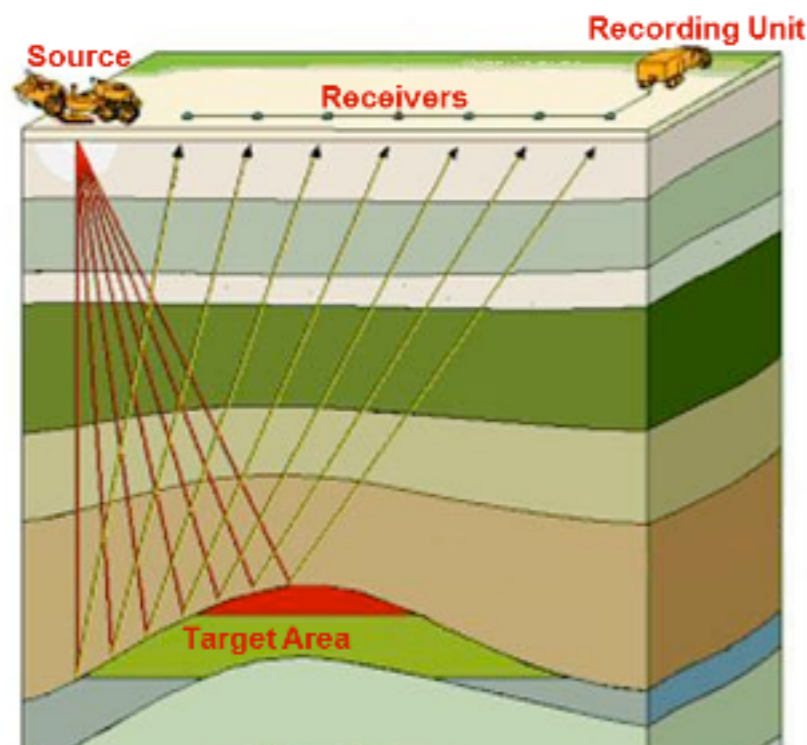


# Accelerate The Stencil Computation by Time-skewing

Muhong Zhou

\*The importance of **forward modeling**:

1. It can be used to generate synthetic seismograms with the acquired seismic data
2. To develop models addressing the problems of structure and stratigraphy during the interpretation of seismic data
3. To simulate the seismic response that would occur if the target objectives were met
4. ...



\* [http://www.arcis.com/Satinder/PDFs/INTRODUCTION%20TO%20TLE%20SPECIAL%20SECTIONS/Intro\\_Seismic\\_Modeling\\_TLE\\_May09.pdf](http://www.arcis.com/Satinder/PDFs/INTRODUCTION%20TO%20TLE%20SPECIAL%20SECTIONS/Intro_Seismic_Modeling_TLE_May09.pdf)  
[figures]: <http://www.tgs.com/geophysical/onshore-seismic-data/seismic-acquisition-basics.aspx>

The wave propagation problem (**forward modeling**)

Wave Equation:

$$\frac{1}{C^2} U_{tt}(t, \vec{X}) - \nabla^2 U(t, \vec{X}) = 0 \quad t \in [0, T], \vec{X} \in [0, X] \times [0, Y] \times [0, Z]$$

Initial Condition

$$\frac{\partial U}{\partial t}(0, \vec{X}) = 0, U(0, \vec{X}) = \begin{cases} 1 & \vec{X} = (\frac{X}{2}, \frac{Y}{2}, \frac{Z}{2}) \\ 0 & \text{else} \end{cases}$$

Boundary Condition

$$U(0, \vec{X}) = 0 \text{ if } x = 0 \text{ or } X, y = 0 \text{ or } Y, z = 0 \text{ or } Z$$

Finite difference scheme(2-4) and corresponding stencil codes for the elastic wave equation

$$\begin{aligned}
 & \frac{1}{C^2} \frac{U(t+\Delta t, \vec{X}) - 2U(t, \vec{X}) + U(t-\Delta t, \vec{X})}{\Delta t^2} \\
 = & \left( \frac{-5}{2\Delta x^2} + \frac{-5}{2\Delta y^2} + \frac{-5}{2\Delta z^2} \right) U(t, \vec{X}) \\
 & + \frac{4}{3\Delta x^2} (U(t, x + \Delta x, y, z) + U(t, x - \Delta x, y, z)) \\
 & + \frac{4}{3\Delta y^2} (U(t, x, y + \Delta y, z) + U(t, x, y - \Delta y, z)) \\
 & + \frac{4}{3\Delta z^2} (U(t, x, y, z + \Delta z) + U(t, x, y, z - \Delta z)) \\
 & - \frac{1}{12\Delta x^2} (U(t, x + 2\Delta x, y, z) + U(t, x - 2\Delta x, y, z)) \\
 & - \frac{1}{12\Delta y^2} (U(t, x, y + 2\Delta y, z) + U(t, x, y - 2\Delta y, z)) \\
 & - \frac{1}{12\Delta z^2} (U(t, x, y, z + 2\Delta z) + U(t, x, y, z - 2\Delta z))
 \end{aligned}$$

$$\begin{aligned}
 U\_in[i][j][k] &= U(t, i * \Delta x, j * \Delta y, k * \Delta z) \\
 U\_out[i][j][k] &= U(t - \Delta t, i * \Delta x, j * \Delta y, k * \Delta z)
 \end{aligned}$$

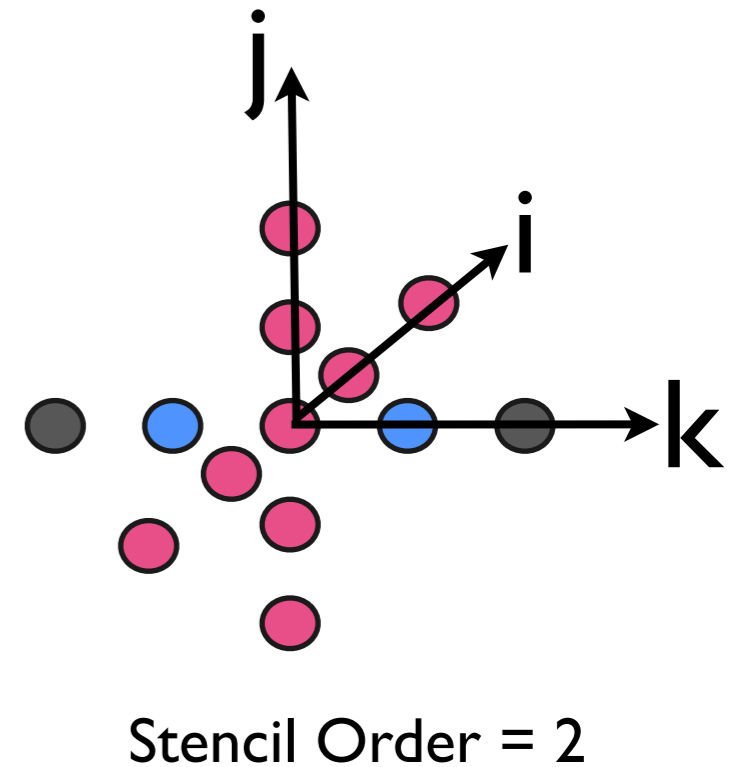
$$\begin{aligned}
 c[0] &= \Delta t^2 \left( \frac{-5}{2\Delta x^2} + \frac{-5}{2\Delta y^2} + \frac{-5}{2\Delta z^2} \right) + 2 \\
 c[1] &= \frac{4\Delta t^2}{3\Delta x^2}, c[2] = \frac{4\Delta t^2}{3\Delta y^2}, c[3] = \frac{4\Delta t^2}{3\Delta z^2} \\
 c[4] &= \frac{-\Delta t^2}{12\Delta x^2}, c[5] = \frac{-\Delta t^2}{12\Delta y^2}, c[6] = \frac{-\Delta t^2}{12\Delta z^2}
 \end{aligned}$$

```

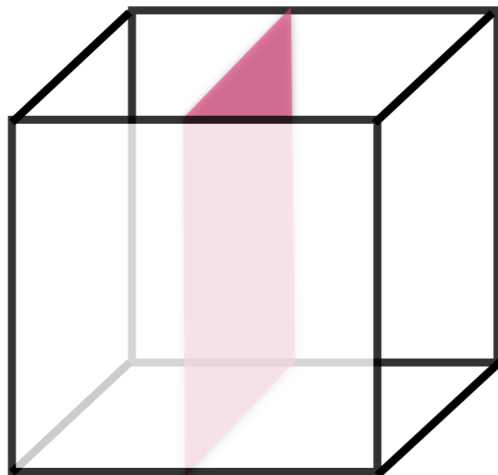
U_out[k][j][i] = -U_out[k][j][i]
                + c[0]*U_in[k][j][i]
                + c[3]*(U_in[k+1][j][i]+U_in[k-1][j][i])
                + c[2]*(U_in[k][j+1][i]+U_in[k][j-1][i])
                + c[1]*(U_in[k][j][i+1]+U_in[k][j][i-1])
                + c[6]*(U_in[k+2][j][i]+U_in[k-2][j][i])
                + c[5]*(U_in[k][j+2][i]+U_in[k][j-2][i])
                + c[4]*(U_in[k][j][i+2]+U_in[k][j][i-2]);
    
```

## Stencil sweep in terms of planes

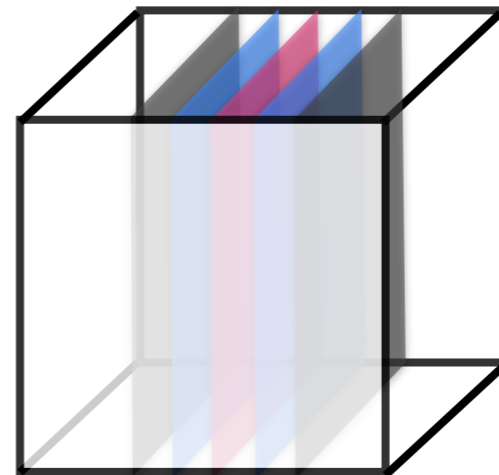
```
for(k = start;k <= end;k++)
  for(j = 1;j < ny;j++)
    for(i = 1;i < nx; i++)
      U_out[k][j][i] = -U_out[k][j][i]
      + c[0]*U_in[k][j][i]
      + c[3]*(U_in[k+1][j][i]+U_in[k-1][j][i])
      + c[2]*(U_in[k][j+1][i]+U_in[k][j-1][i])
      + c[1]*(U_in[k][j][i+1]+U_in[k][j][i-1])
      + c[6]*(U_in[k+2][j][i]+U_in[k-2][j][i])
      + c[5]*(U_in[k][j+2][i]+U_in[k][j-2][i])
      + c[4]*(U_in[k][j][i+2]+U_in[k][j][i-2]);
```



U\_out[k][][[]]

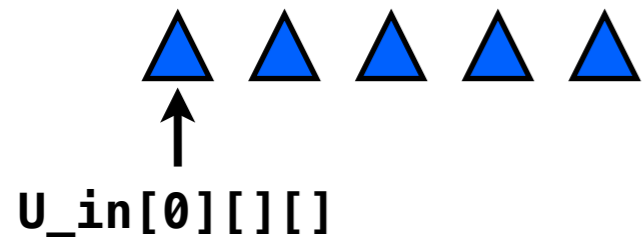


U\_in[k-2:k+2][][[]]



# Naive Implementation

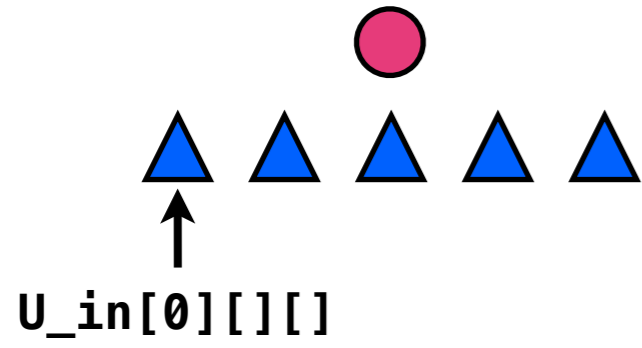
●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$



<http://blog.stuffedcow.net/2013/01/ivb-cache-replacement/>

# Naive Implementation

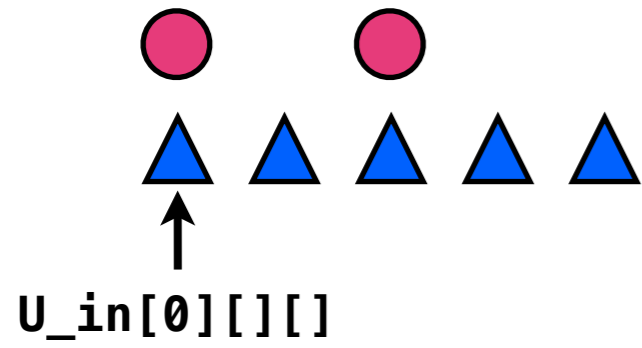
●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$



<http://blog.stuffedcow.net/2013/01/ivb-cache-replacement/>

# Naive Implementation

●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$

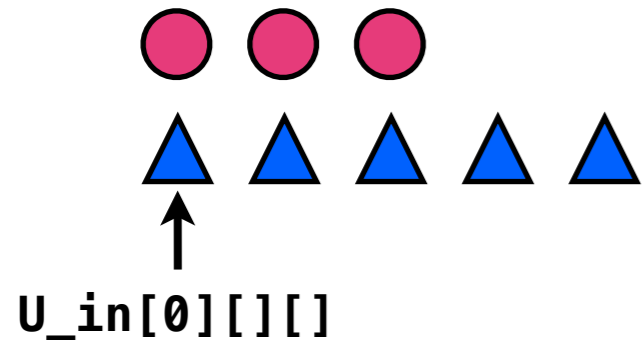


<http://blog.stuffedcow.net/2013/01/ivb-cache-replacement/>



# Naive Implementation

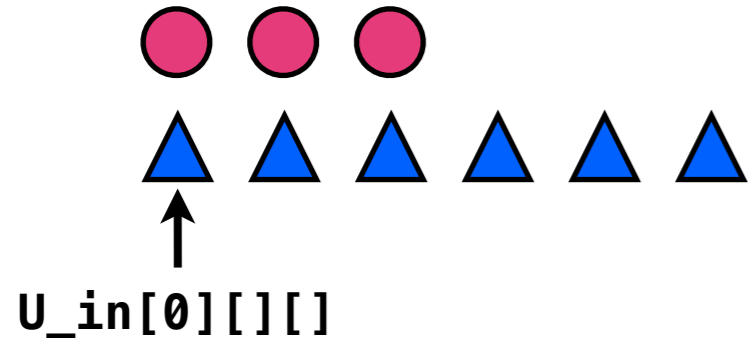
●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$



<http://blog.stuffedcow.net/2013/01/ivb-cache-replacement/>

# Naive Implementation

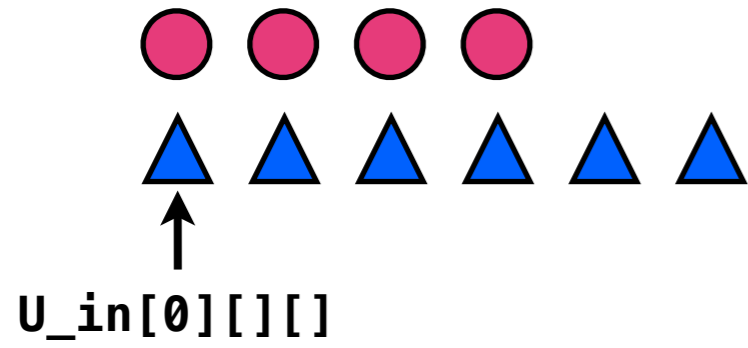
●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$



<http://blog.stuffedcow.net/2013/01/ivb-cache-replacement/>

# Naive Implementation

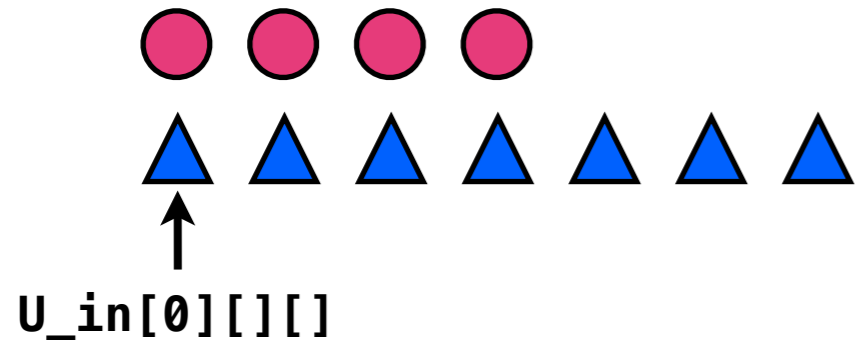
●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$



<http://blog.stuffedcow.net/2013/01/ivb-cache-replacement/>

# Naive Implementation

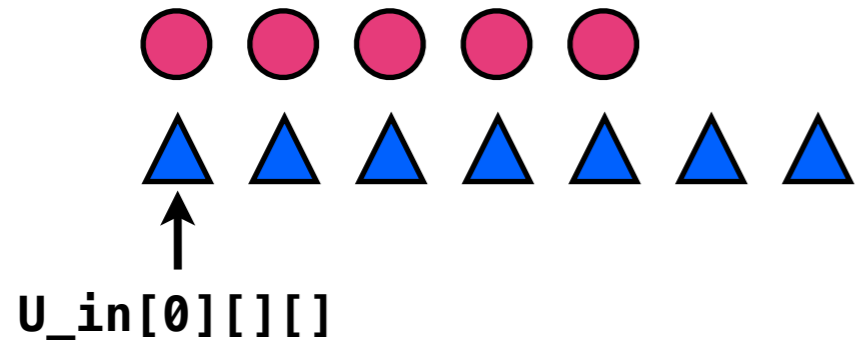
●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$



<http://blog.stuffedcow.net/2013/01/ivb-cache-replacement/>

# Naive Implementation

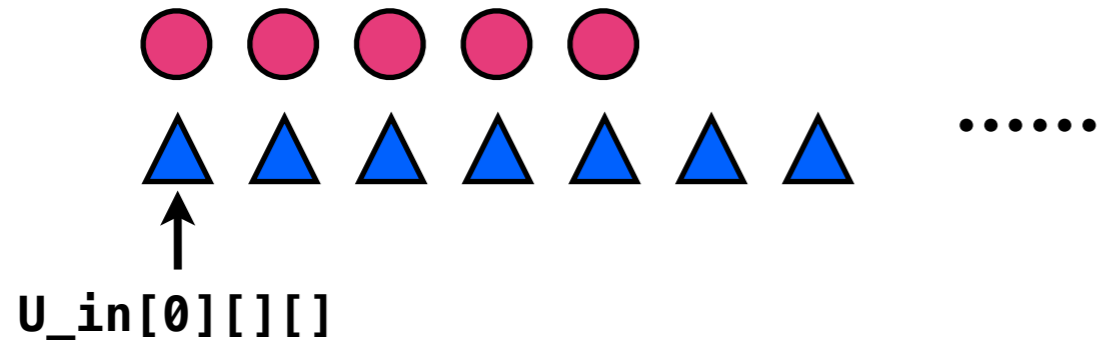
●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$



<http://blog.stuffedcow.net/2013/01/ivb-cache-replacement/>

# Naive Implementation

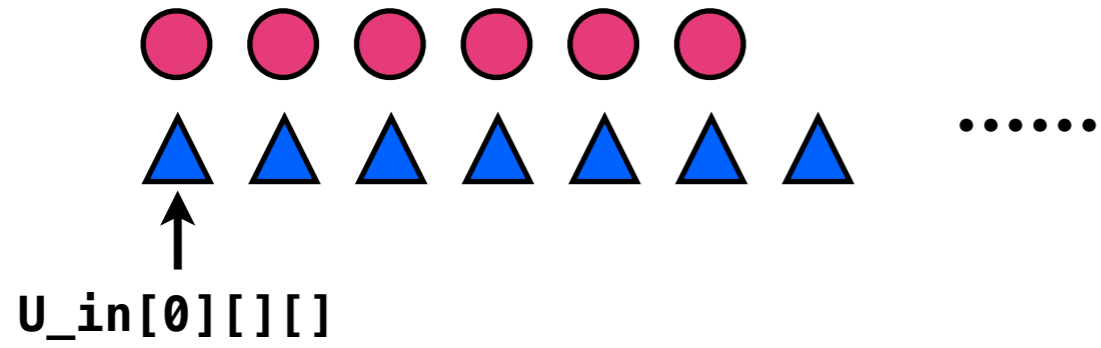
●  $U\_out[k][][[]]$     ▲  $U\_in[k][][[]]$



<http://blog.stuffedcow.net/2013/01/ivb-cache-replacement/>

# Naive Implementation

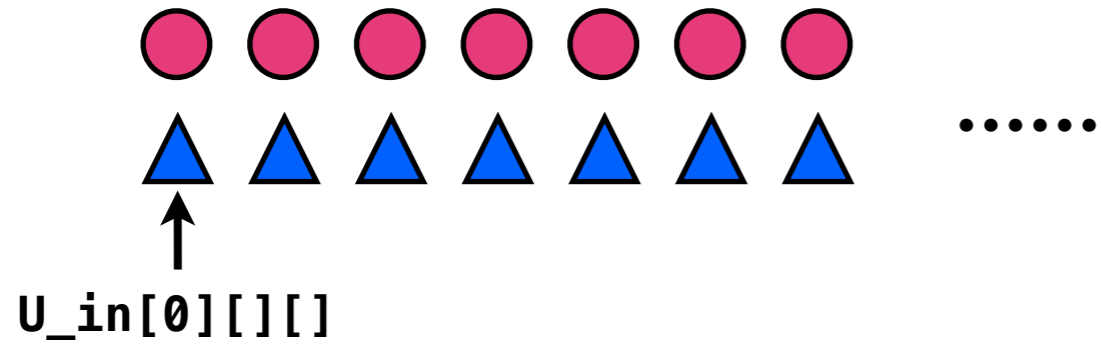
●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$



<http://blog.stuffedcow.net/2013/01/ivb-cache-replacement/>

# Naive Implementation

●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$

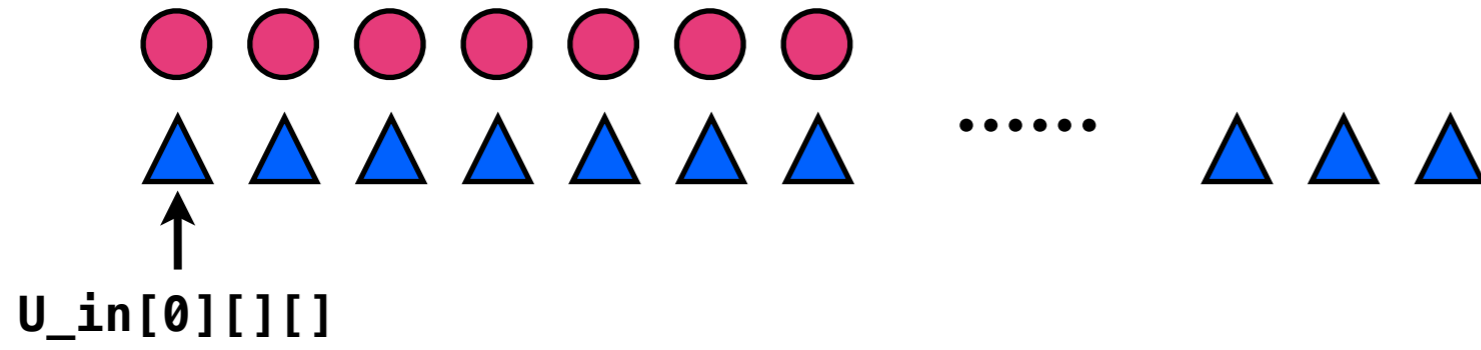


<http://blog.stuffedcow.net/2013/01/ivb-cache-replacement/>



# Naive Implementation

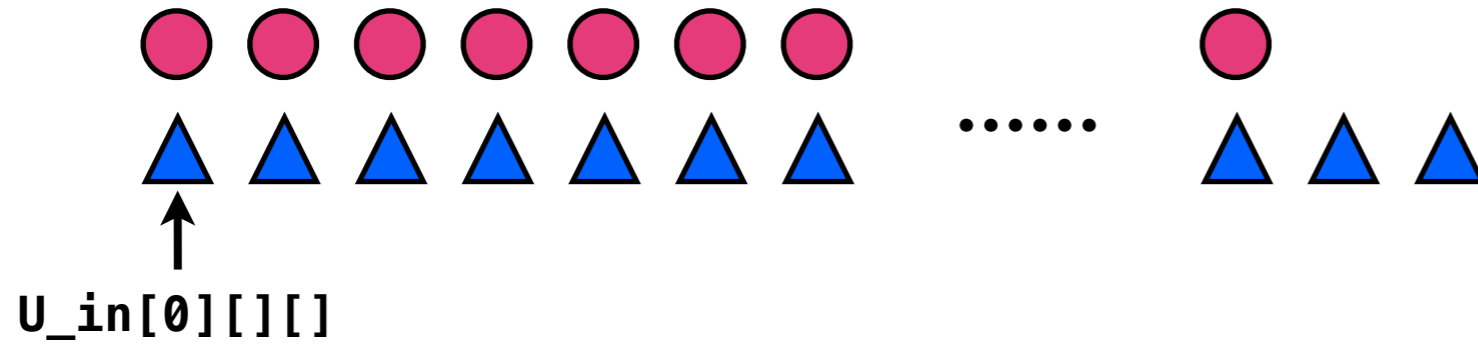
●  $U\_out[k][][[]]$     ▲  $U\_in[k][][[]]$



<http://blog.stuffedcow.net/2013/01/ivb-cache-replacement/>

# Naive Implementation

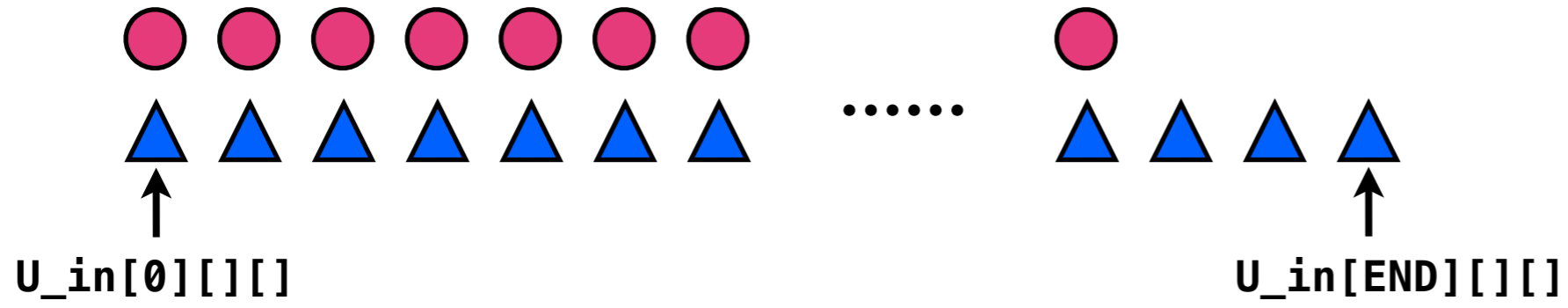
●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$



<http://blog.stuffedcow.net/2013/01/ivb-cache-replacement/>

# Naive Implementation

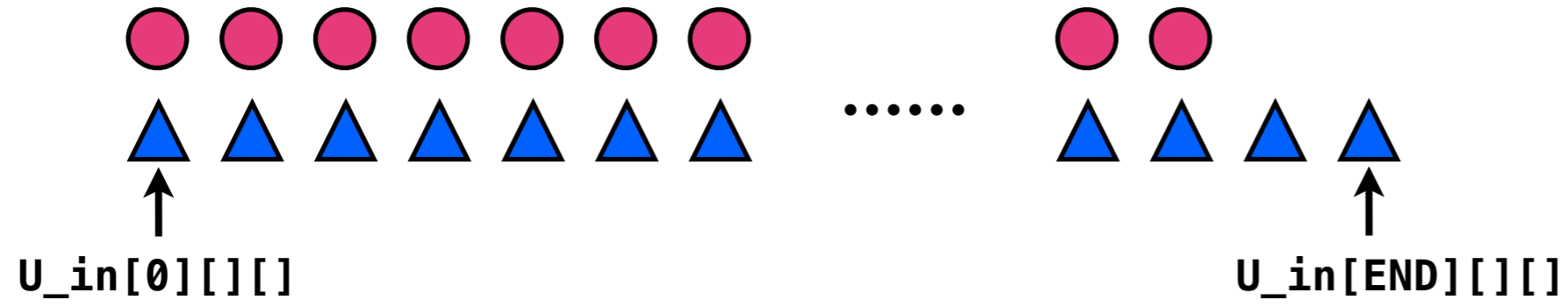
● `U_out[k][][[]]`    ▲ `U_in[k][][[]]`



<http://blog.stuffedcow.net/2013/01/ivb-cache-replacement/>

# Naive Implementation

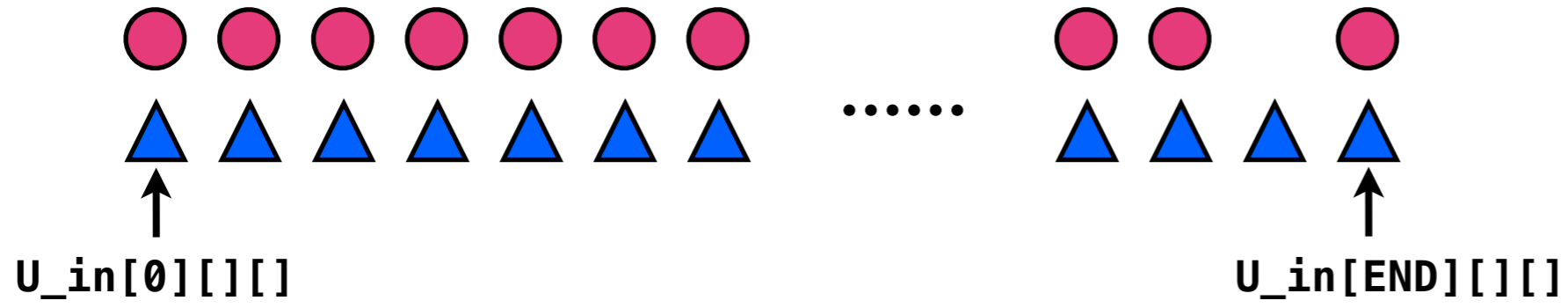
●  $U\_out[k][][[]]$     ▲  $U\_in[k][][[]]$



<http://blog.stuffedcow.net/2013/01/ivb-cache-replacement/>

# Naive Implementation

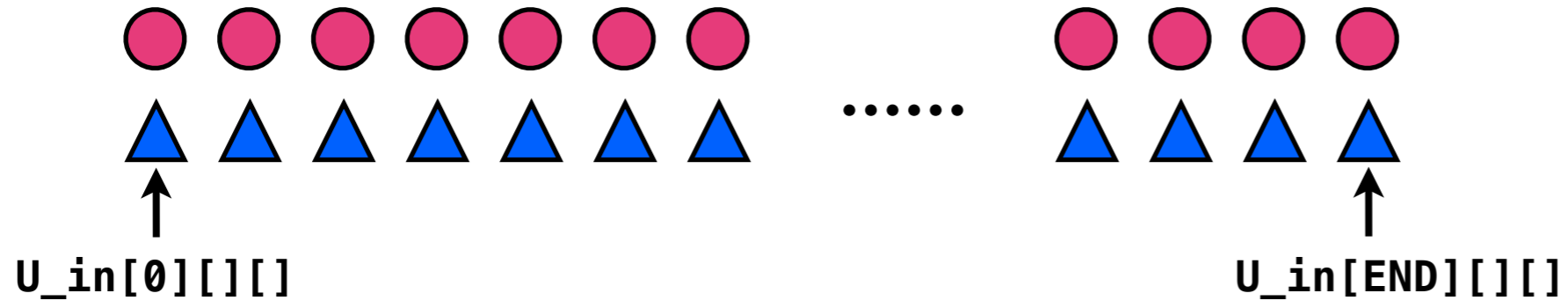
●  $U\_out[k][][[]]$     ▲  $U\_in[k][][[]]$



<http://blog.stuffedcow.net/2013/01/ivb-cache-replacement/>

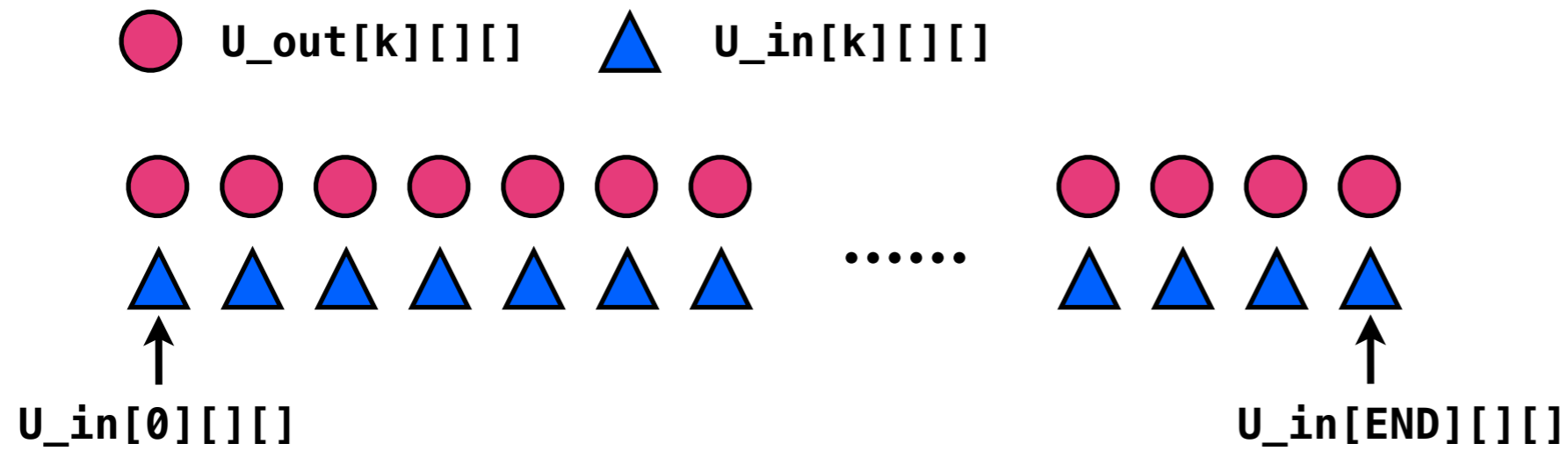
# Naive Implementation

●  $U\_out[k][][[]]$     ▲  $U\_in[k][][[]]$



<http://blog.stuffedcow.net/2013/01/ivb-cache-replacement/>

## Naive Implementation

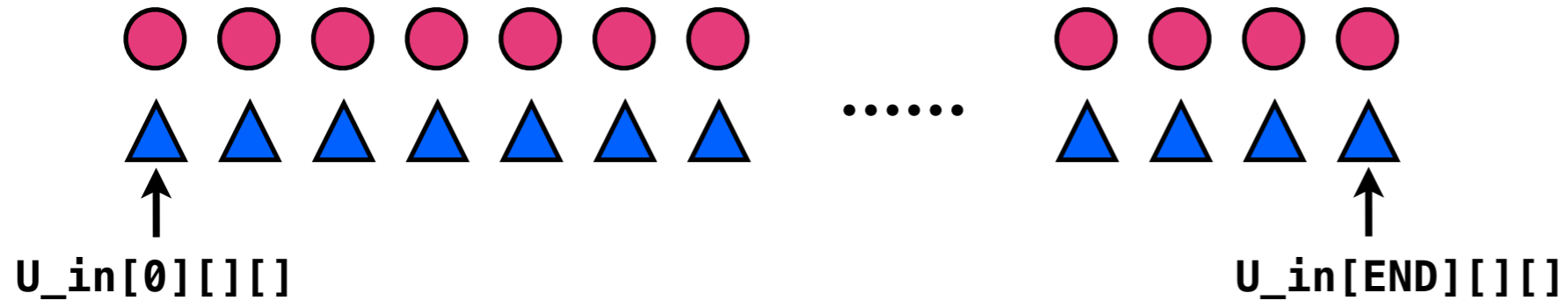


How can I further speed up the code?

<http://blog.stuffedcow.net/2013/01/ivb-cache-replacement/>

# Naive Implementation

●  $U\_out[k][][[]]$     ▲  $U\_in[k][][[]]$

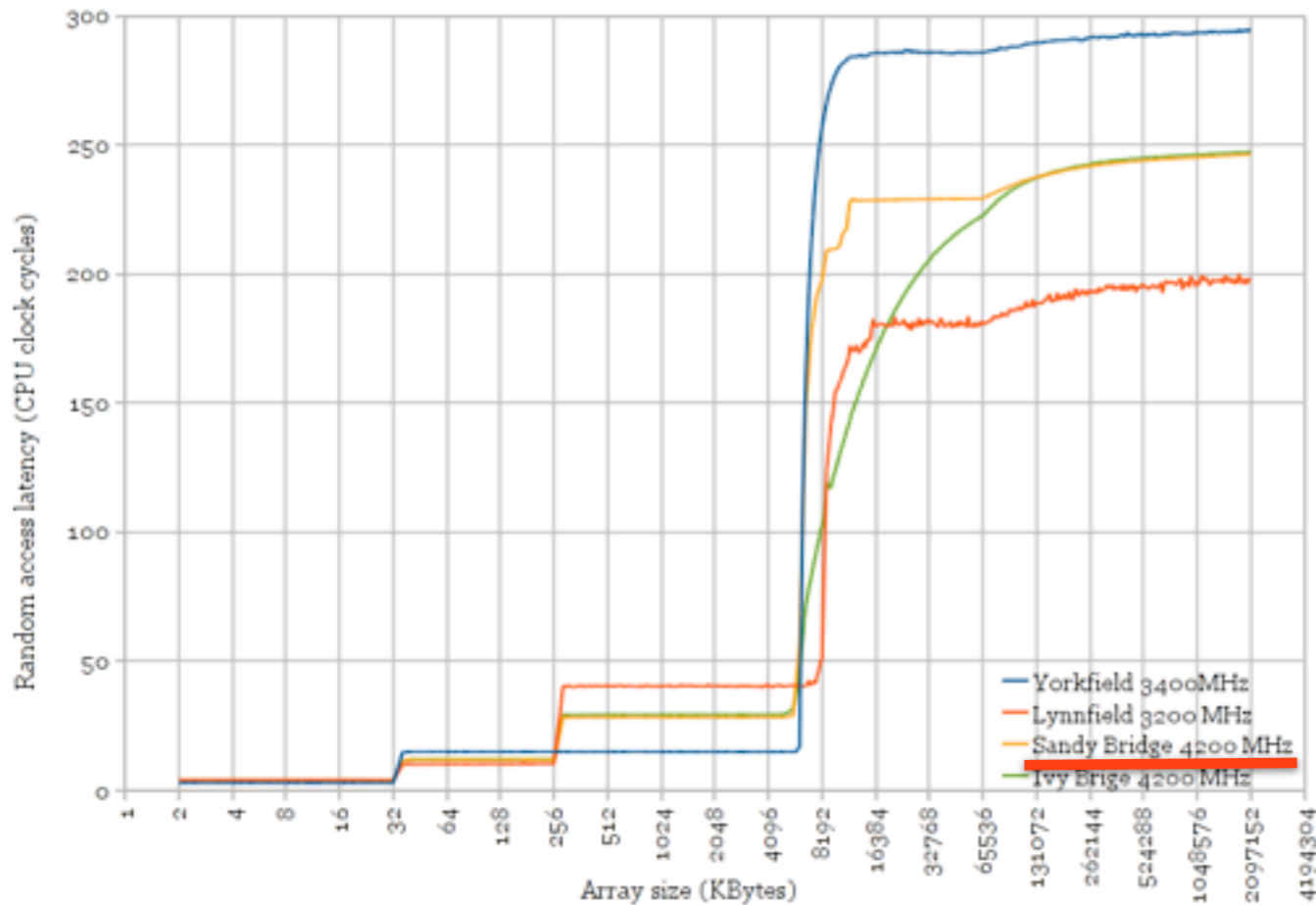
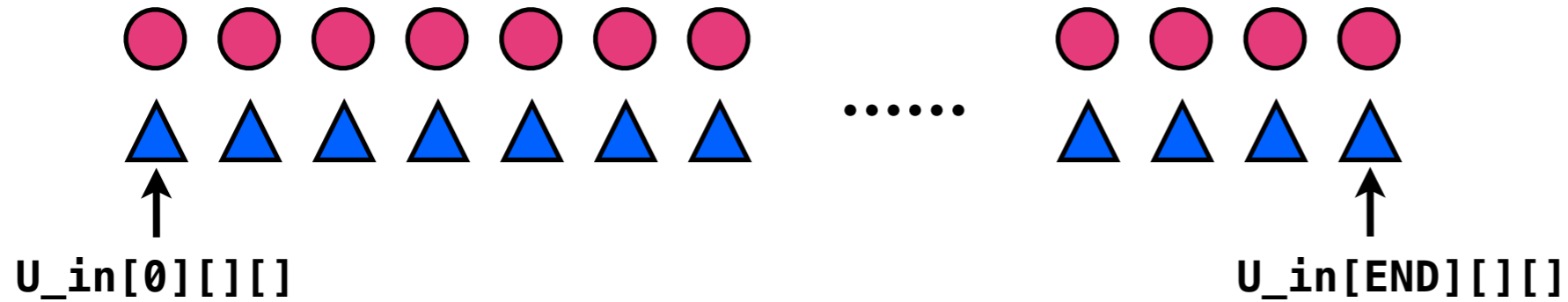


<http://blog.stuffedcow.net/2013/01/ivb-cache-replacement/>



# Naive Implementation

●  $U\_out[k][][[]]$     ▲  $U\_in[k][][[]]$



Accessing Time: L1, L2, L3 < 50 CPU cycles  
RAM 200~250 CPU cycles

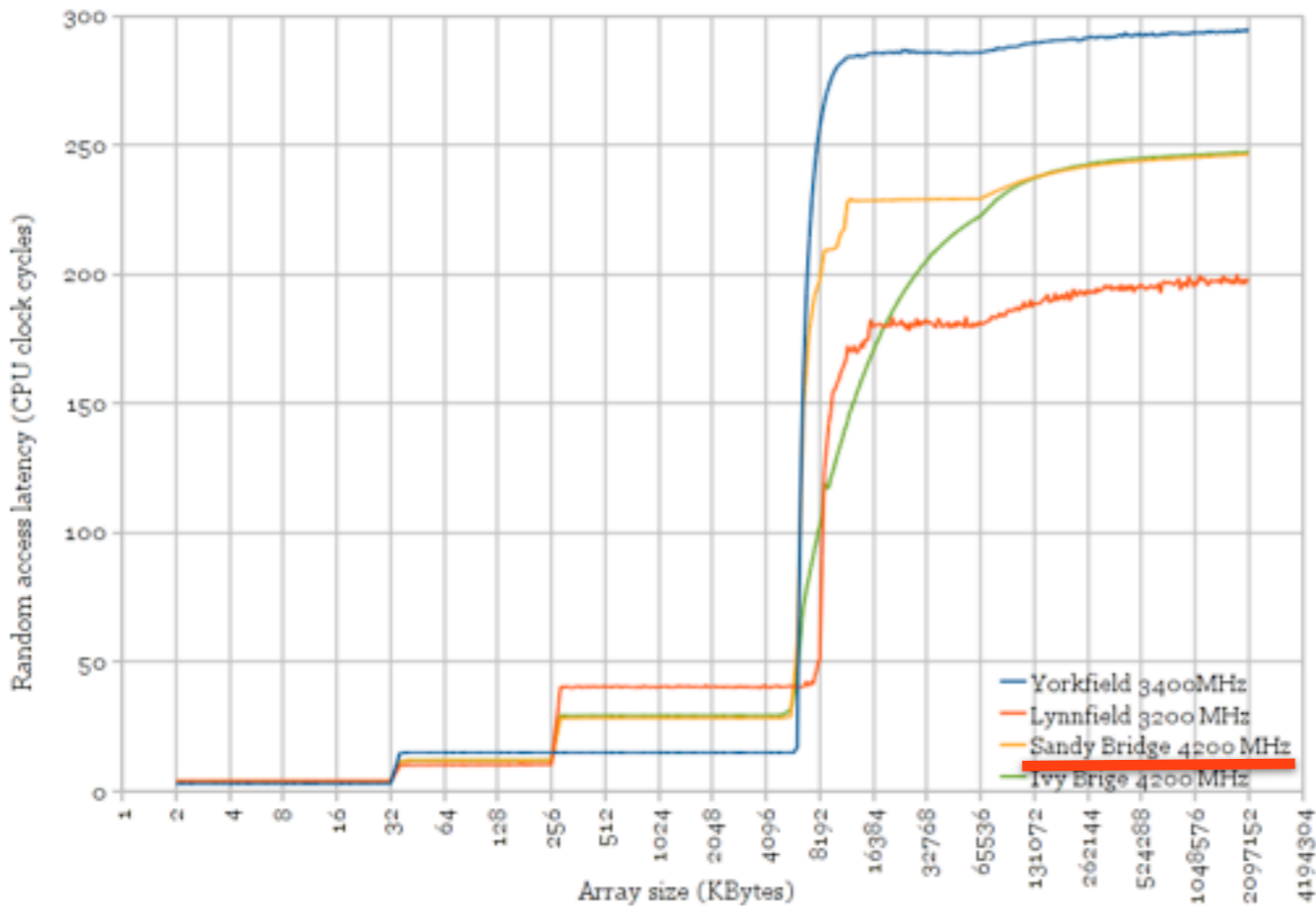
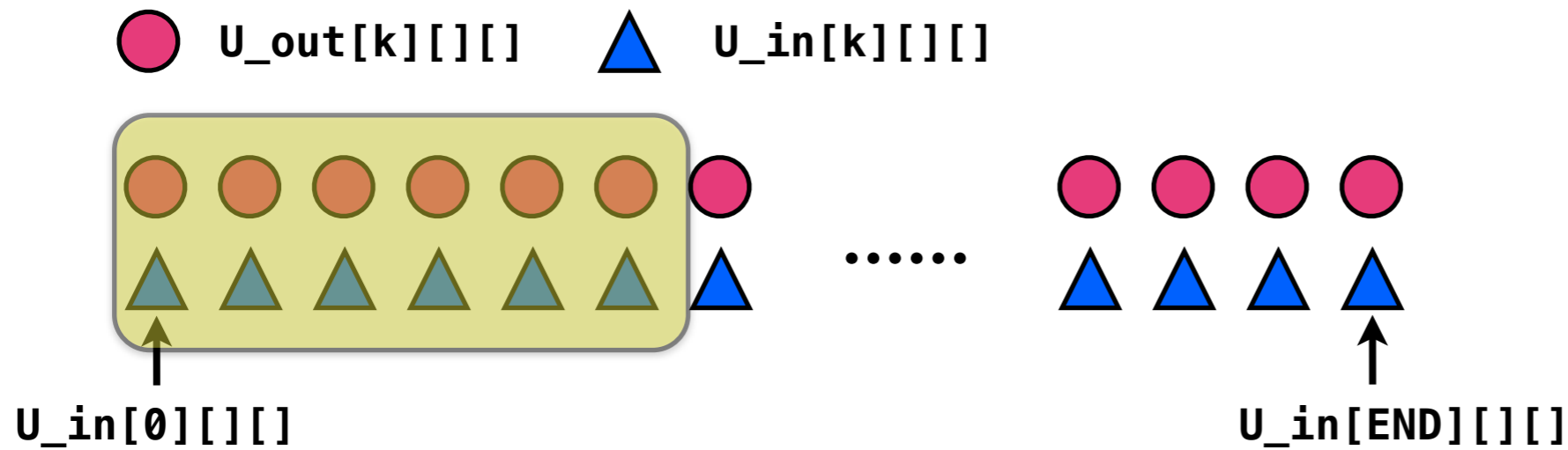
Cache Replacement Policy (FIFO, LFU)  
L3 cache size is 12MB\* shared by 6 cores in one Westmere node(DAVinCI, Rice U)

Consider the array size is 260\*260\*260  
 $12 * 10^6 / 4 / (260 * 260) = 44.379$  (using float)  
It implies that at most 22 planes of each data array can be inserted into the cache.

\* <http://www.cpu-world.com/sspec/Q4/Q4EN.html>

<http://blog.stuffedcow.net/2013/01/ivb-cache-replacement/>

# Naive Implementation



Accessing Time: L1, L2, L3 < **50** CPU cycles  
 RAM **200~250** CPU cycles

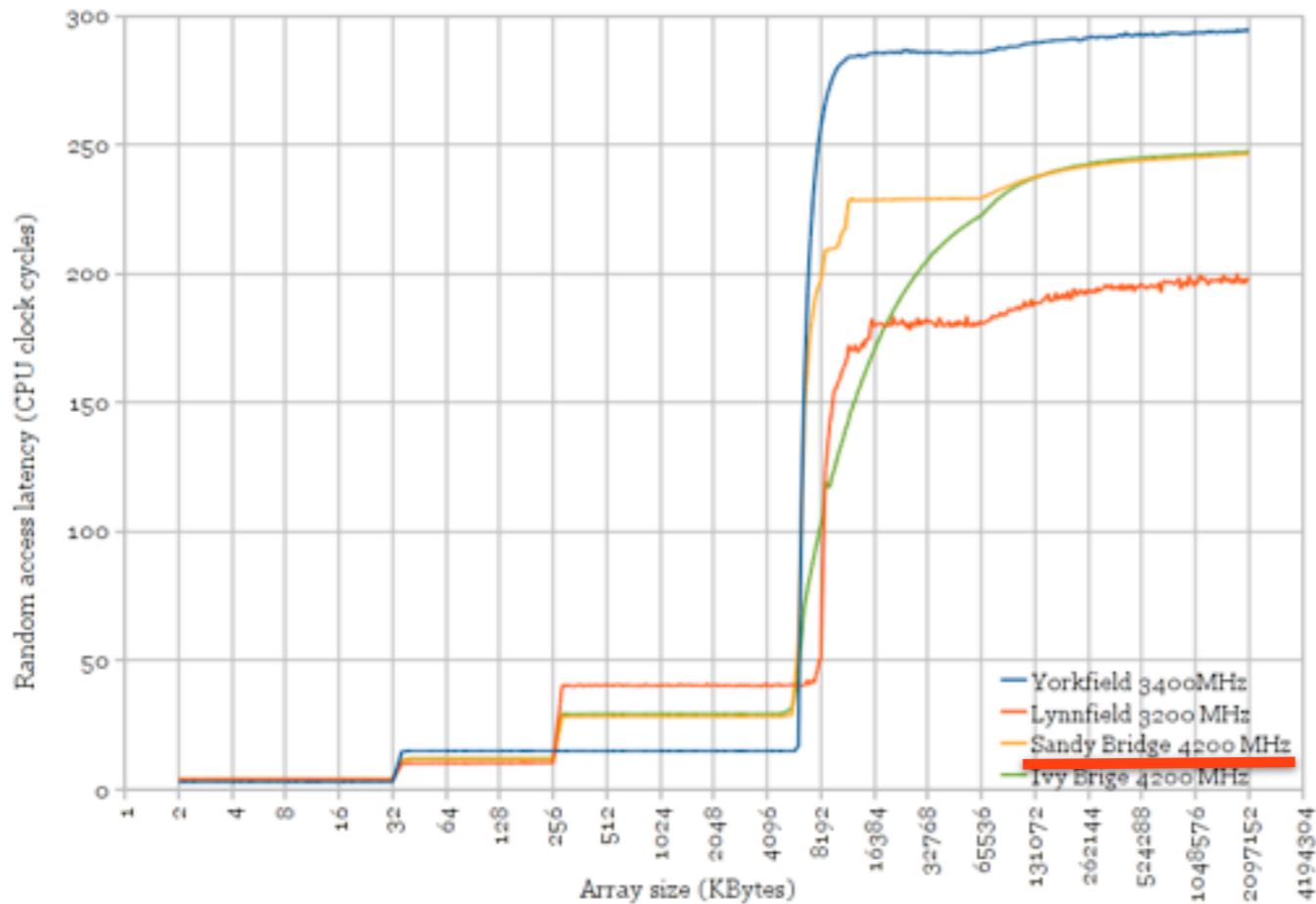
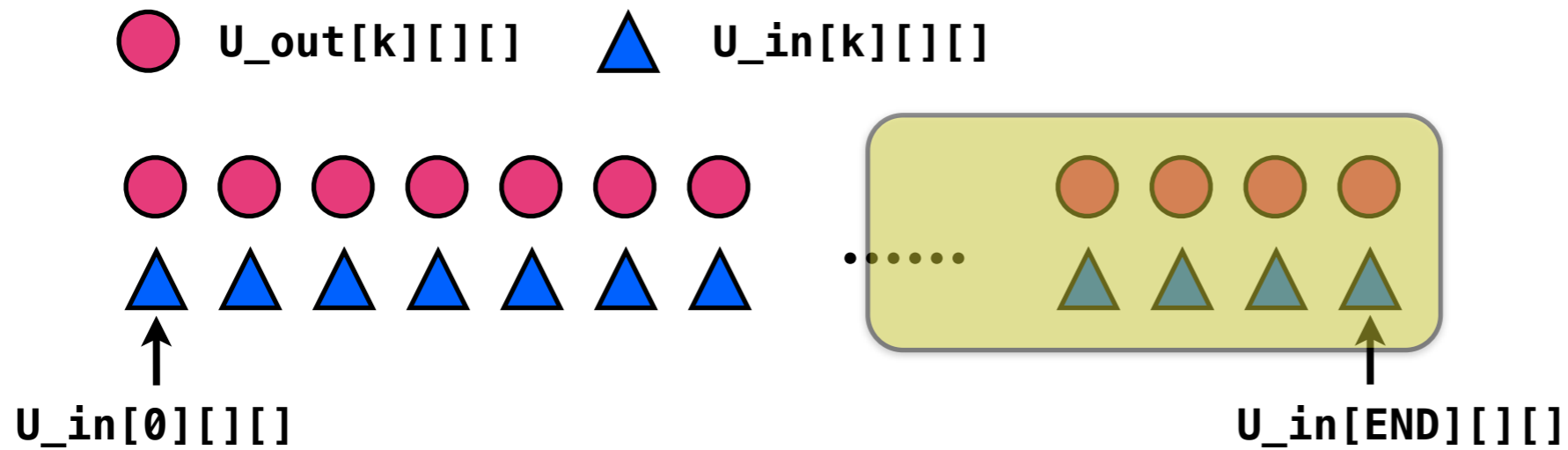
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<http://blog.stuffedcow.net/2013/01/ivb-cache-replacement/>

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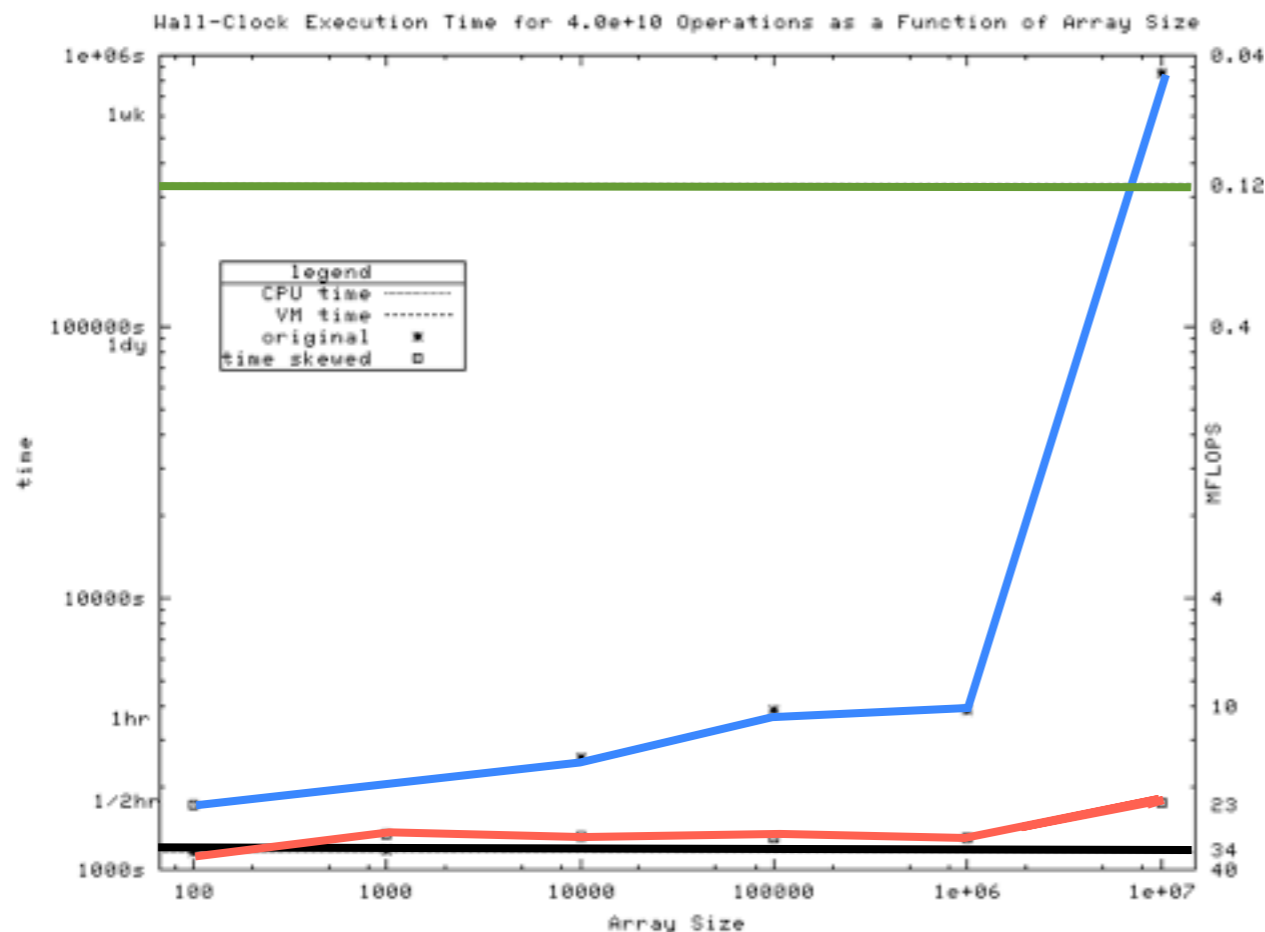
\* <http://www.cpu-world.com/sspec/Q4/Q4EN.html>

<http://blog.stuffedcow.net/2013/01/ivb-cache-replacement/>

## The Time-Skewing Approach

Time skewing is an optimization that can be used to optimize certain regular scientific codes for machines vastly outperforms the memory systems.

<http://www.haverford.edu/computerscience/faculty/davew/cache-opt/cache-opt.html>



\*In the acquisition design studies for subsalt imaging, the computational model has  $640*640*400$  grid points. For the vector acoustic method, 14 3D arrays (approximately **10 GB of addressable memory**) is required.

\* John T. Etgen, Michael J. OBrien, *Computational methods for large-scale 3D acoustic finite-difference modeling: a tutorial*. Geophysics 72 (2007) SM223SM230.

## Domain Decomposition?

If high-speed communication among processors is possible, the approach has the merit.

Drawbacks: complicated language, increasing the probability of failure

# Time-Skewing Approach Description(5 steps, tile size = 4)

  $U_{out}[k][][]$      $U_{in}[k][][]$

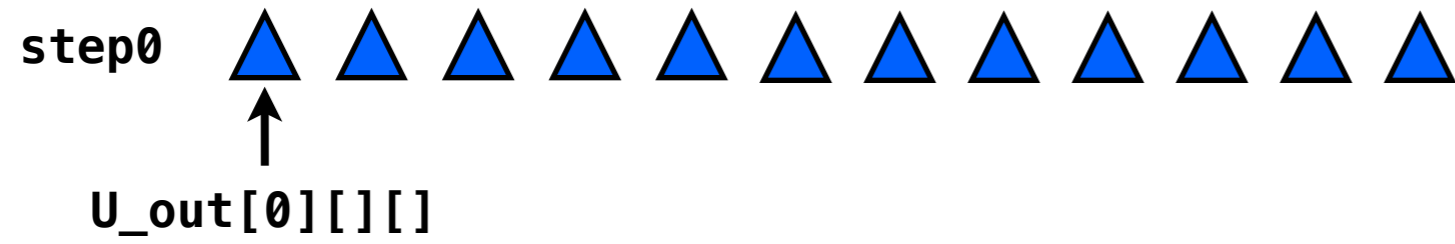
# Time-Skewing Approach Description(5 steps, tile size = 4)

  $U_{out}[k][][]$       $U_{in}[k][][]$

**step0**

# Time-Skewing Approach Description(5 steps, tile size = 4)

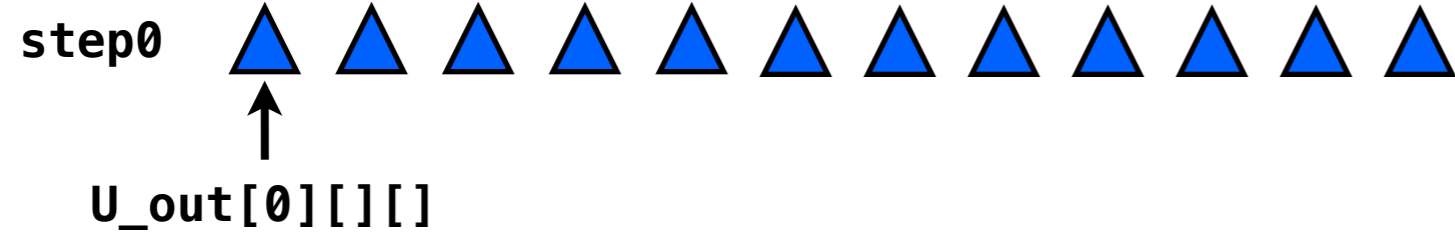
●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$



# Time-Skewing Approach Description(5 steps, tile size = 4)

●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$

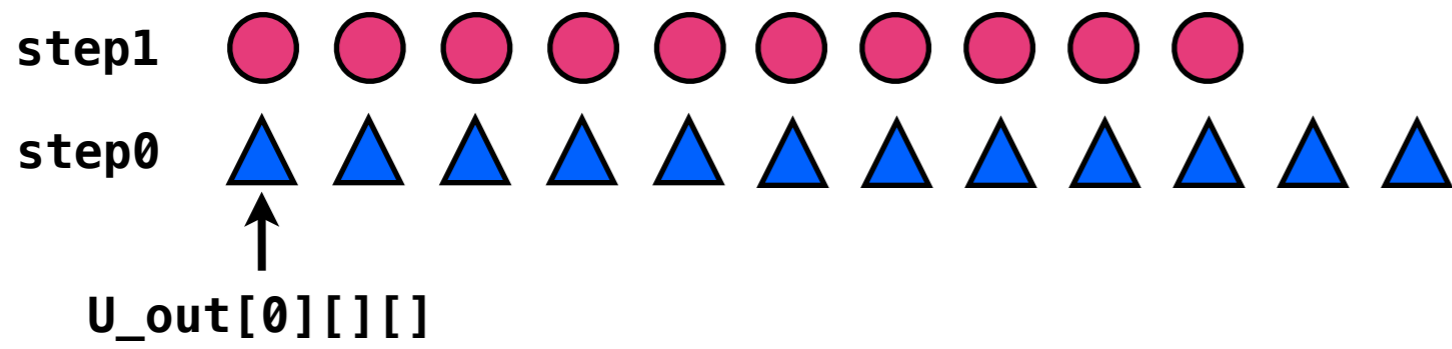
step1





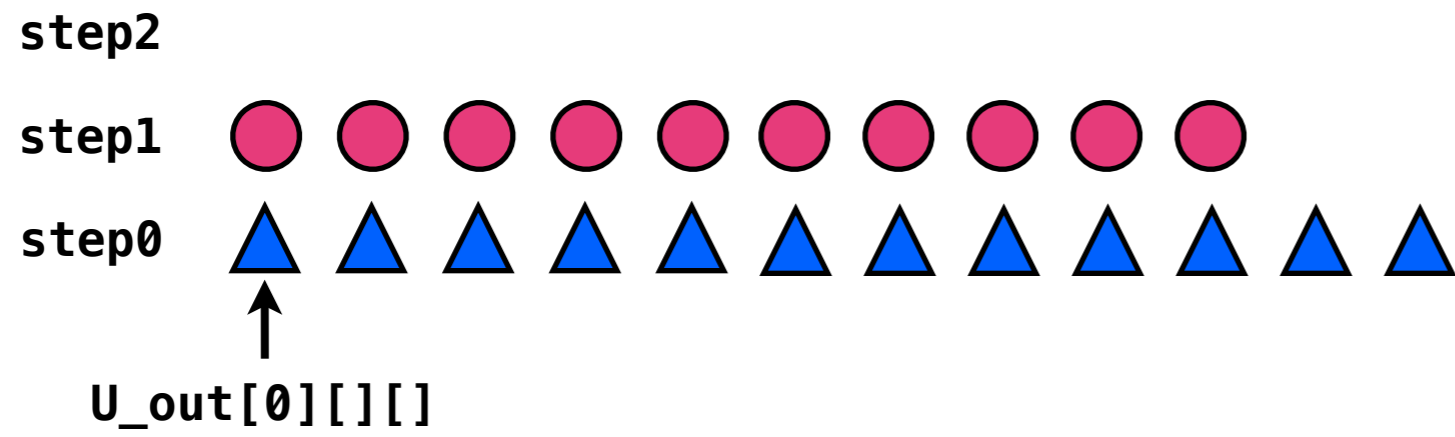
# Time-Skewing Approach Description(5 steps, tile size = 4)

●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$



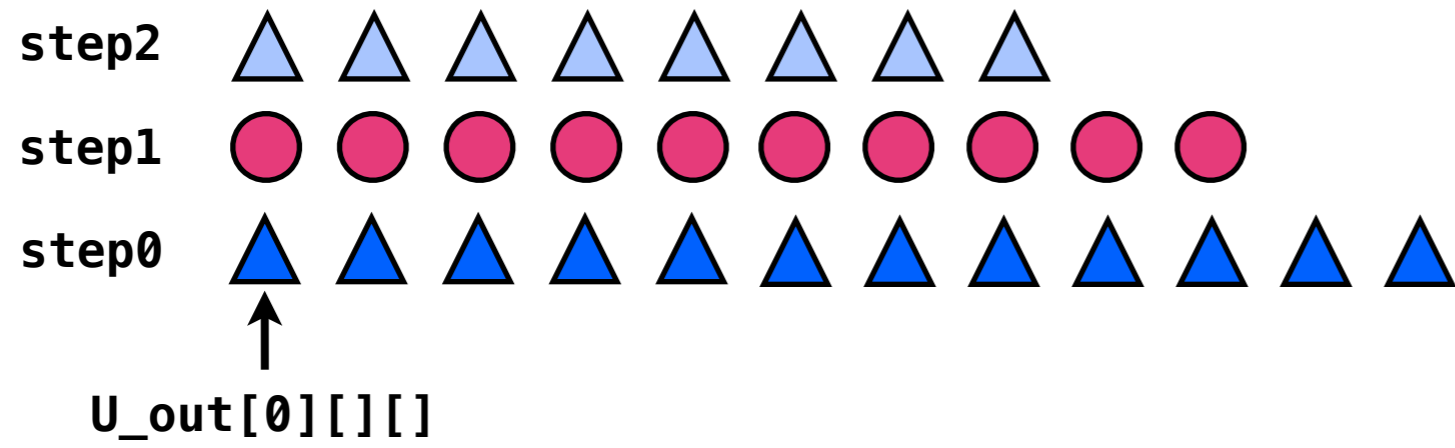
# Time-Skewing Approach Description(5 steps, tile size = 4)

●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$



# Time-Skewing Approach Description(5 steps, tile size = 4)

●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$



# Time-Skewing Approach Description(5 steps, tile size = 4)

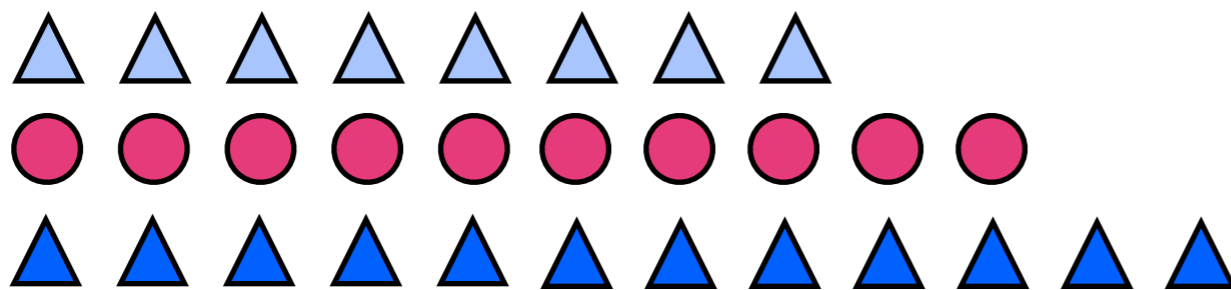
●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$

step3

step2

step1

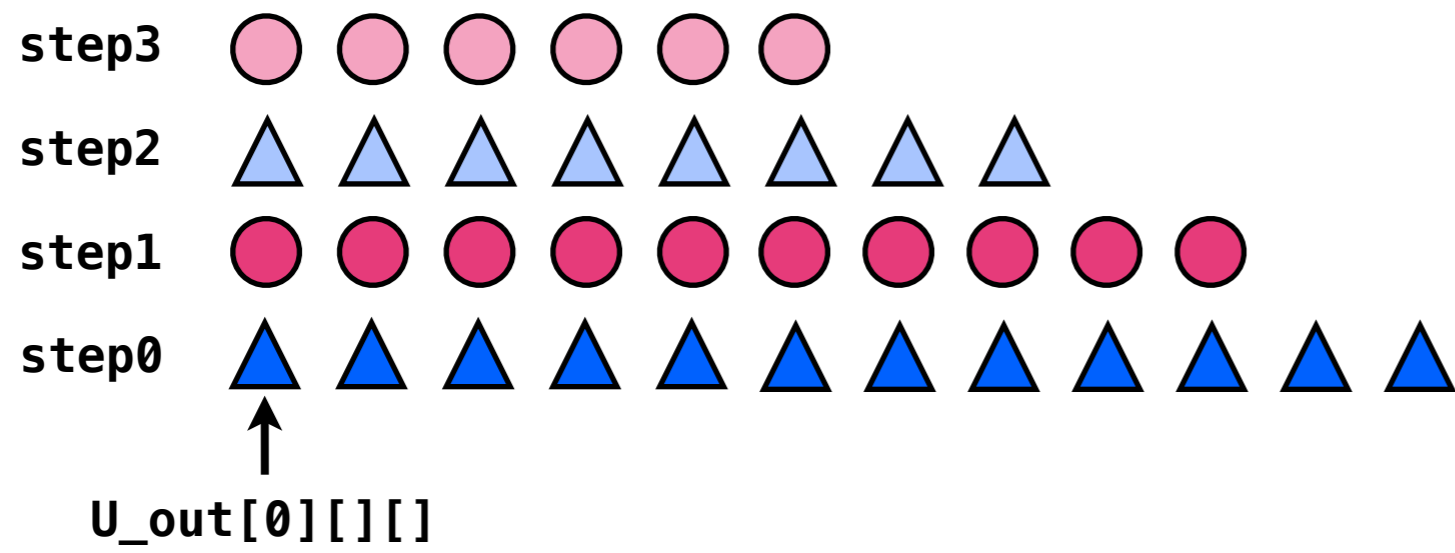
step0



$U_{out}[0][][[]]$

# Time-Skewing Approach Description(5 steps, tile size = 4)

●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$



# Time-Skewing Approach Description(5 steps, tile size = 4)

●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$

step4

step3 ● ● ● ● ● ●

step2 ▲ ▲ ▲ ▲ ▲ ▲ ▲ ▲

step1 ● ● ● ● ● ● ● ● ● ●

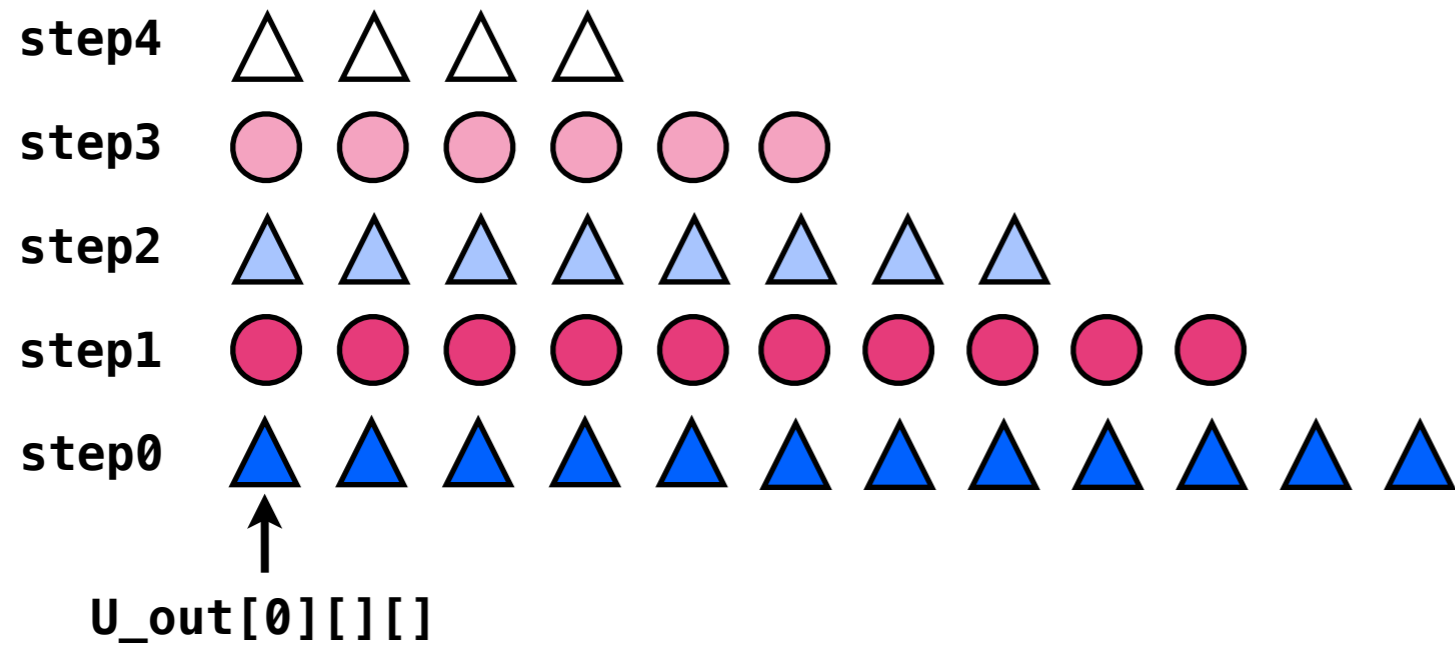
step0 ▲ ▲ ▲ ▲ ▲ ▲ ▲ ▲ ▲ ▲ ▲ ▲



$U_{out}[0][][[]]$

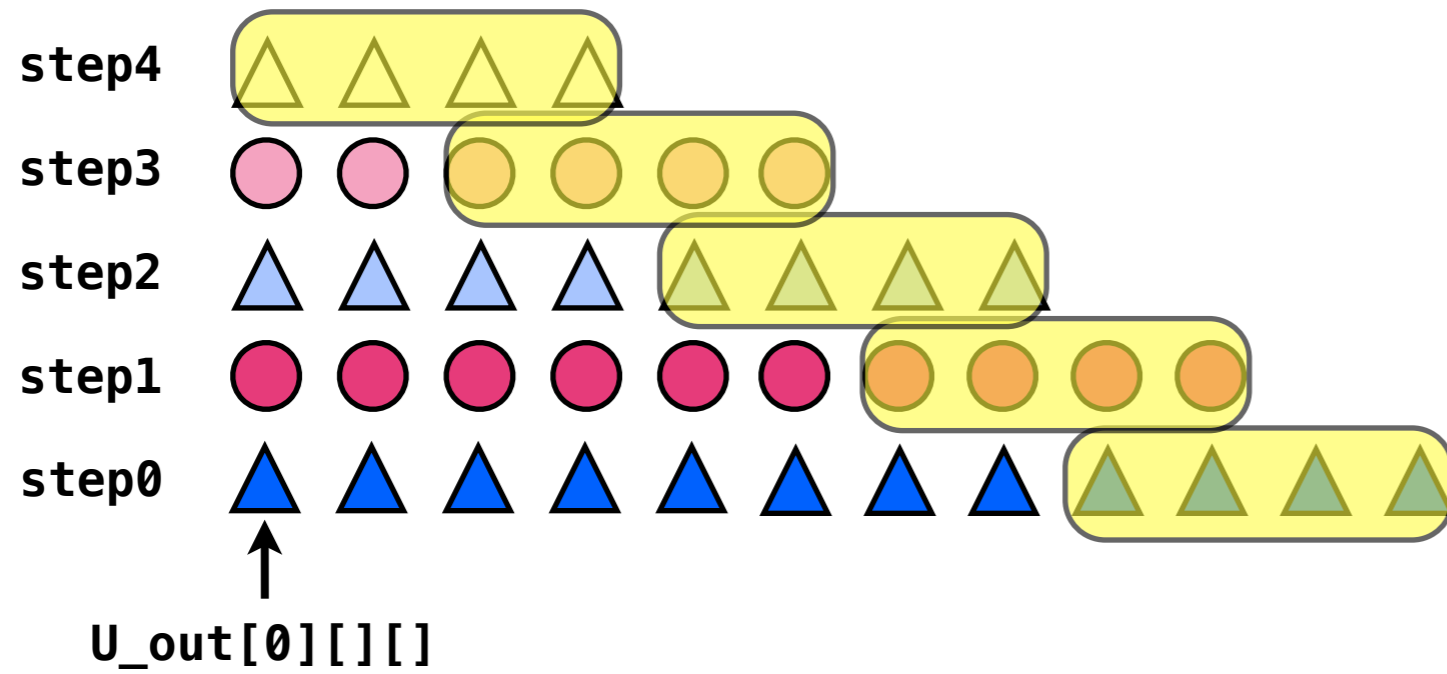
# Time-Skewing Approach Description(5 steps, tile size = 4)

●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$



# Time-Skewing Approach Description(5 steps, tile size = 4)

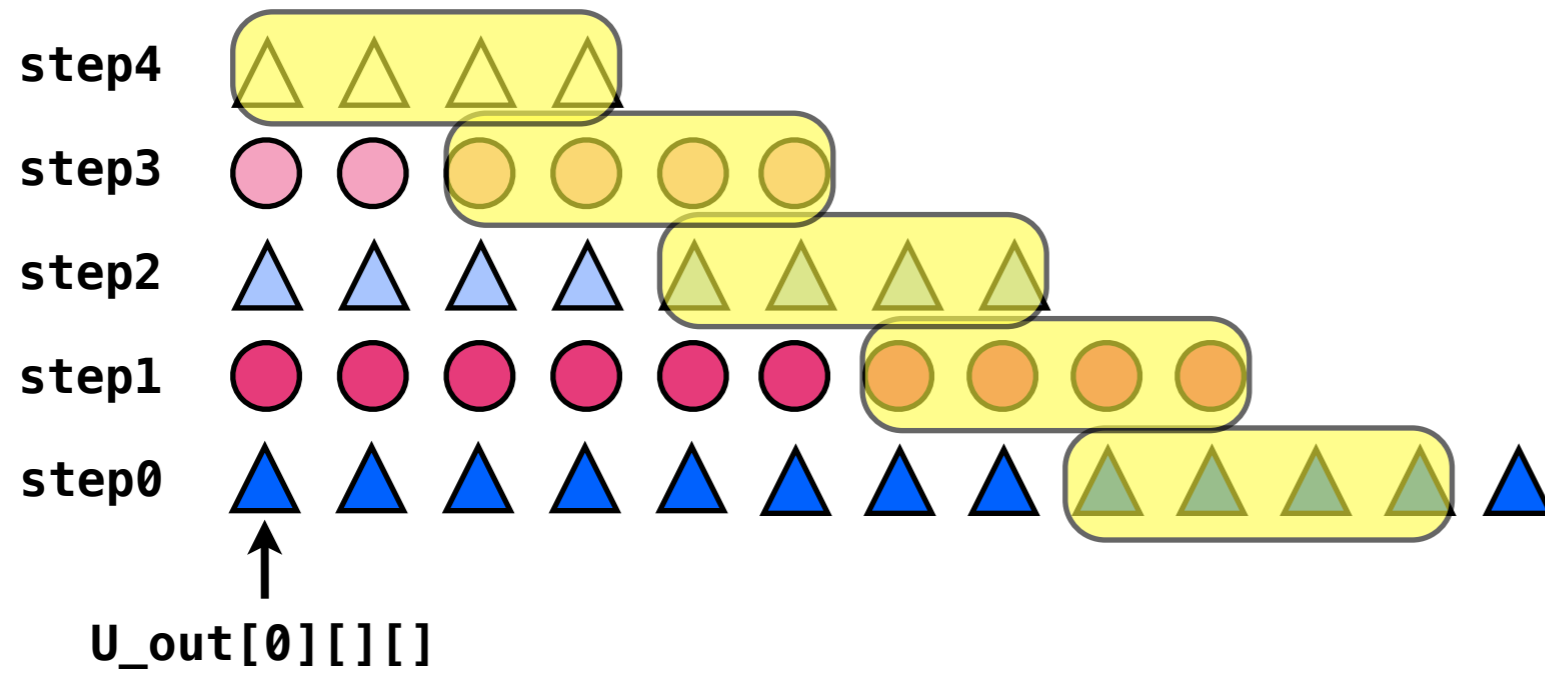
●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$





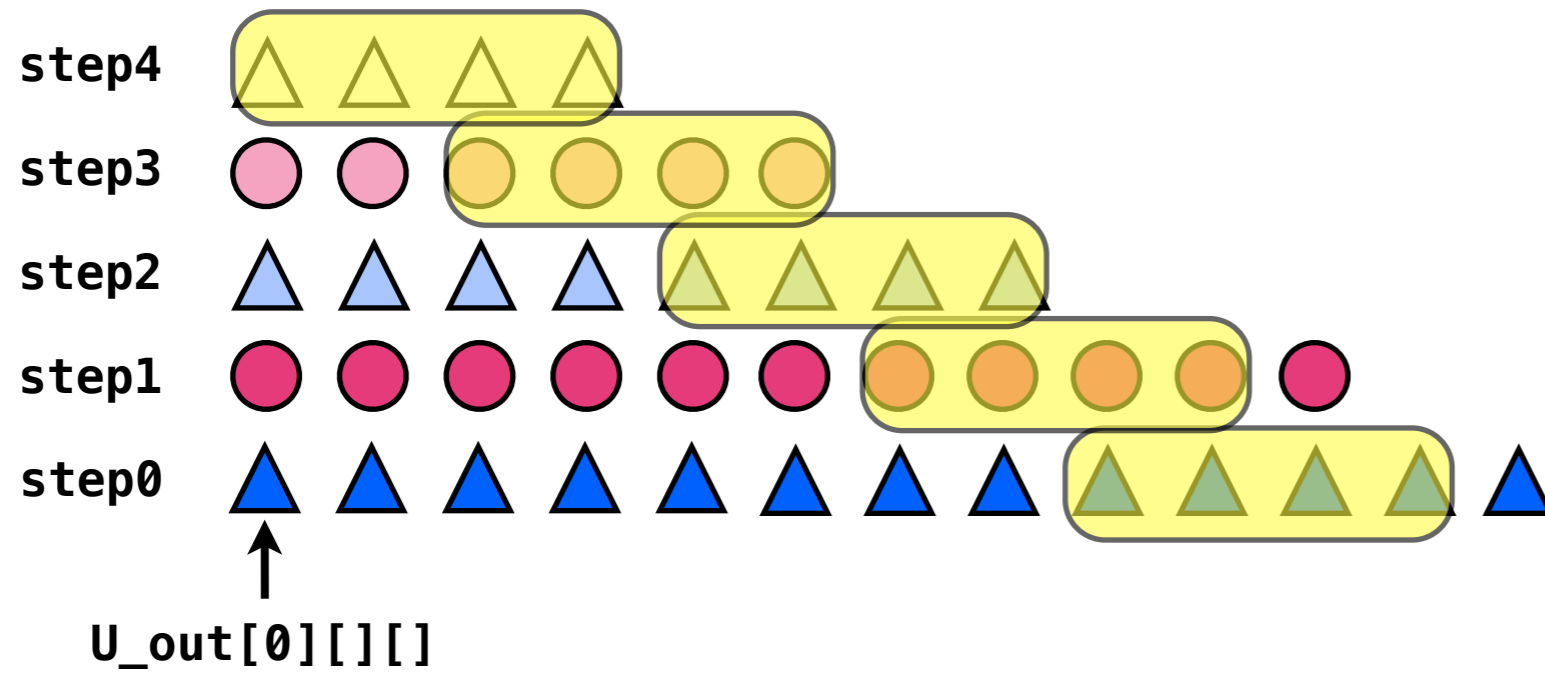
# Time-Skewing Approach Description(5 steps, tile size = 4)

●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$



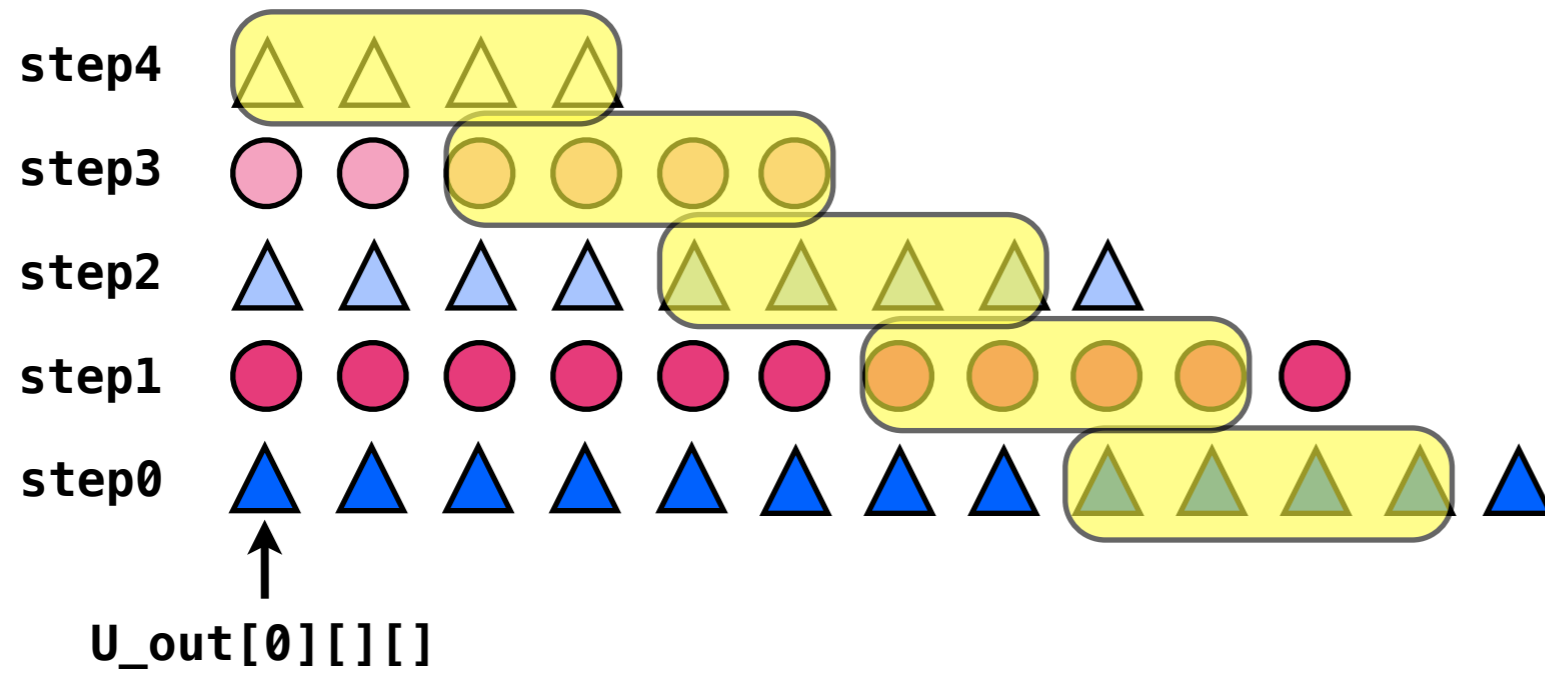
# Time-Skewing Approach Description(5 steps, tile size = 4)

●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$



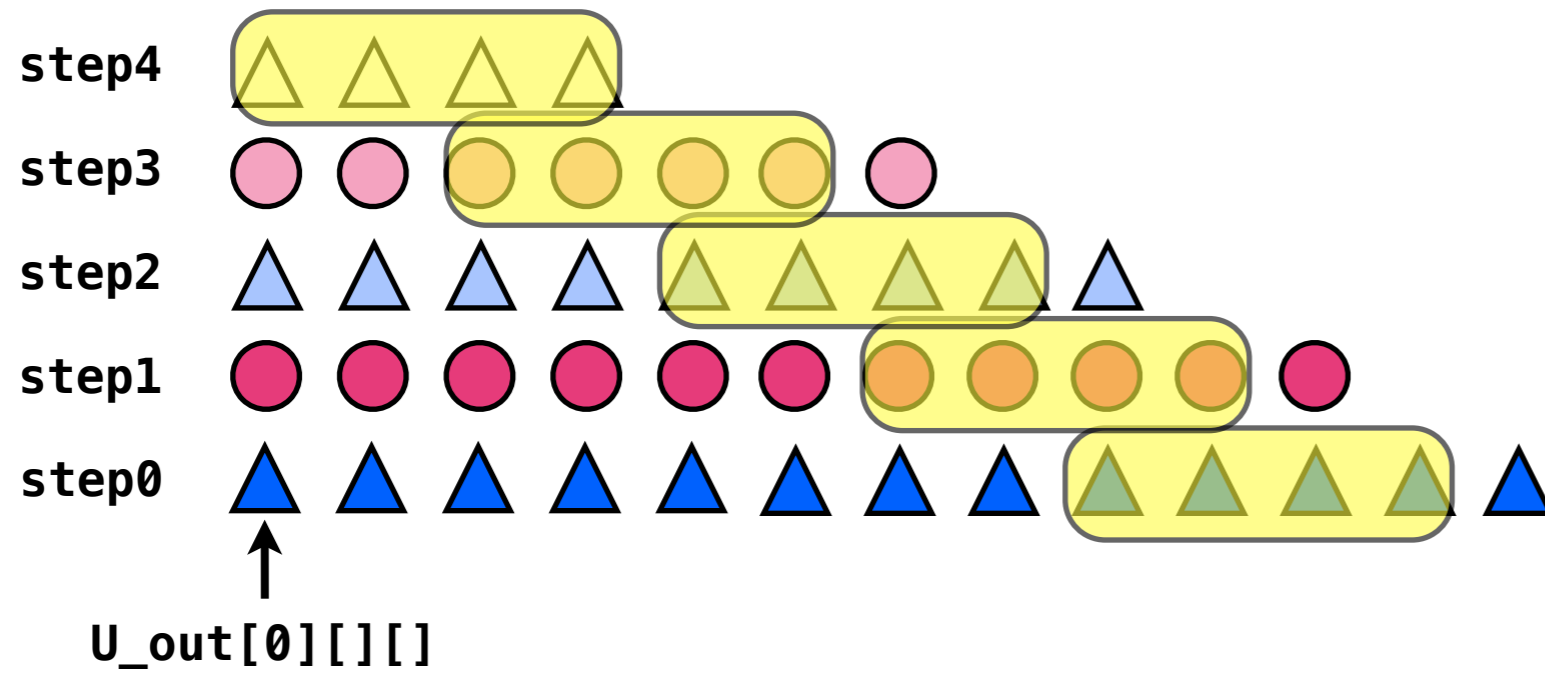
# Time-Skewing Approach Description(5 steps, tile size = 4)

●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$



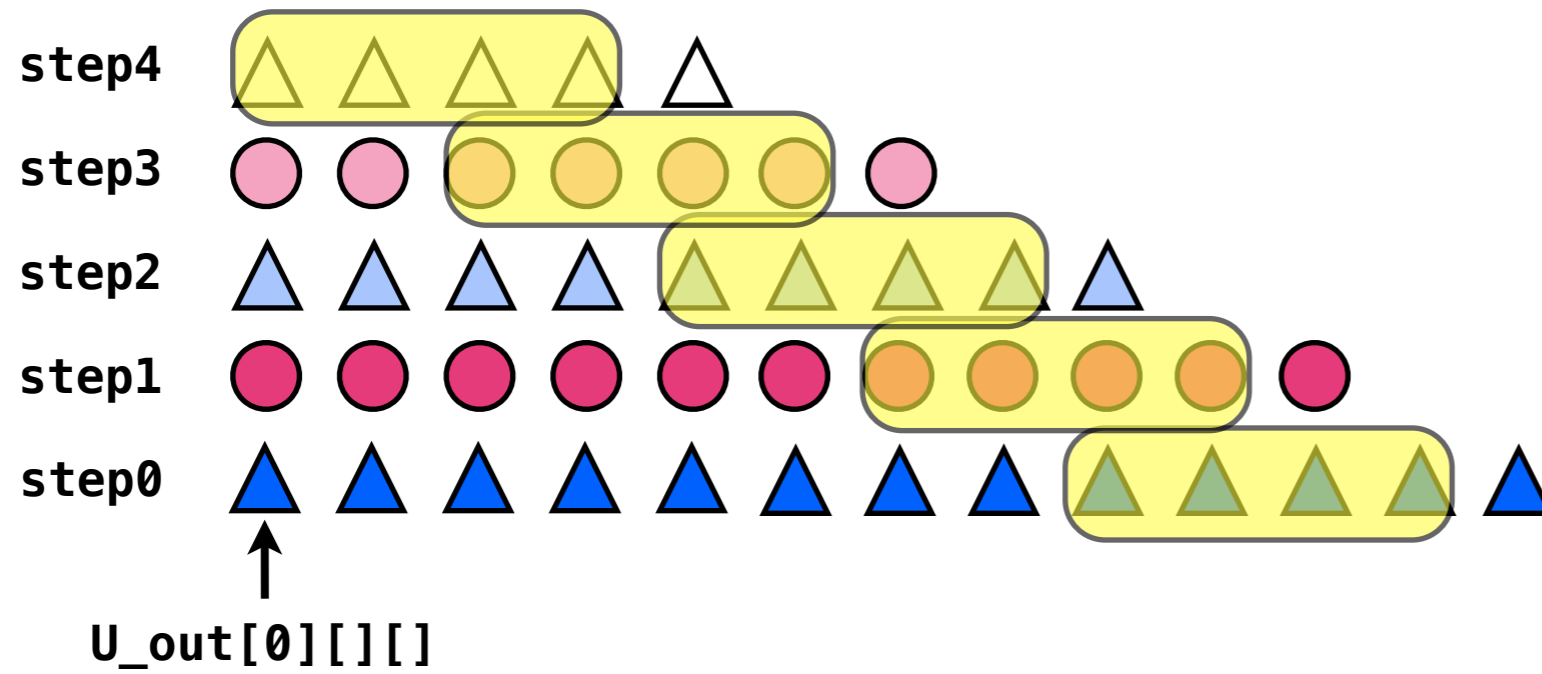
# Time-Skewing Approach Description(5 steps, tile size = 4)

●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$



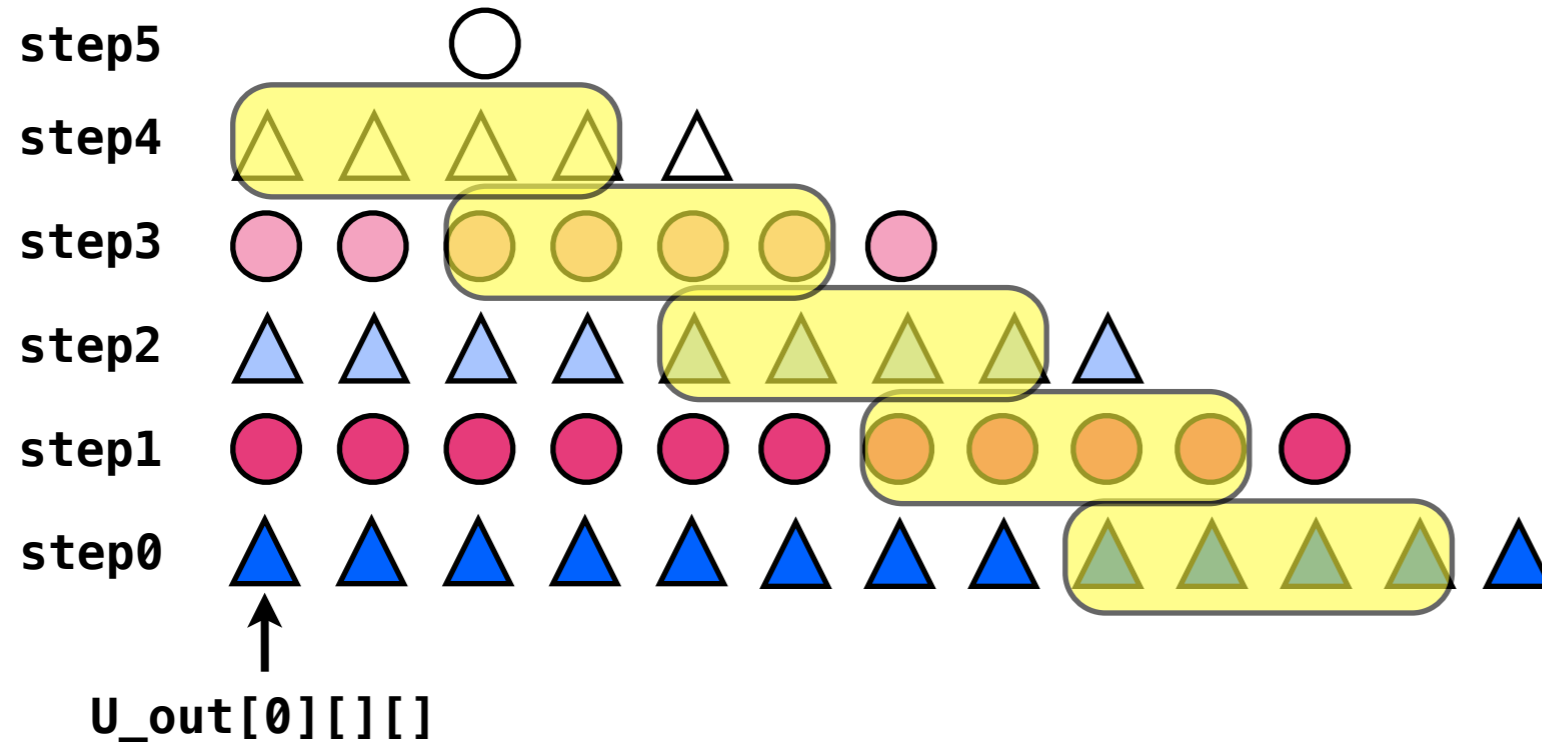
# Time-Skewing Approach Description(5 steps, tile size = 4)

●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$



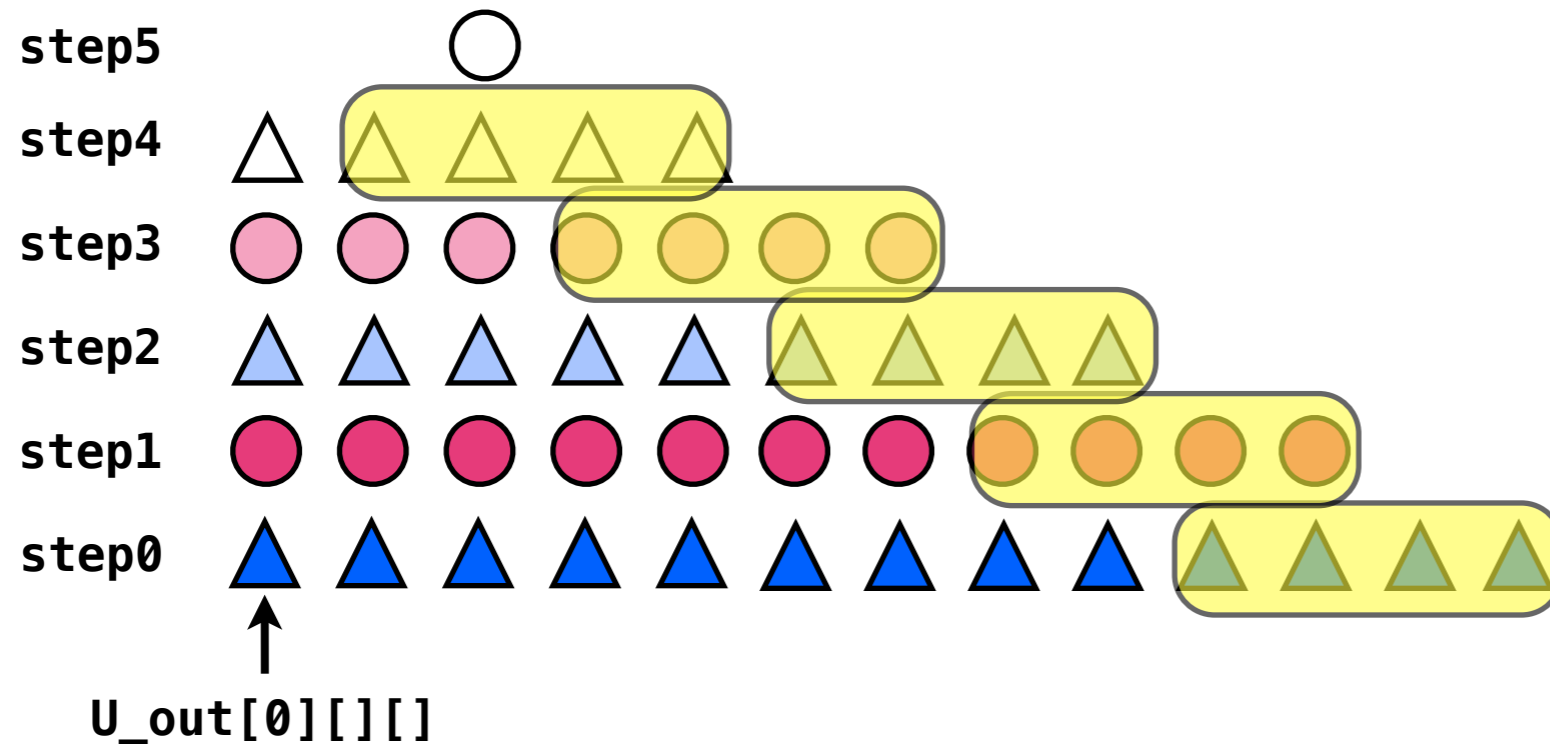
# Time-Skewing Approach Description(5 steps, tile size = 4)

●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$



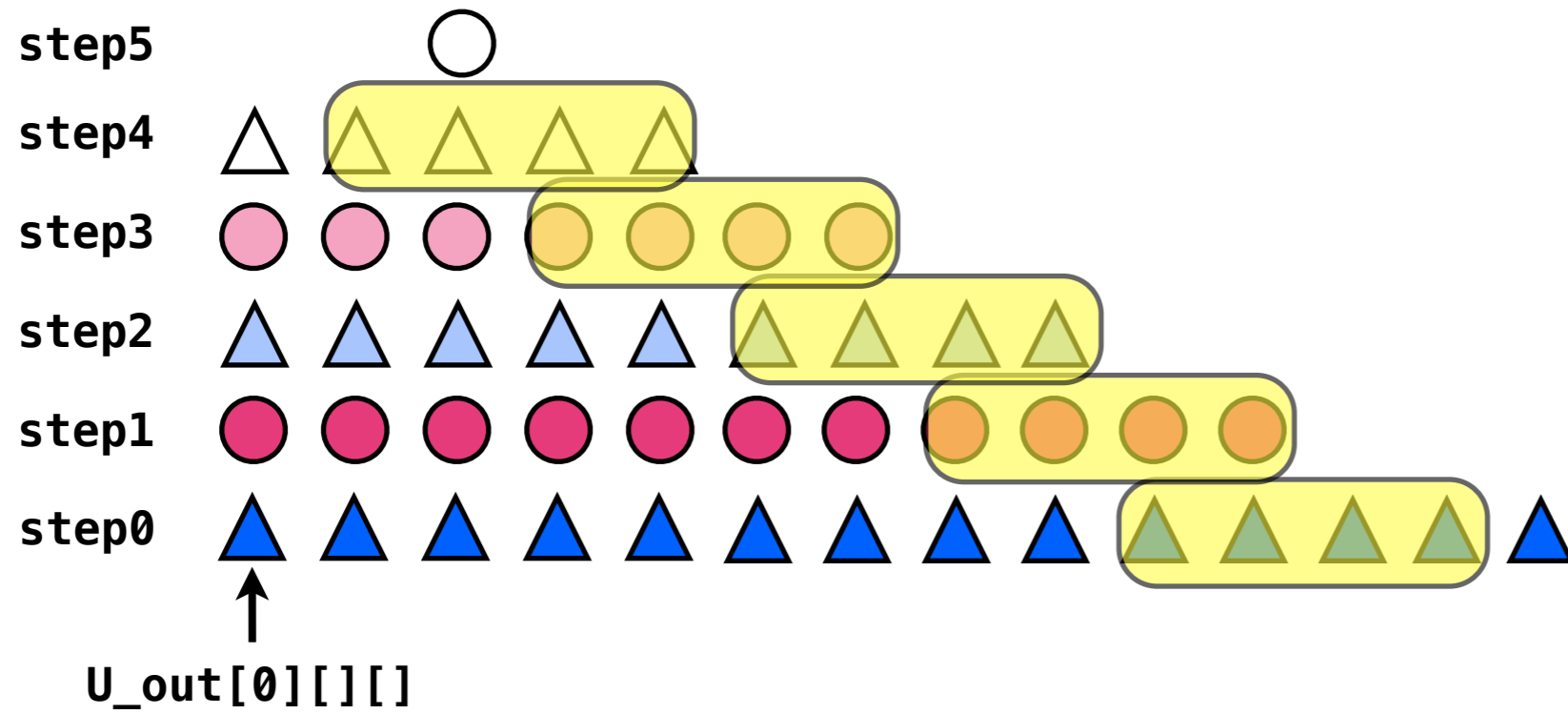
# Time-Skewing Approach Description(5 steps, tile size = 4)

●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$



# Time-Skewing Approach Description(5 steps, tile size = 4)

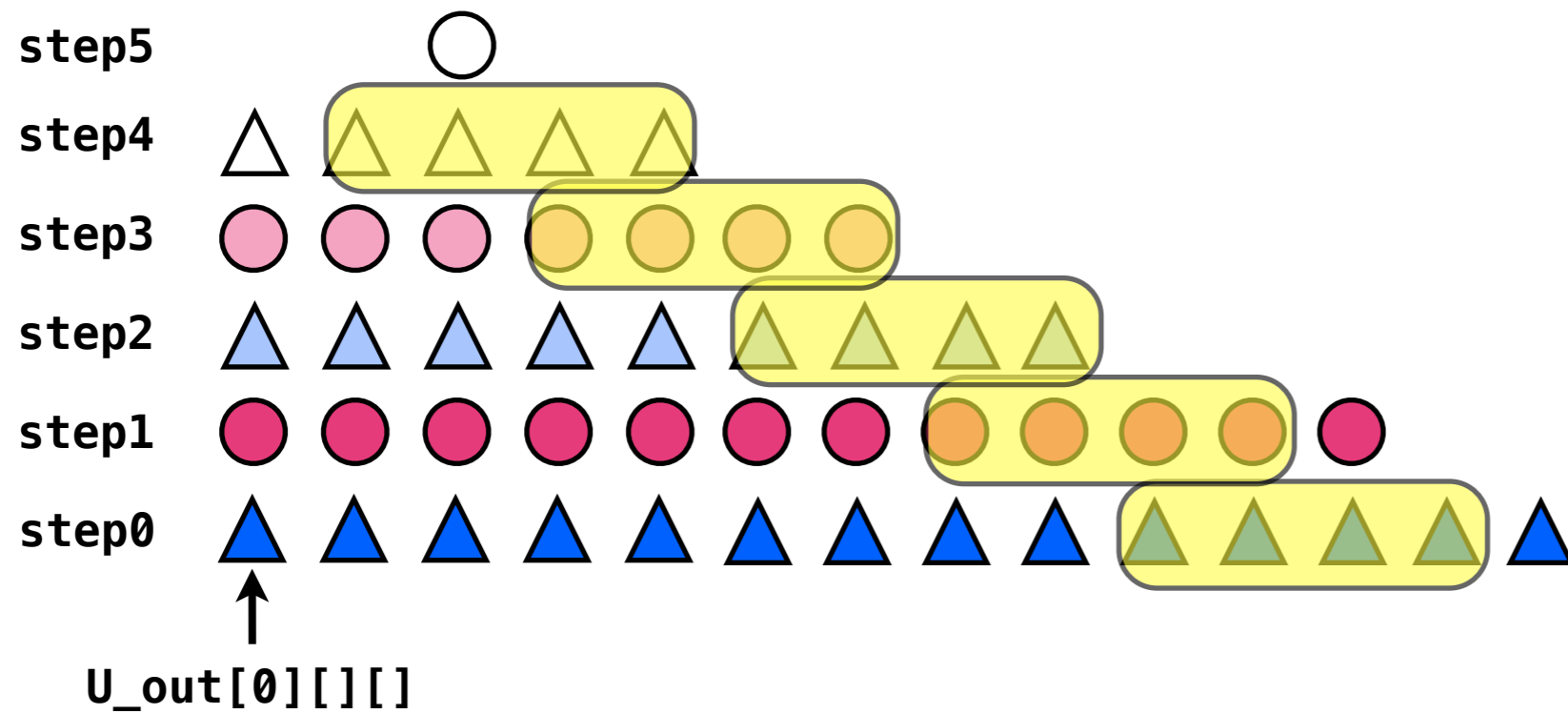
●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$





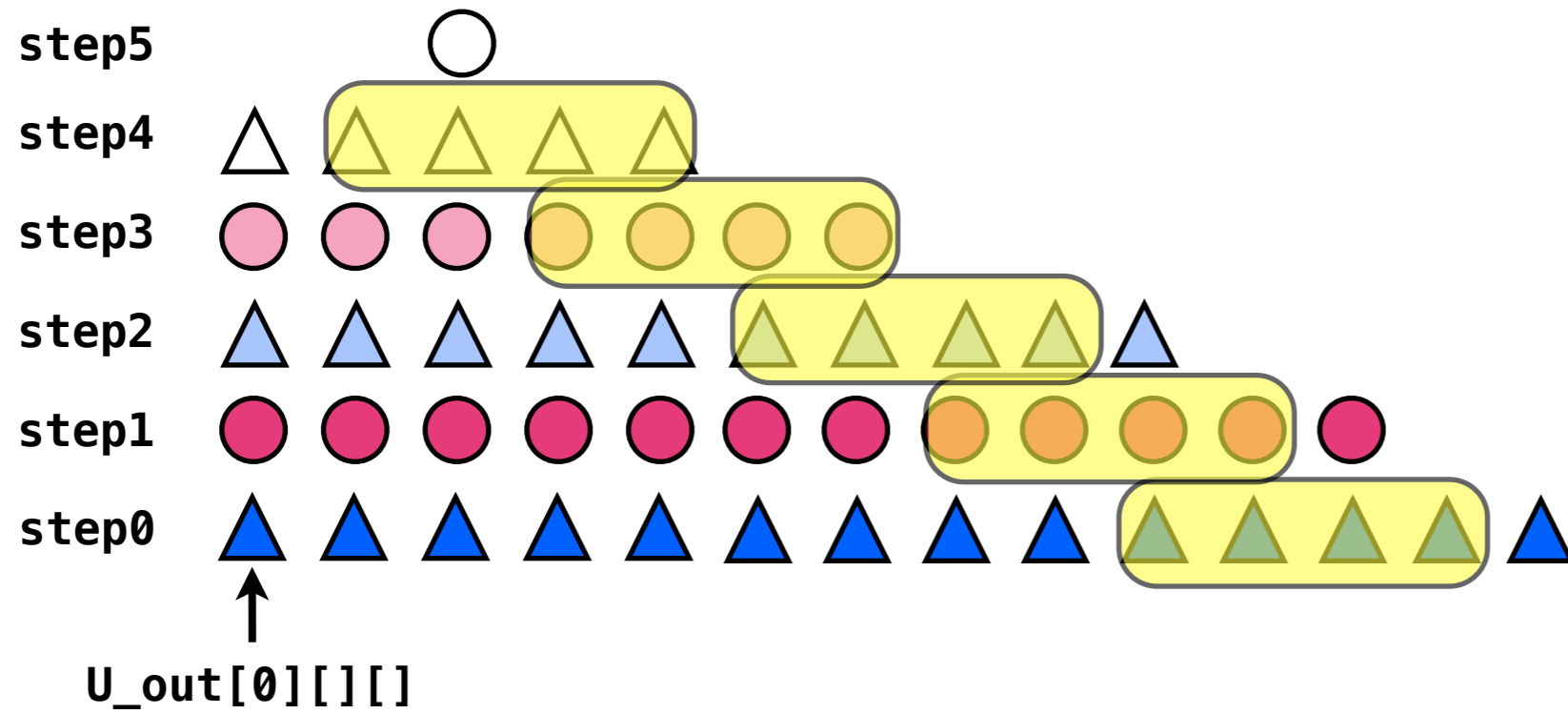
# Time-Skewing Approach Description(5 steps, tile size = 4)

●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$



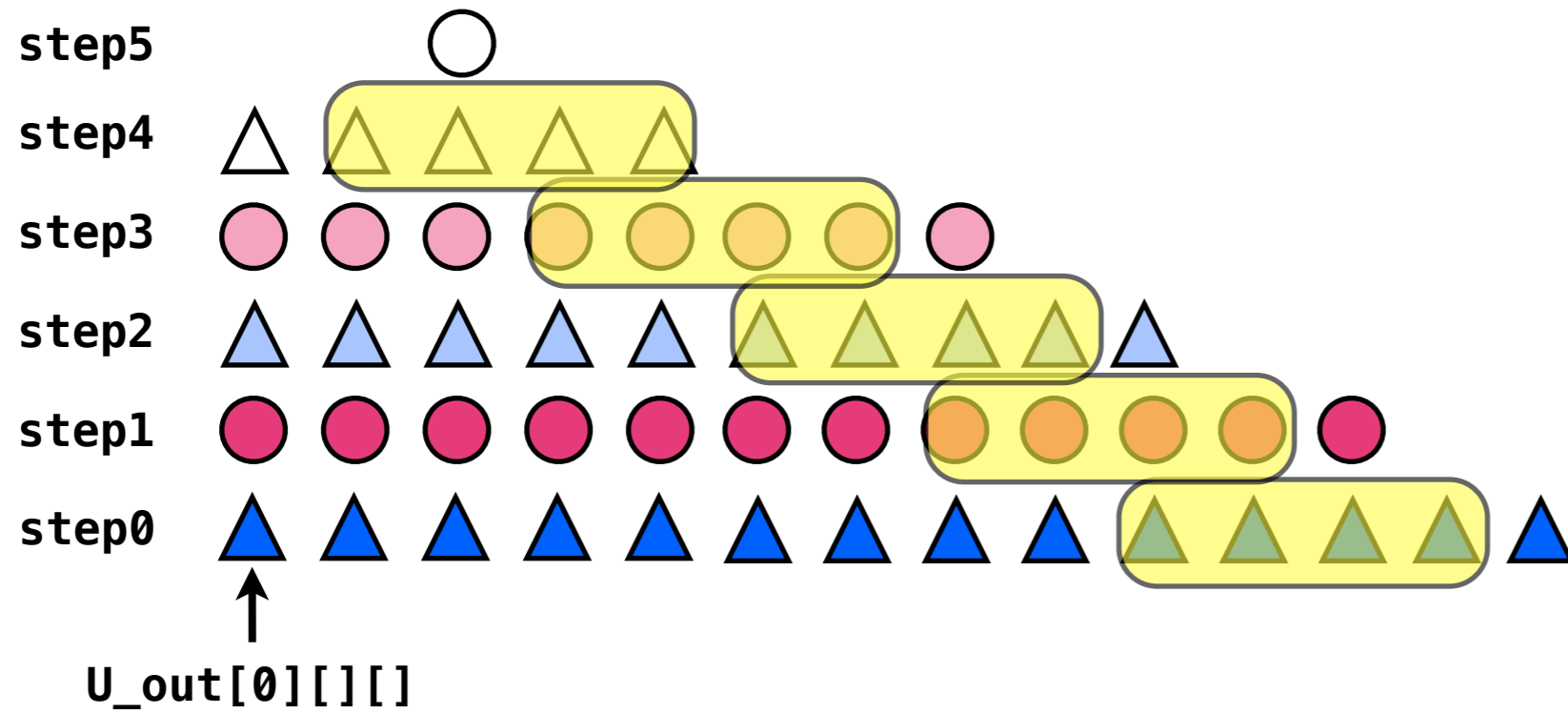
# Time-Skewing Approach Description(5 steps, tile size = 4)

●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$



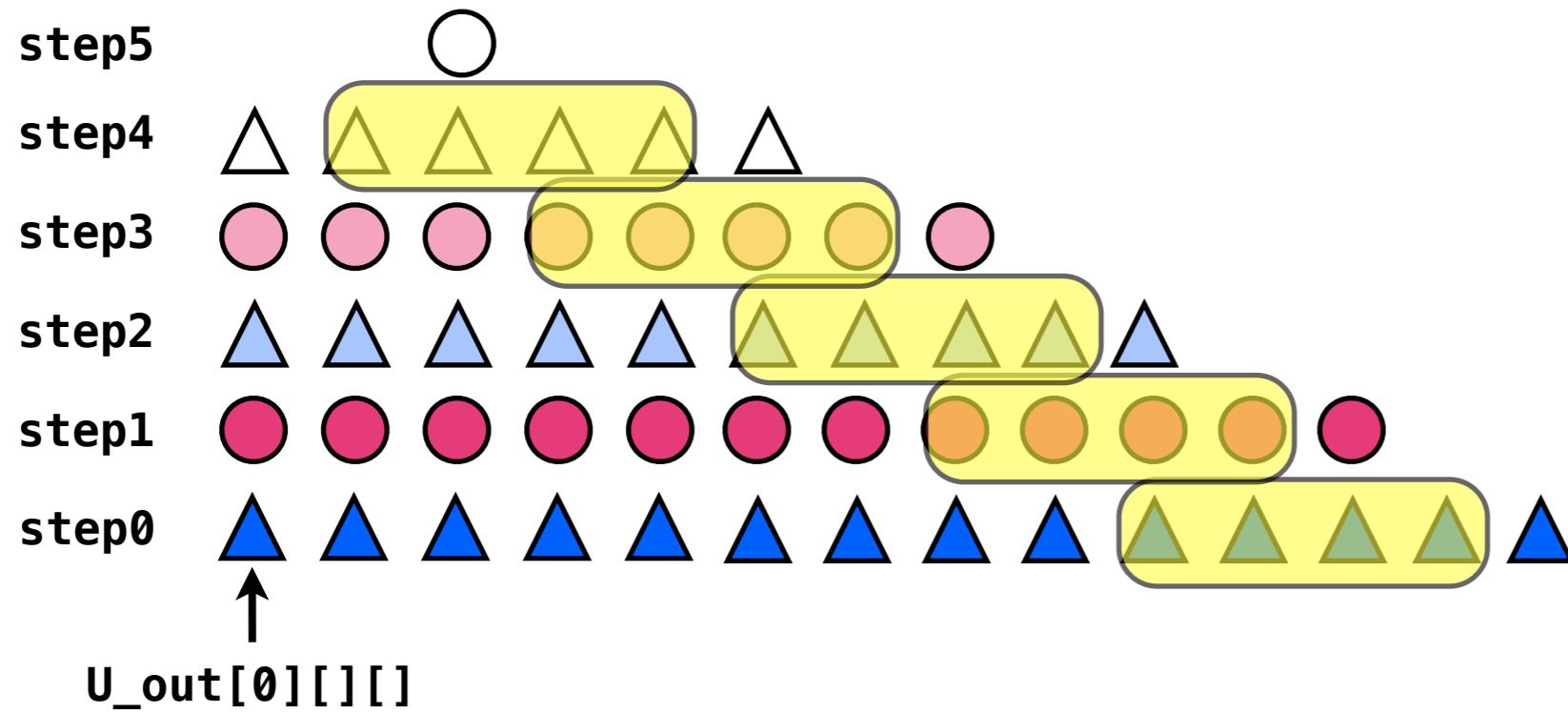
# Time-Skewing Approach Description(5 steps, tile size = 4)

●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$



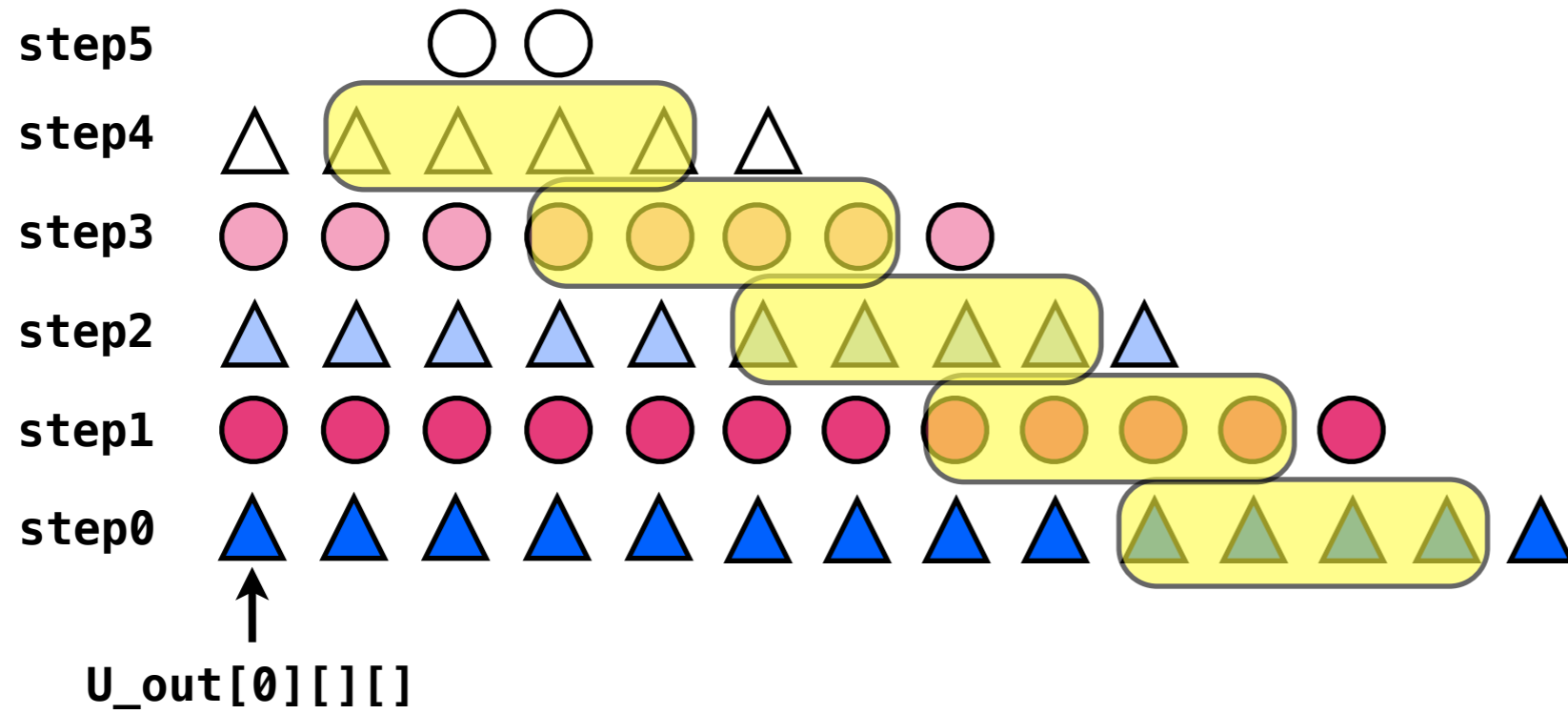
# Time-Skewing Approach Description(5 steps, tile size = 4)

●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$



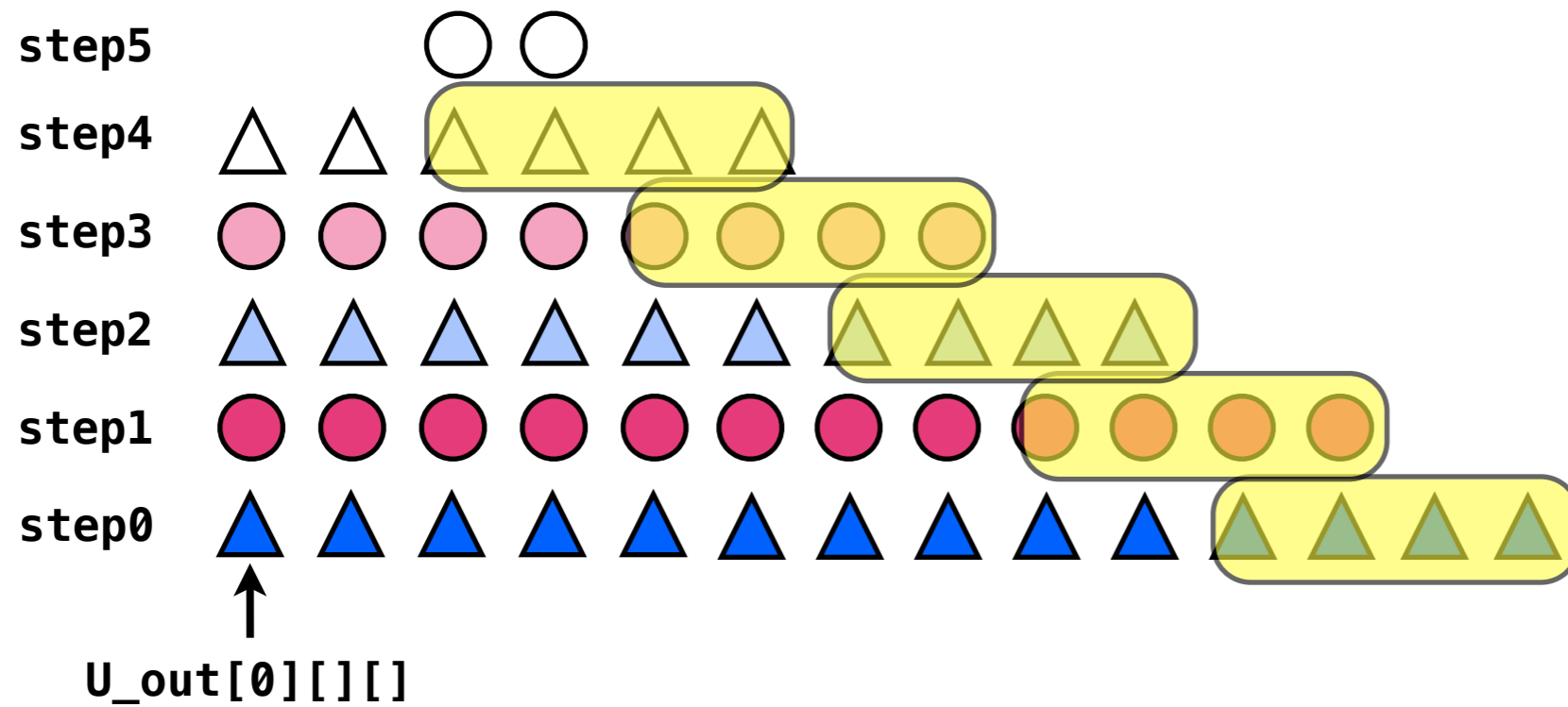
# Time-Skewing Approach Description(5 steps, tile size = 4)

●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$



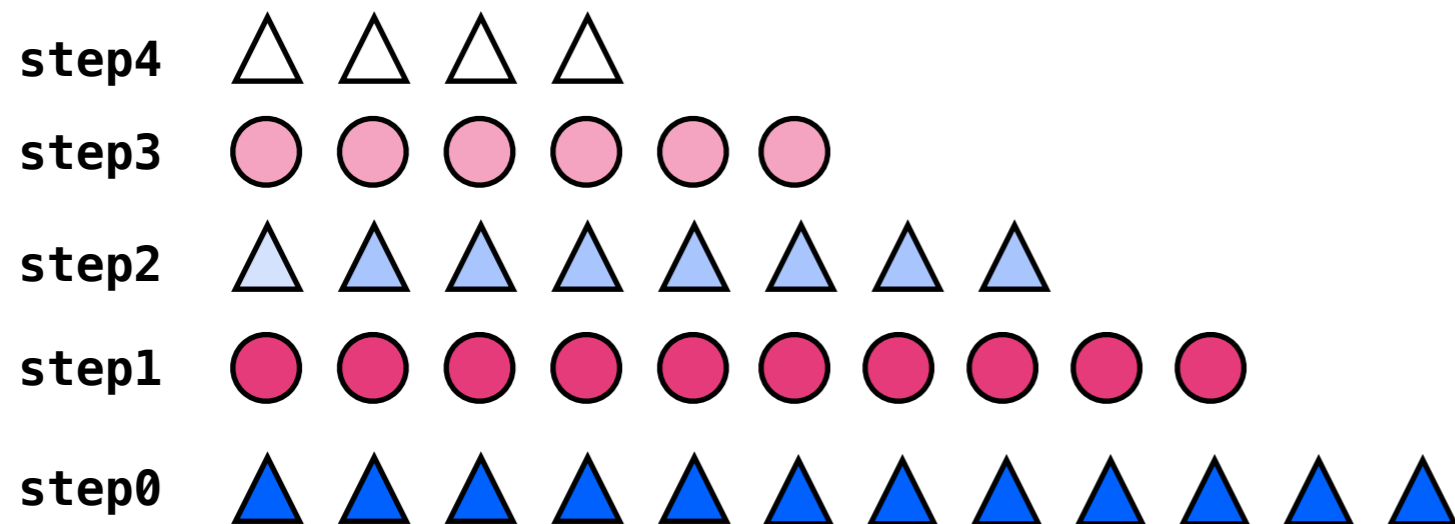
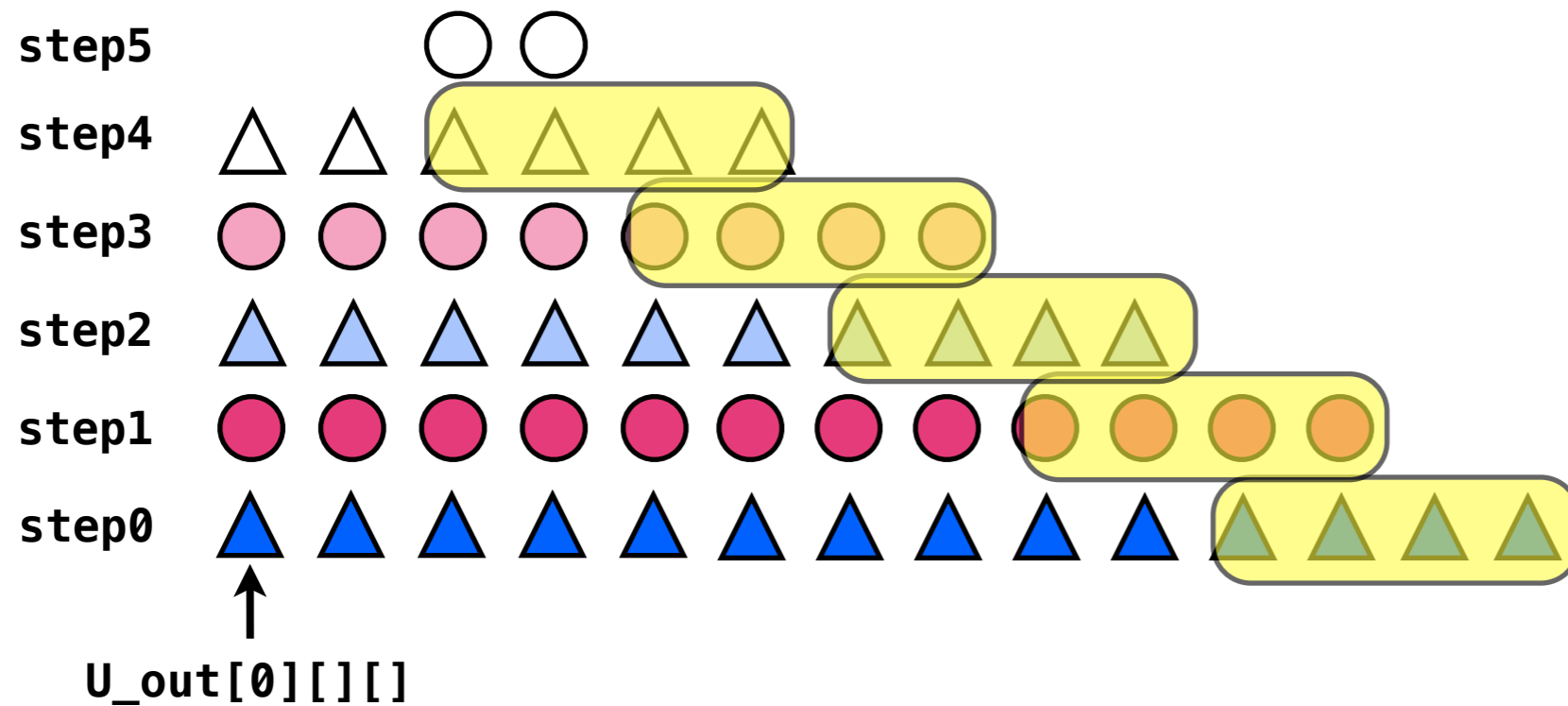
# Time-Skewing Approach Description(5 steps, tile size = 4)

●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$



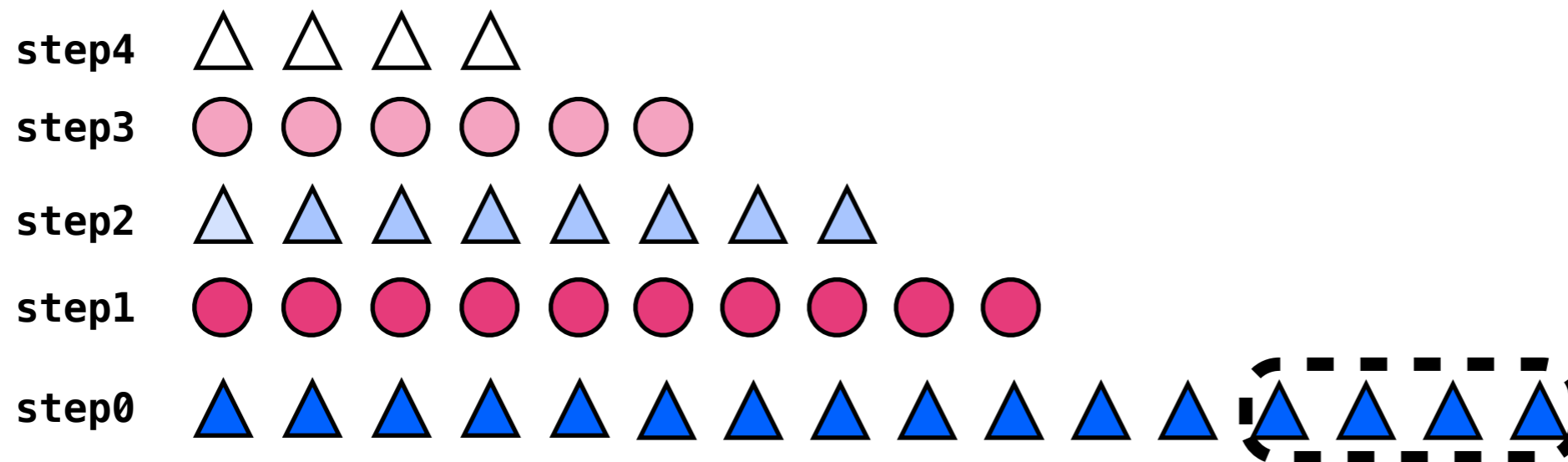
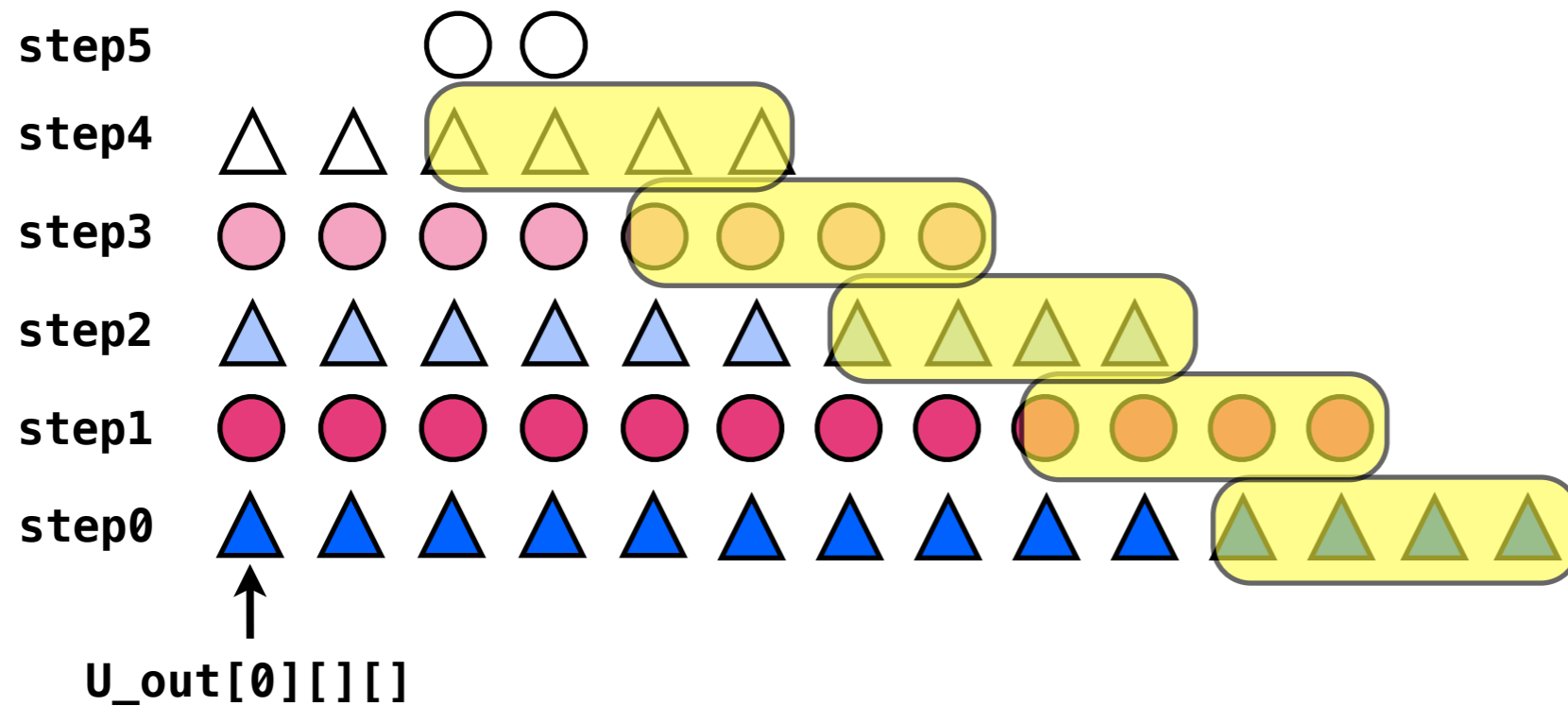
# Time-Skewing Approach Description(5 steps, tile size = 4)

●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$



# Time-Skewing Approach Description(5 steps, tile size = 4)

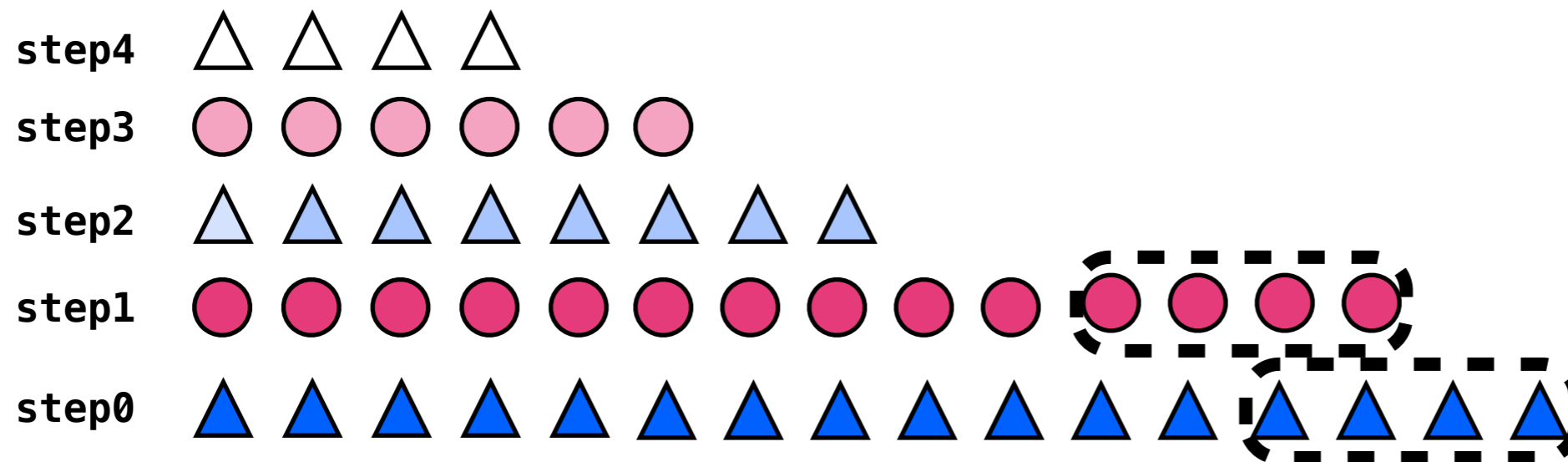
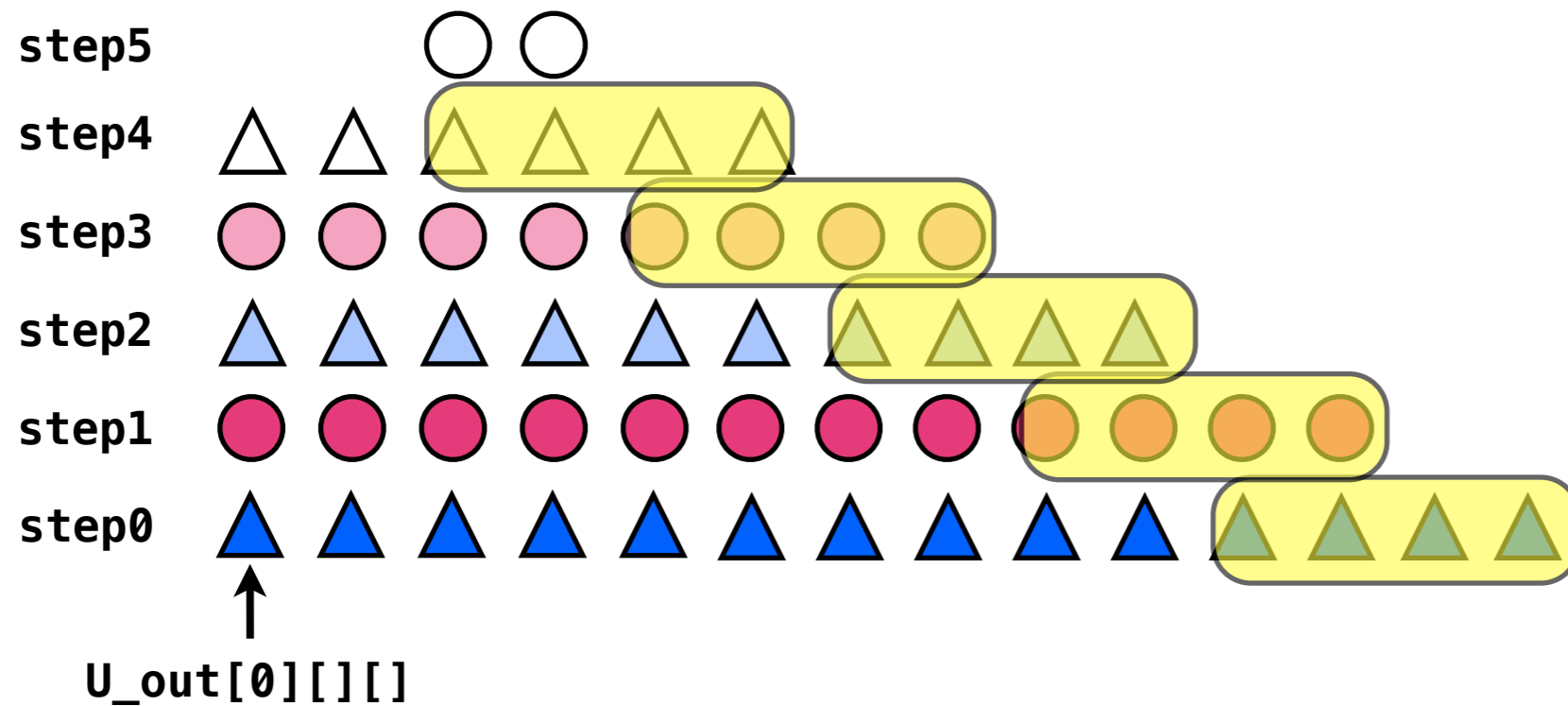
●  $U_{out}[k][][[]]$      ▲  $U_{in}[k][][[]]$





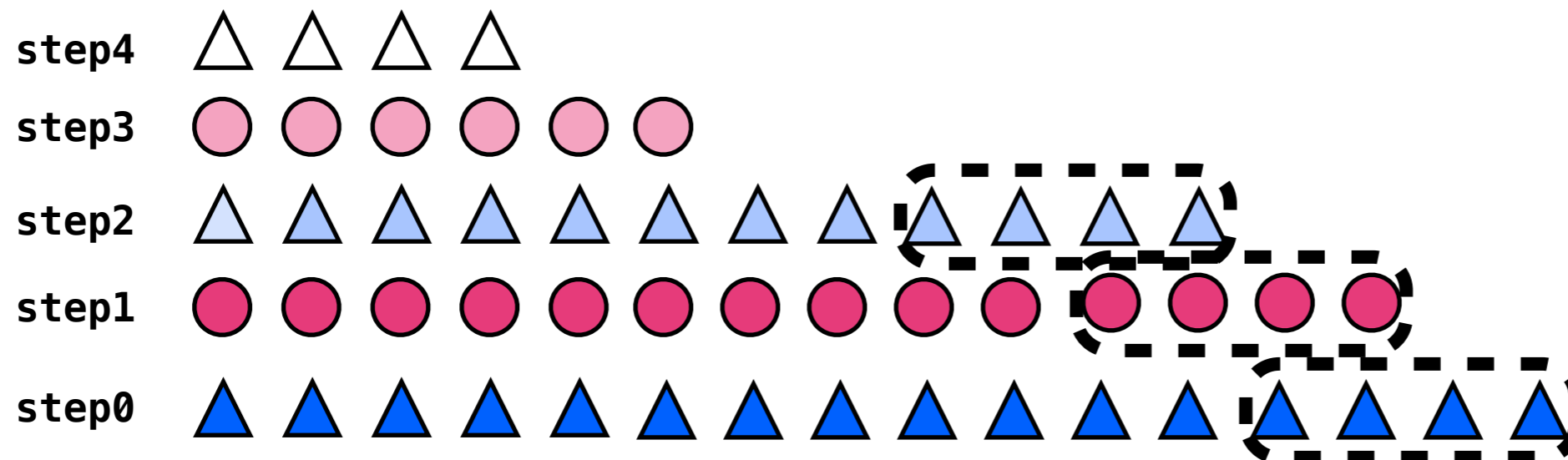
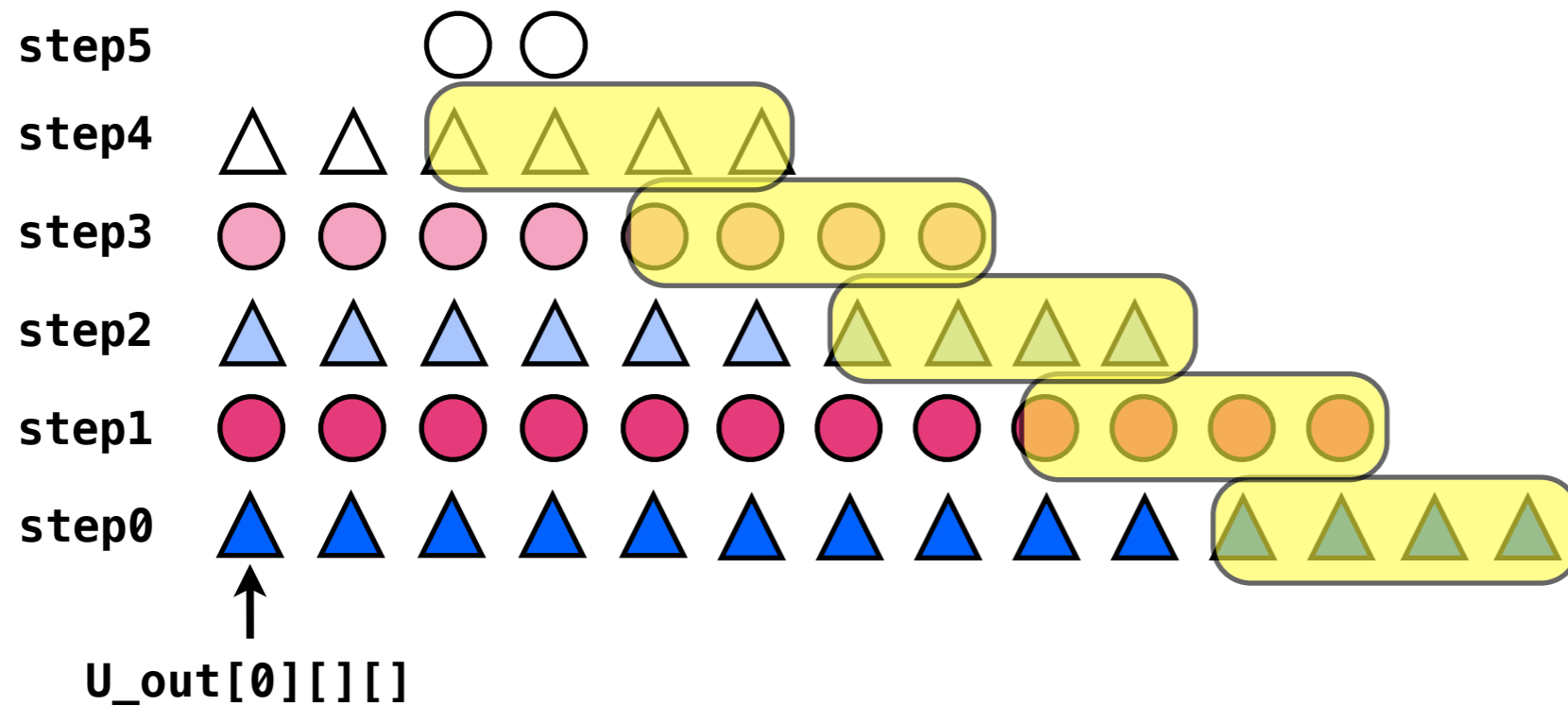
# Time-Skewing Approach Description(5 steps, tile size = 4)

●  $U_{out}[k][][[]]$    
 ▲  $U_{in}[k][][[]]$



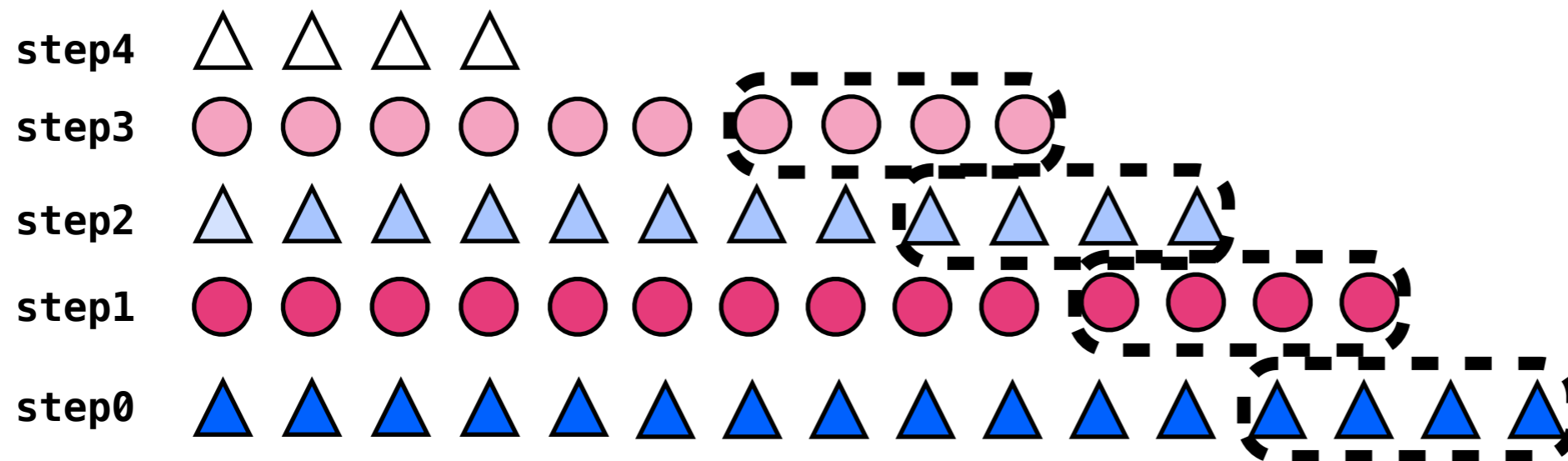
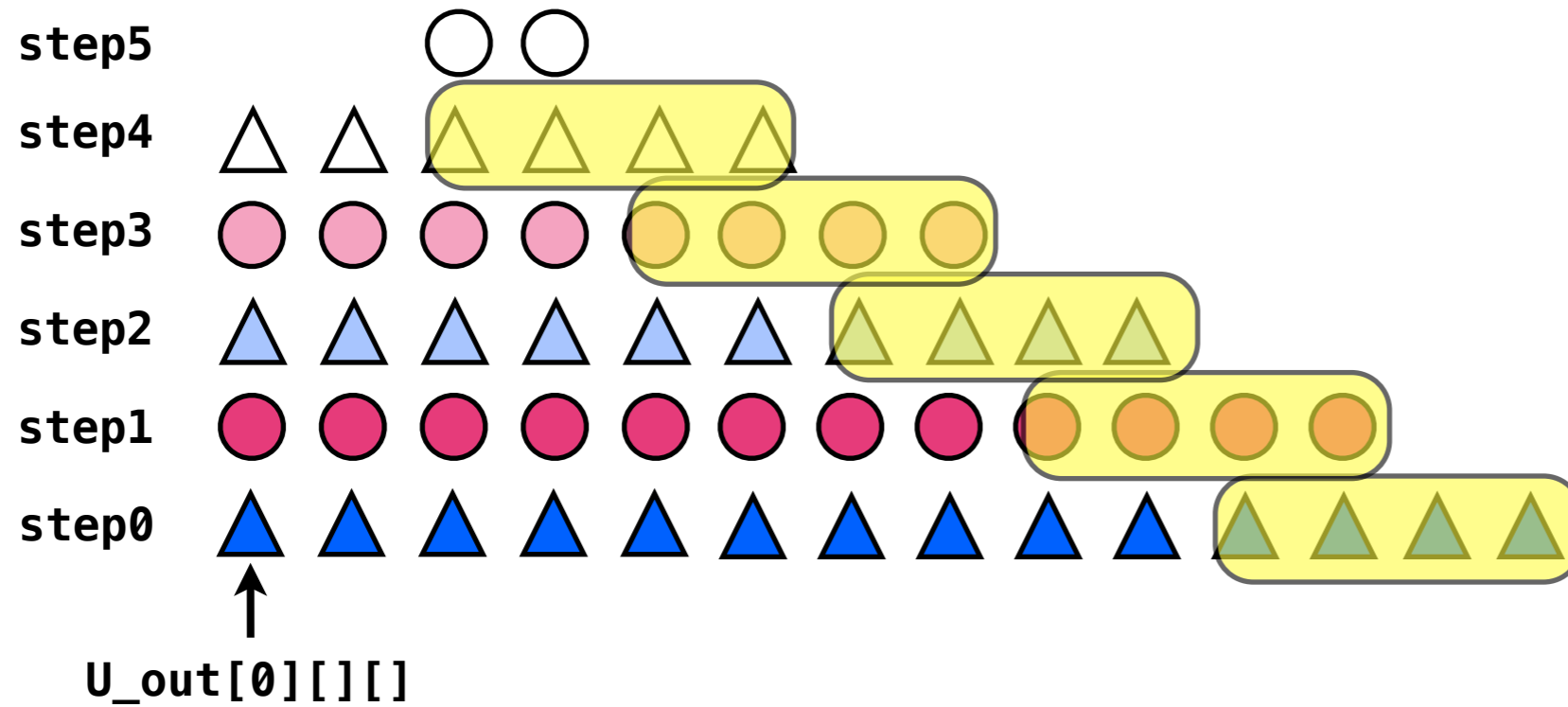
# Time-Skewing Approach Description(5 steps, tile size = 4)

●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$



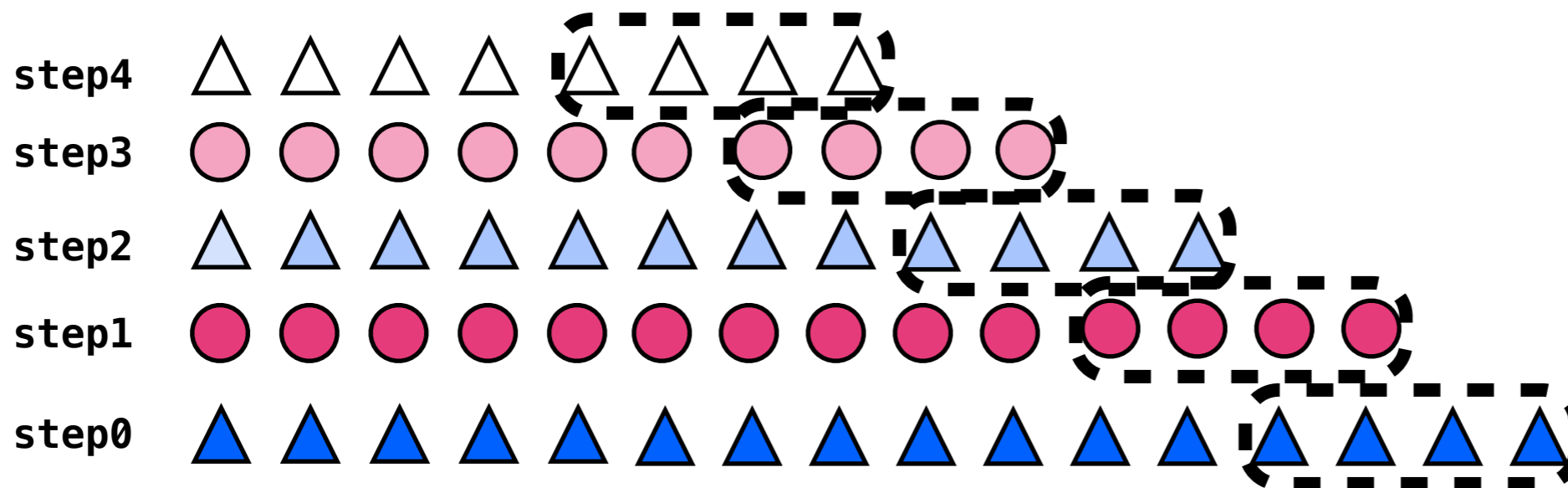
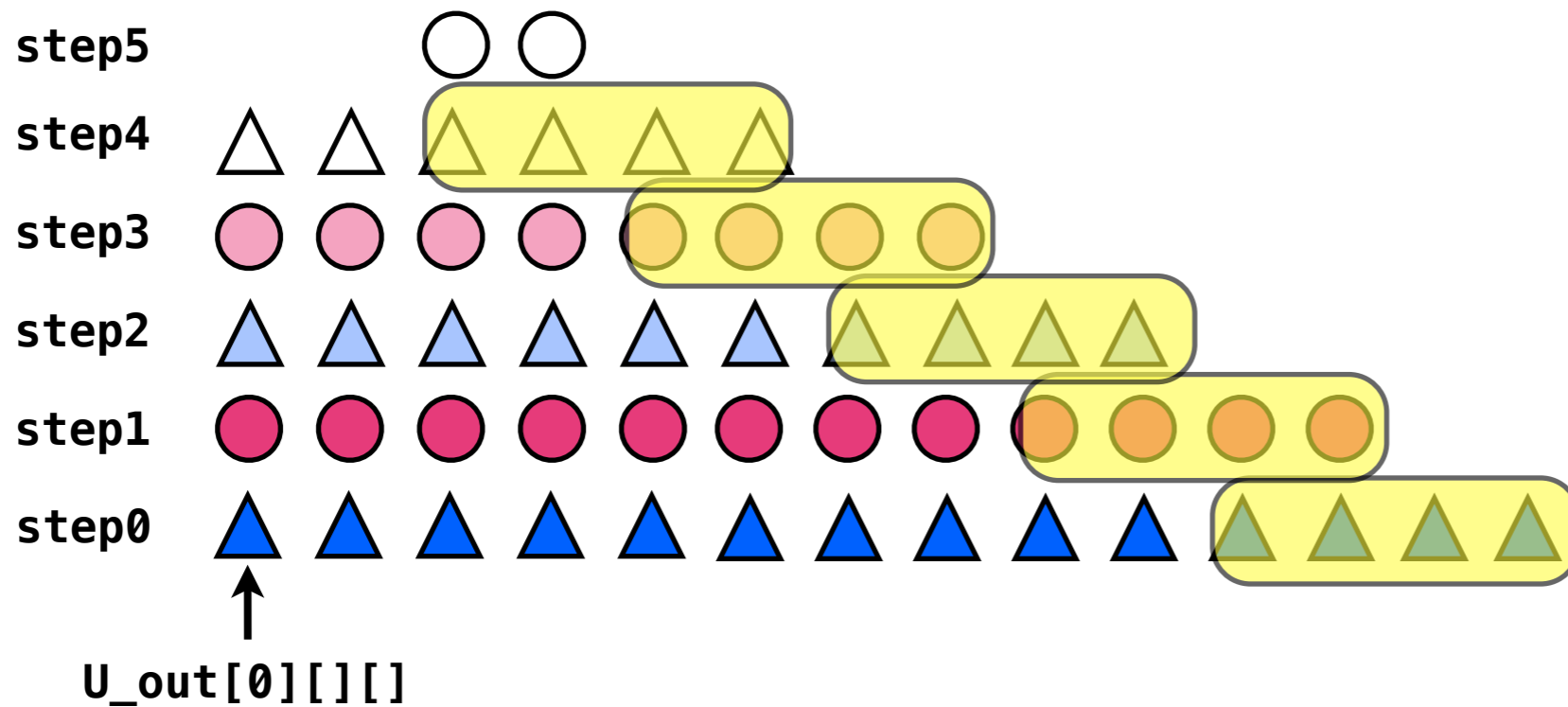
# Time-Skewing Approach Description (5 steps, tile size = 4)

●  $U_{out}[k][][[]]$      ▲  $U_{in}[k][][[]]$



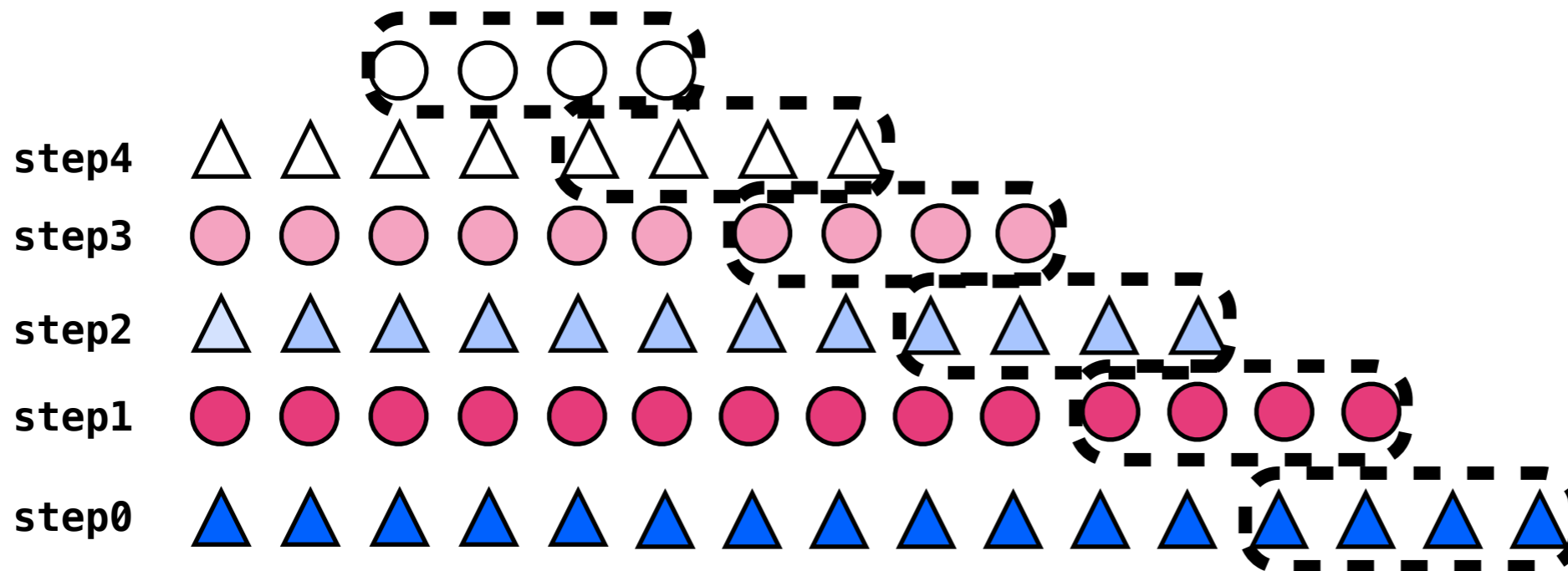
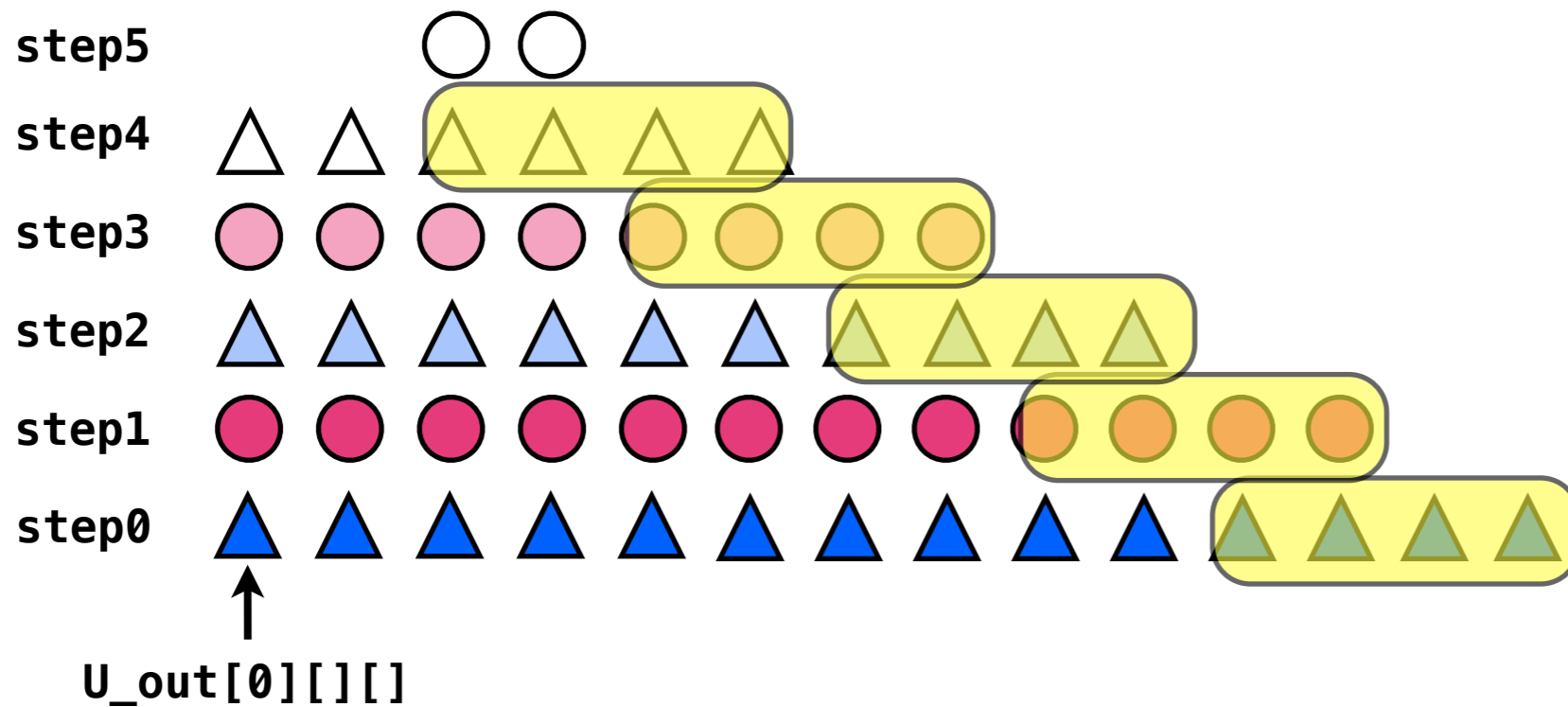
# Time-Skewing Approach Description(5 steps, tile size = 4)

●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$



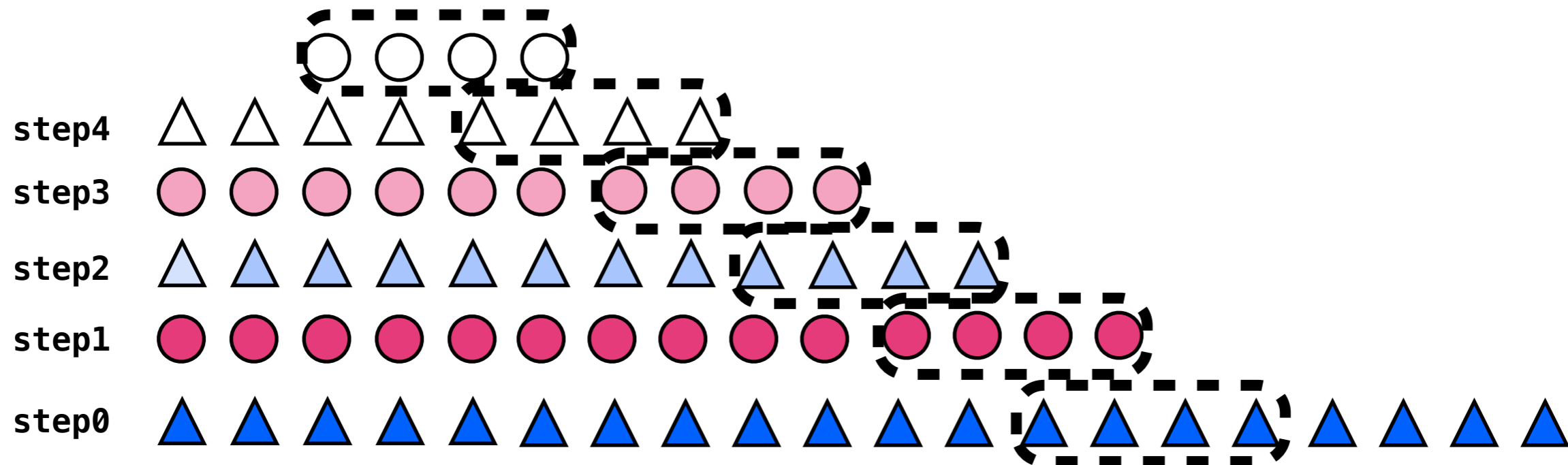
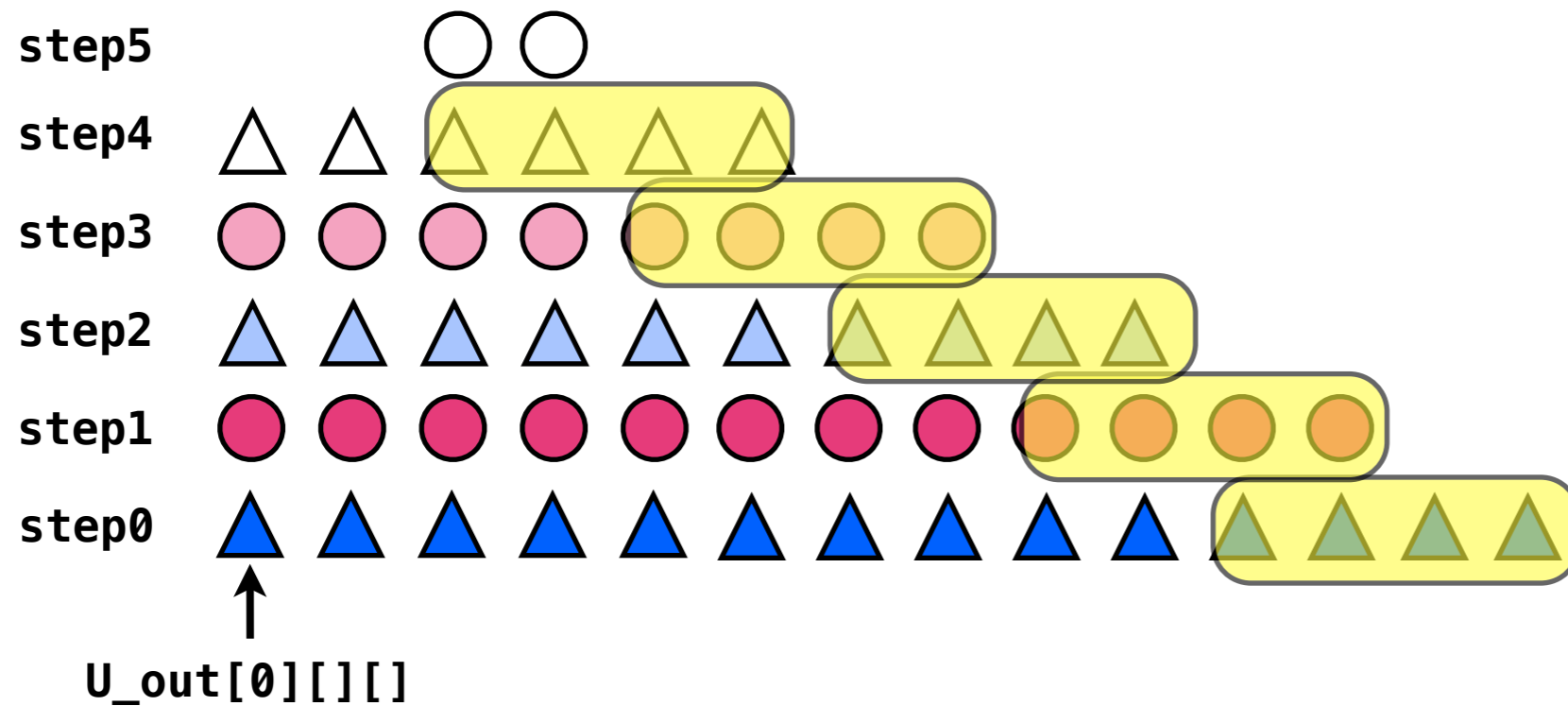
# Time-Skewing Approach Description(5 steps, tile size = 4)

●  $U_{out}[k][][[]]$    
 ▲  $U_{in}[k][][[]]$



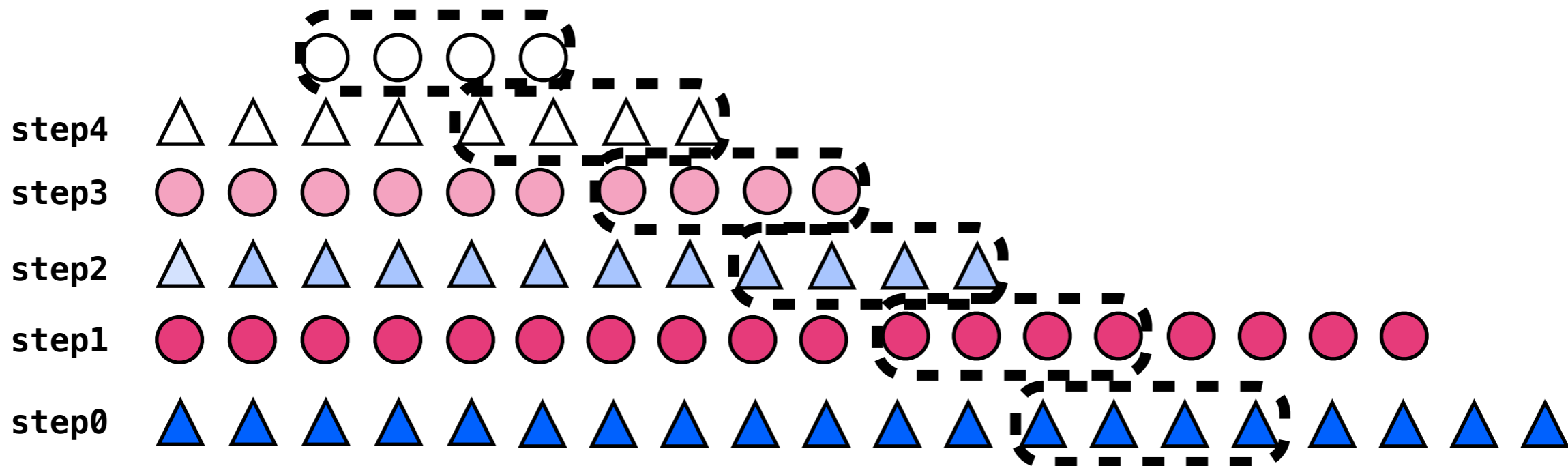
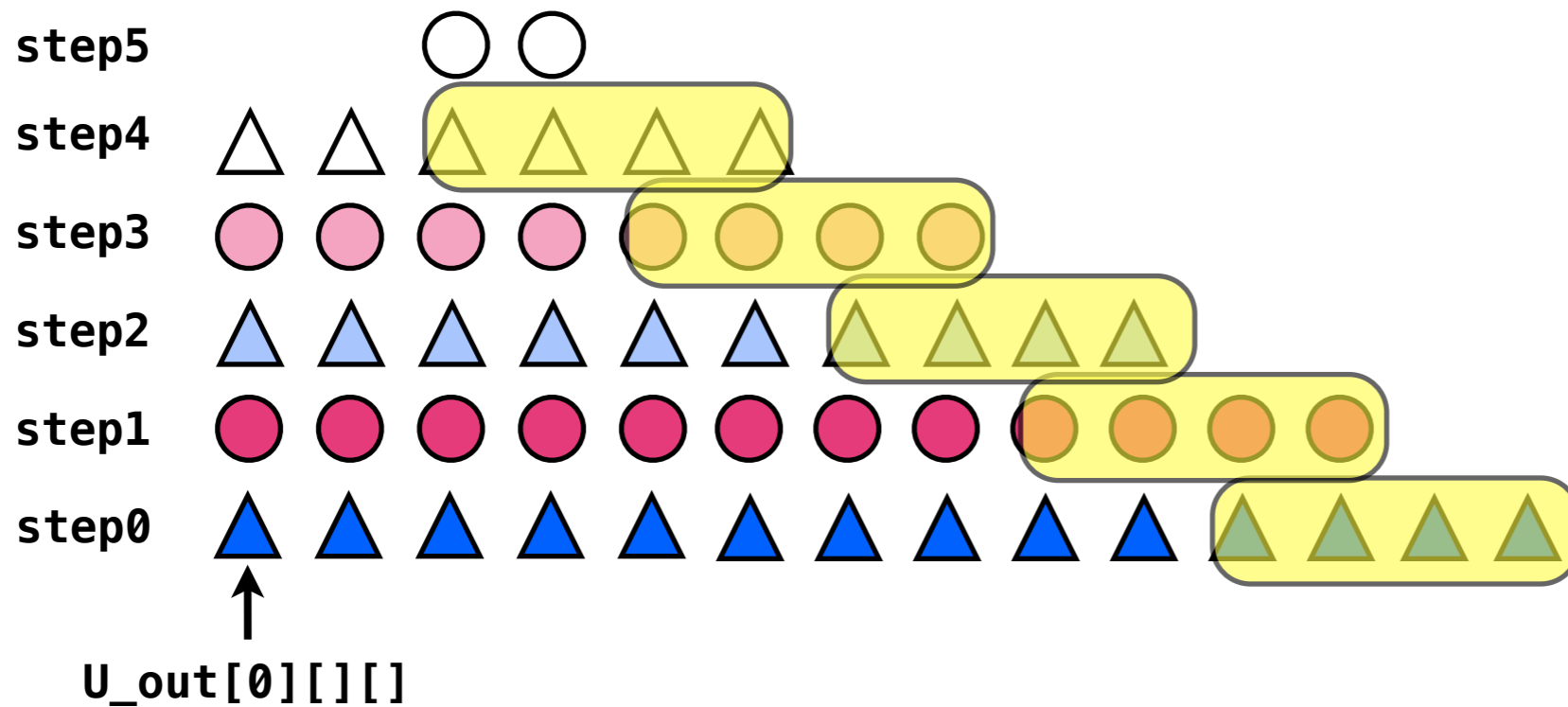
# Time-Skewing Approach Description (5 steps, tile size = 4)

●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$



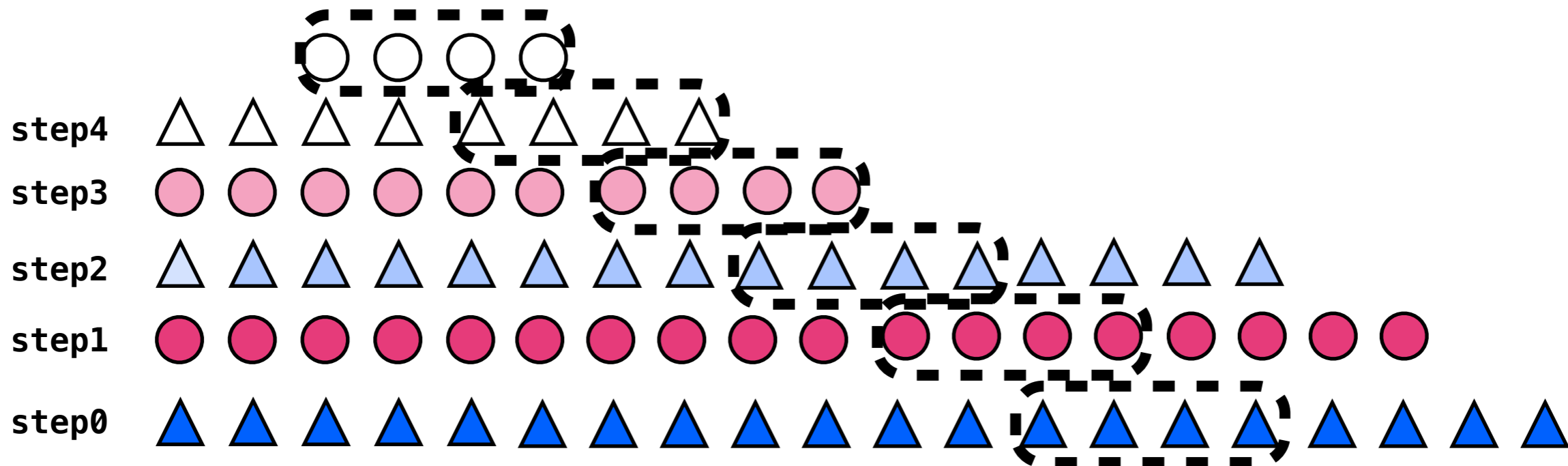
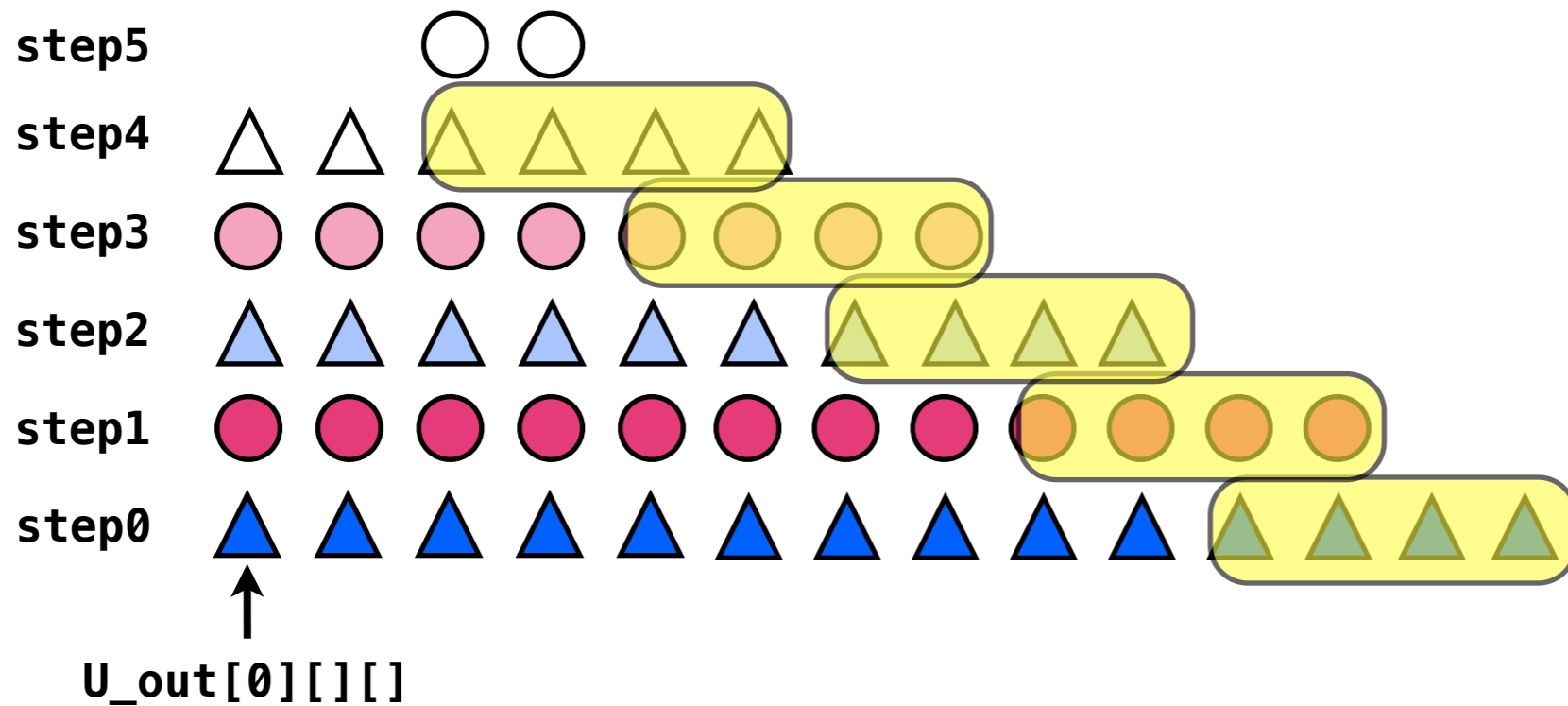
# Time-Skewing Approach Description(5 steps, tile size = 4)

●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$



# Time-Skewing Approach Description(5 steps, tile size = 4)

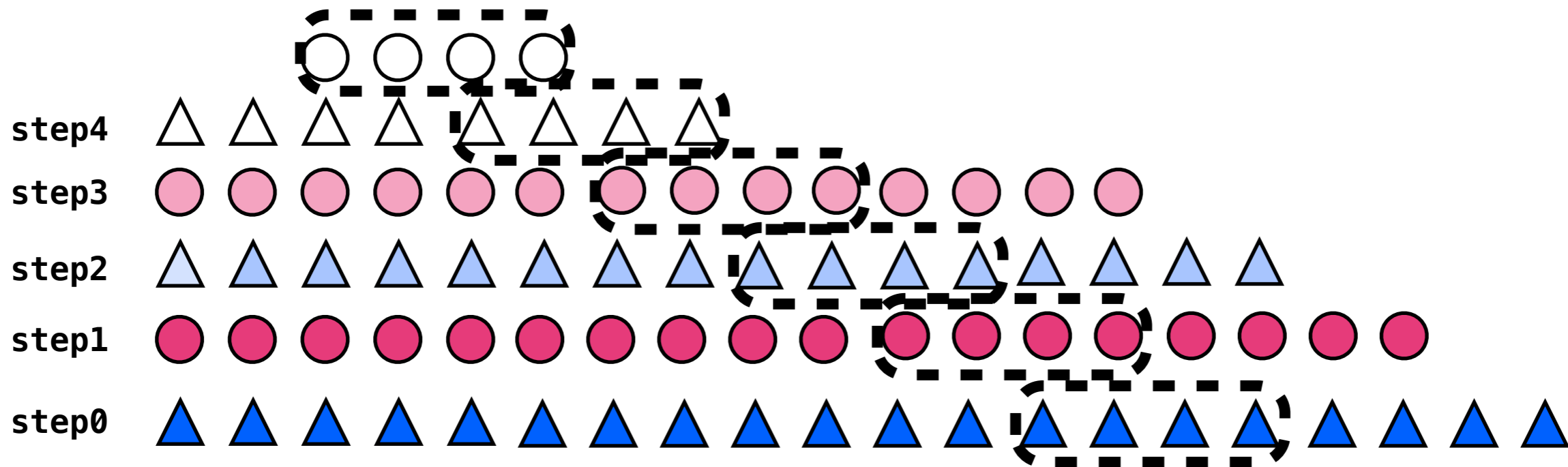
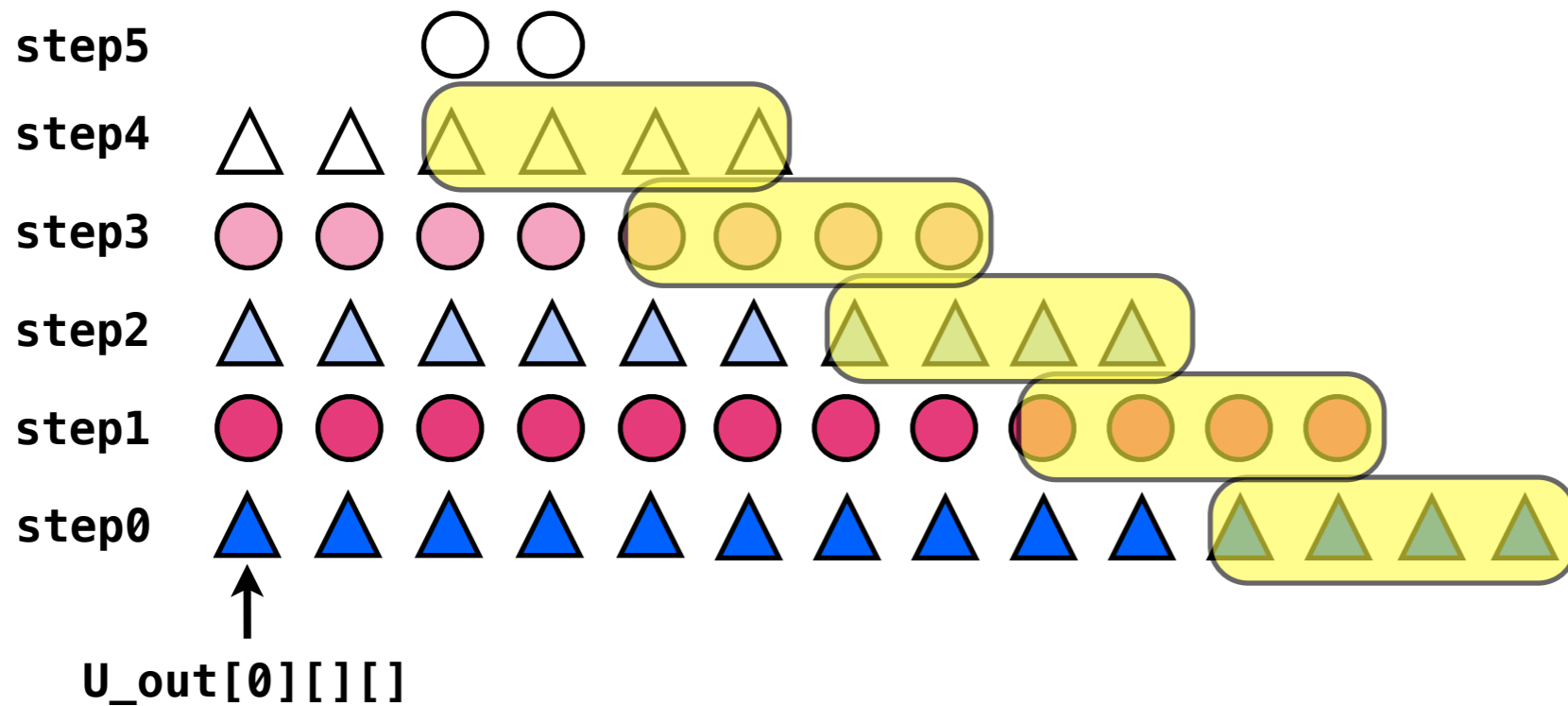
●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$





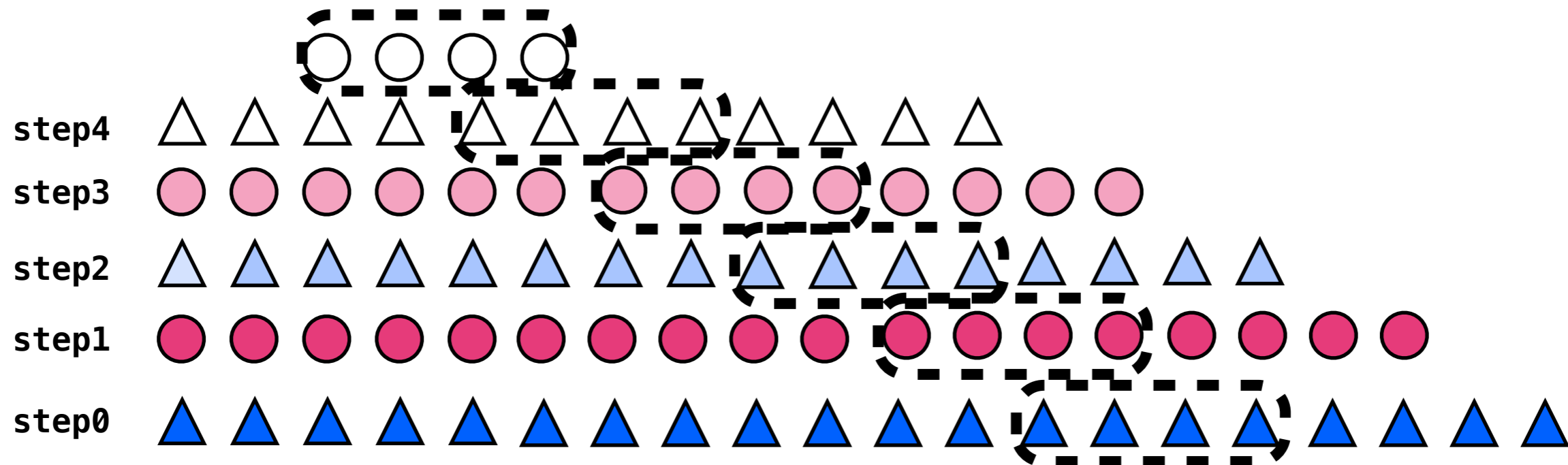
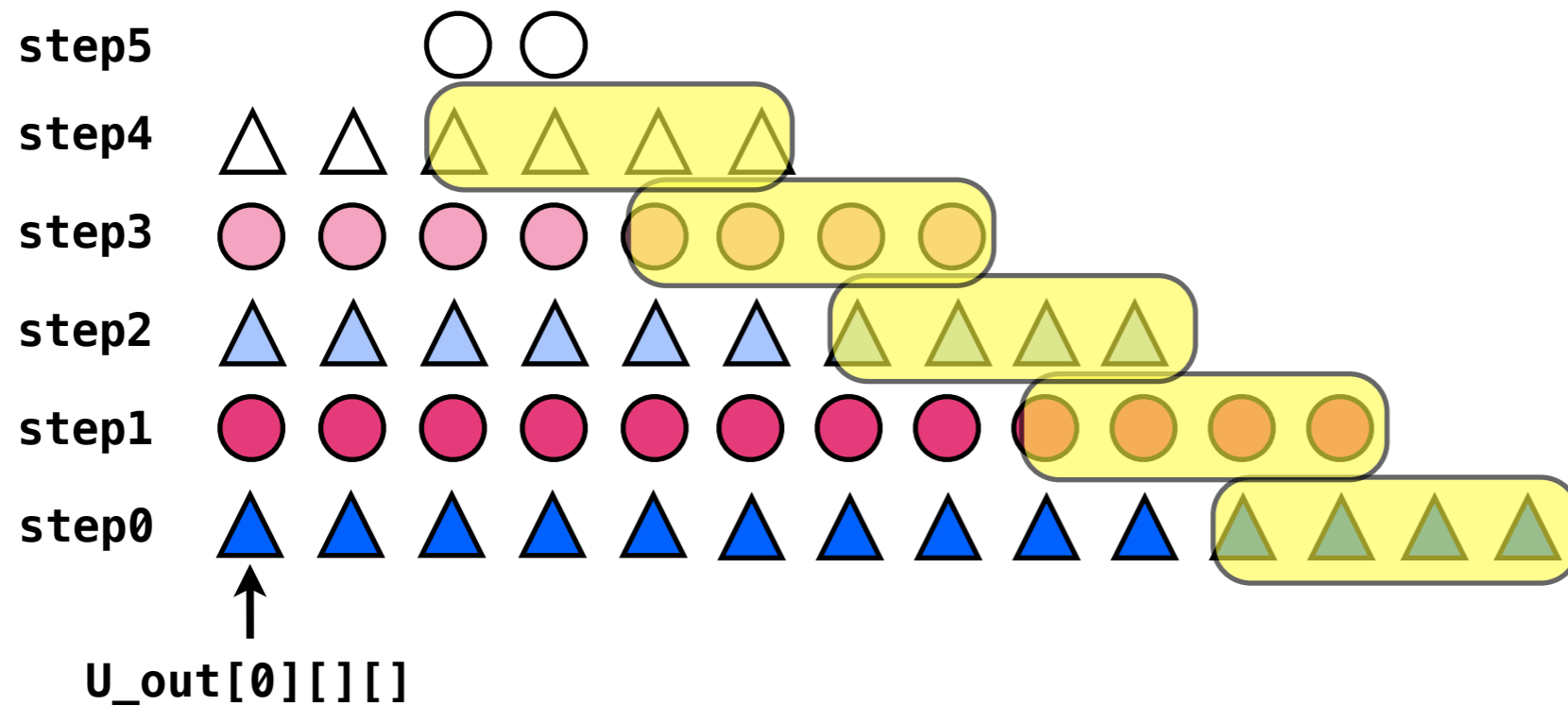
# Time-Skewing Approach Description(5 steps, tile size = 4)

●  $U_{out}[k][][[]]$      ▲  $U_{in}[k][][[]]$



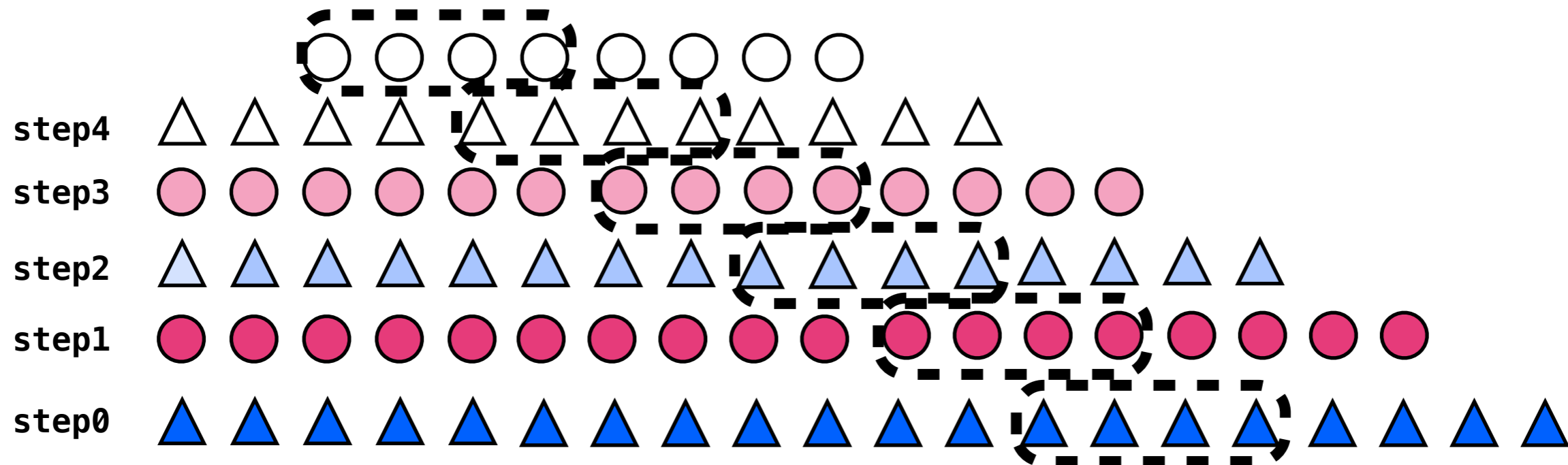
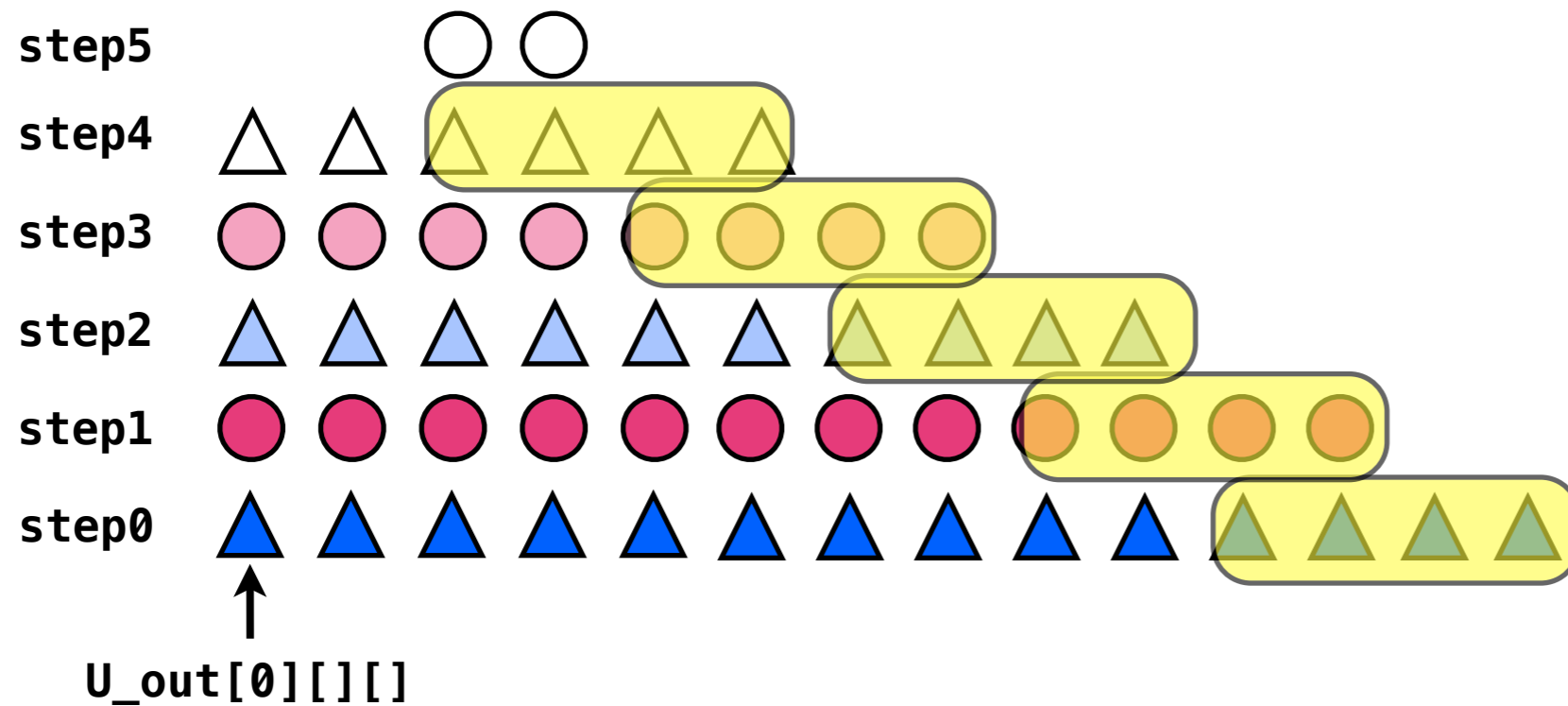
# Time-Skewing Approach Description(5 steps, tile size = 4)

●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$



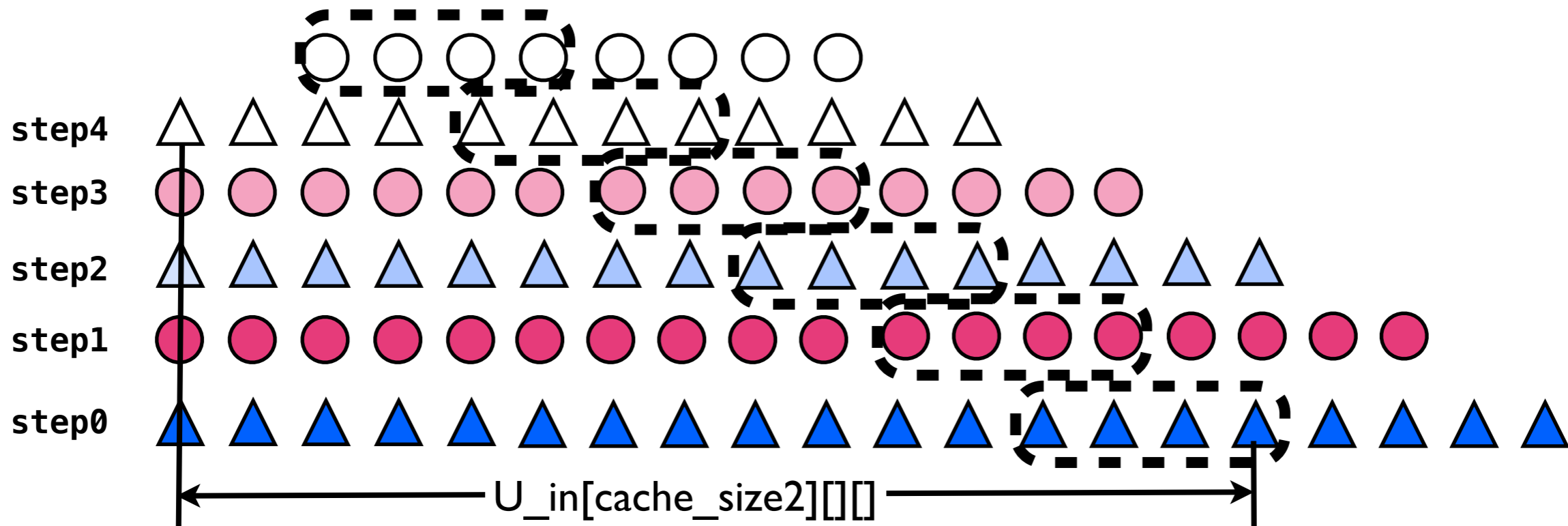
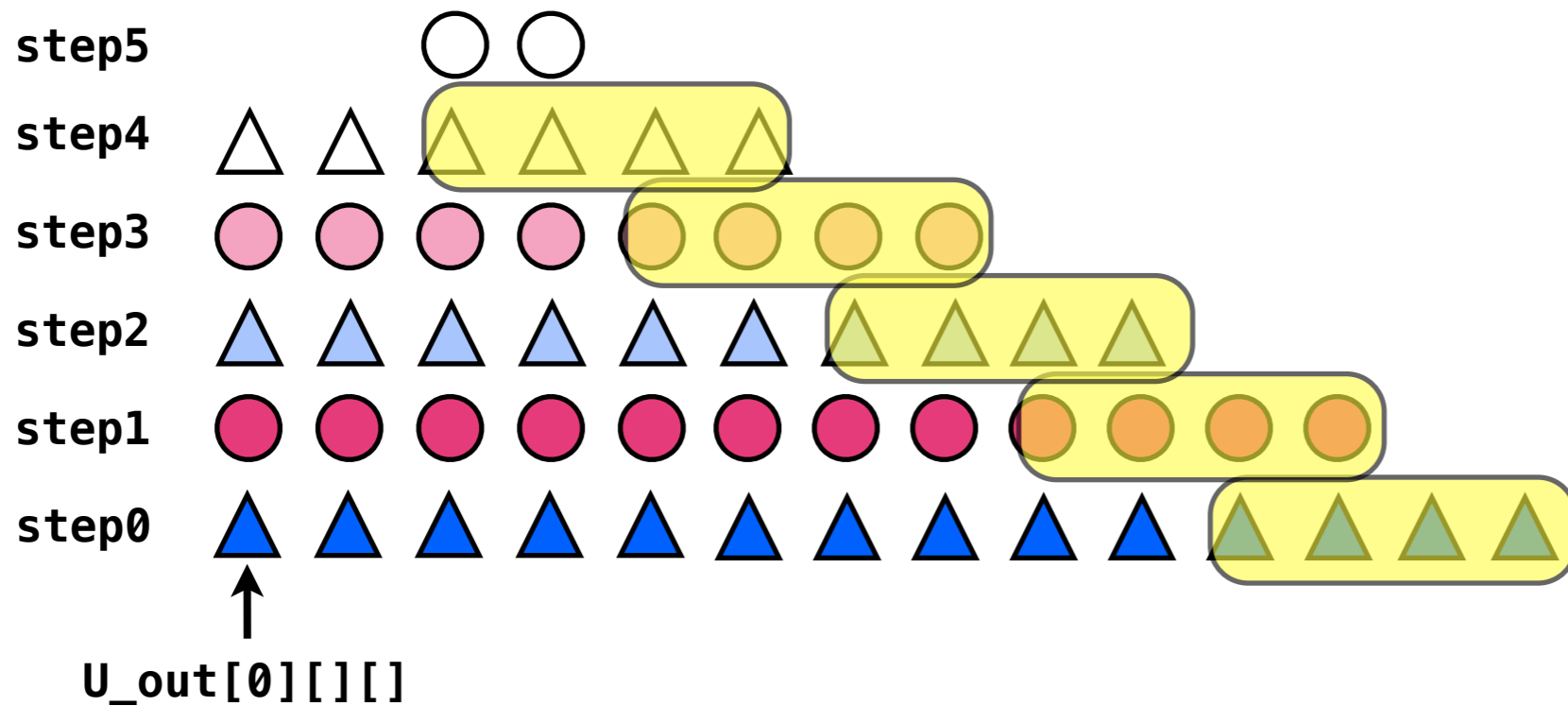
# Time-Skewing Approach Description(5 steps, tile size = 4)

●  $U_{out}[k][][[]]$      ▲  $U_{in}[k][][[]]$



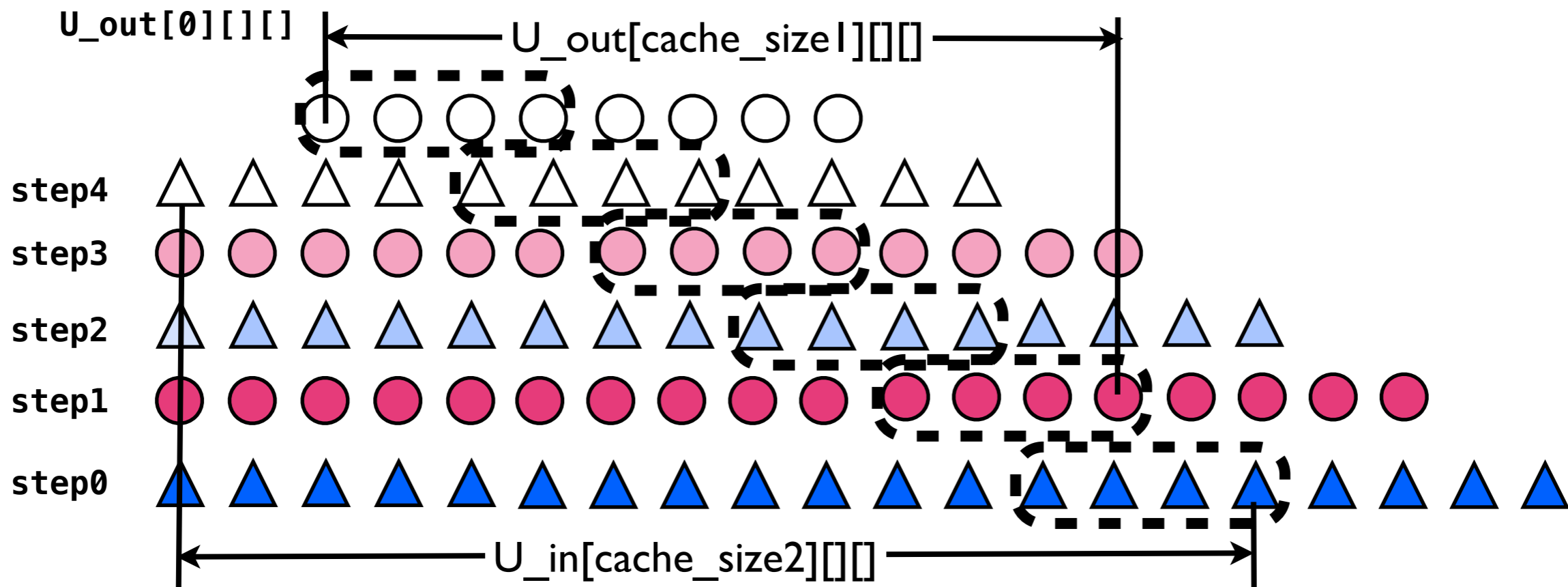
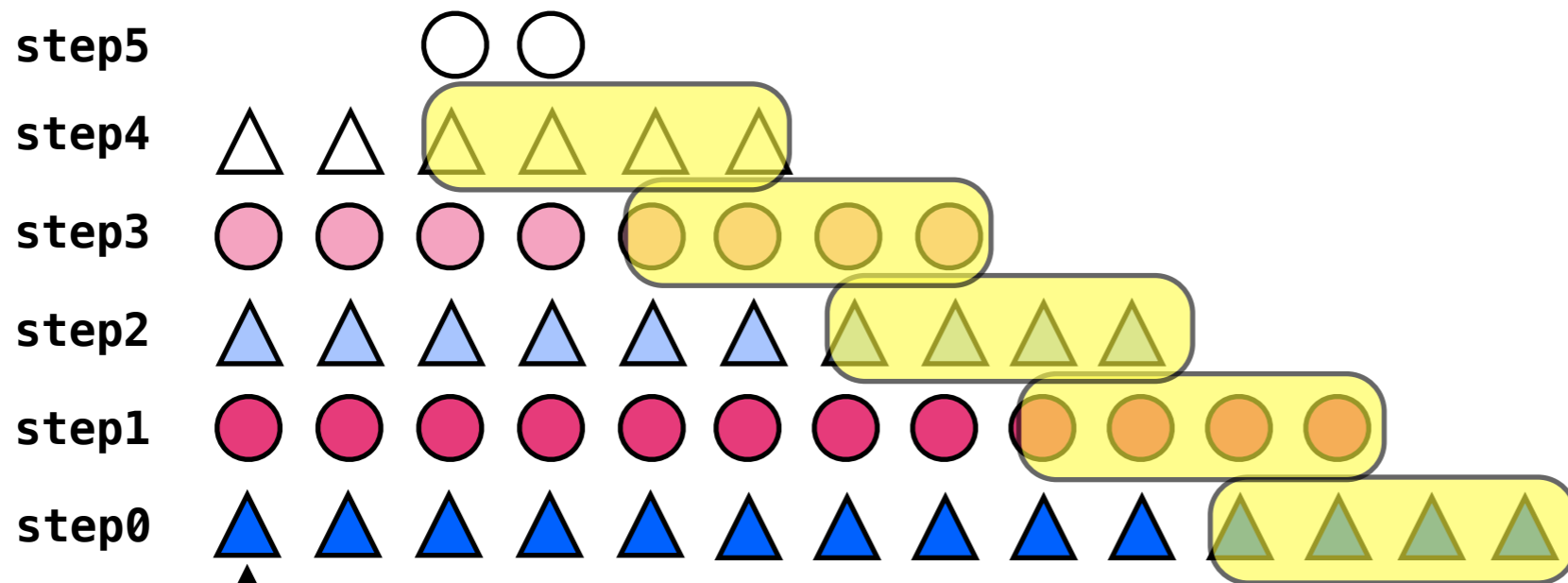
# Time-Skewing Approach Description (5 steps, tile size = 4)

●  $U\_out[k][][[]]$     ▲  $U\_in[k][][[]]$



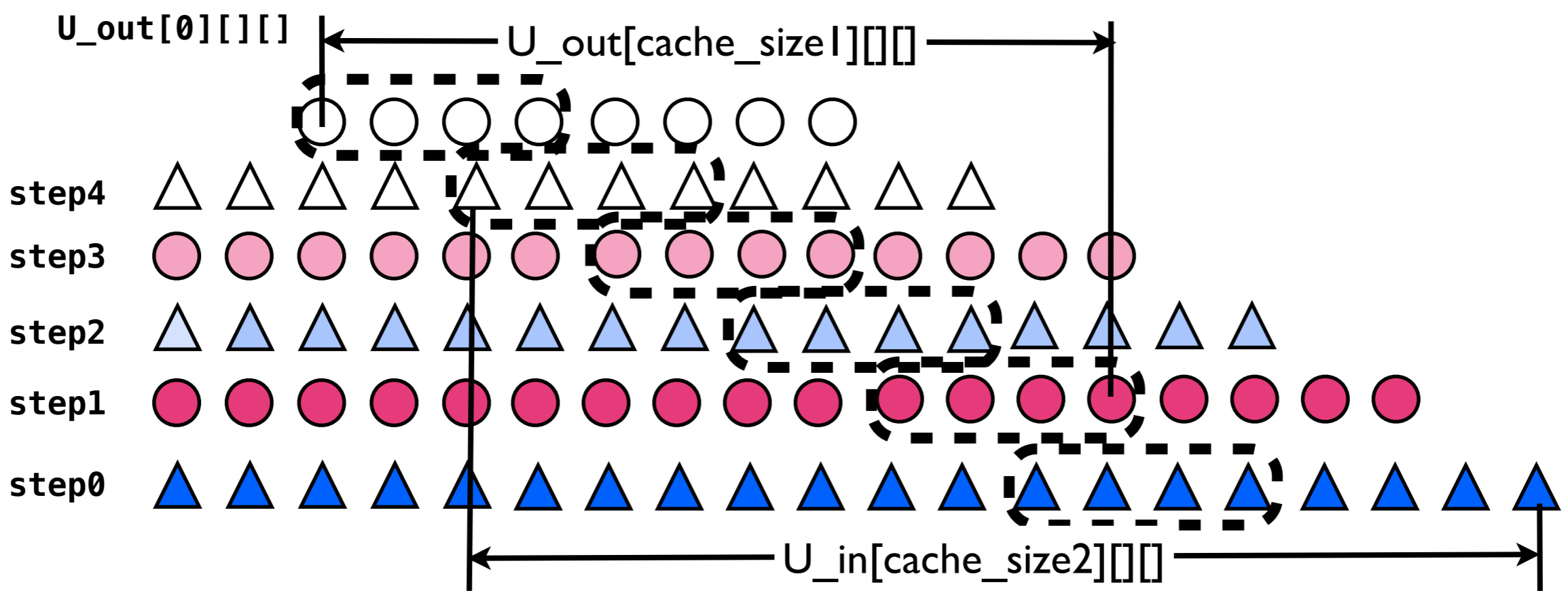
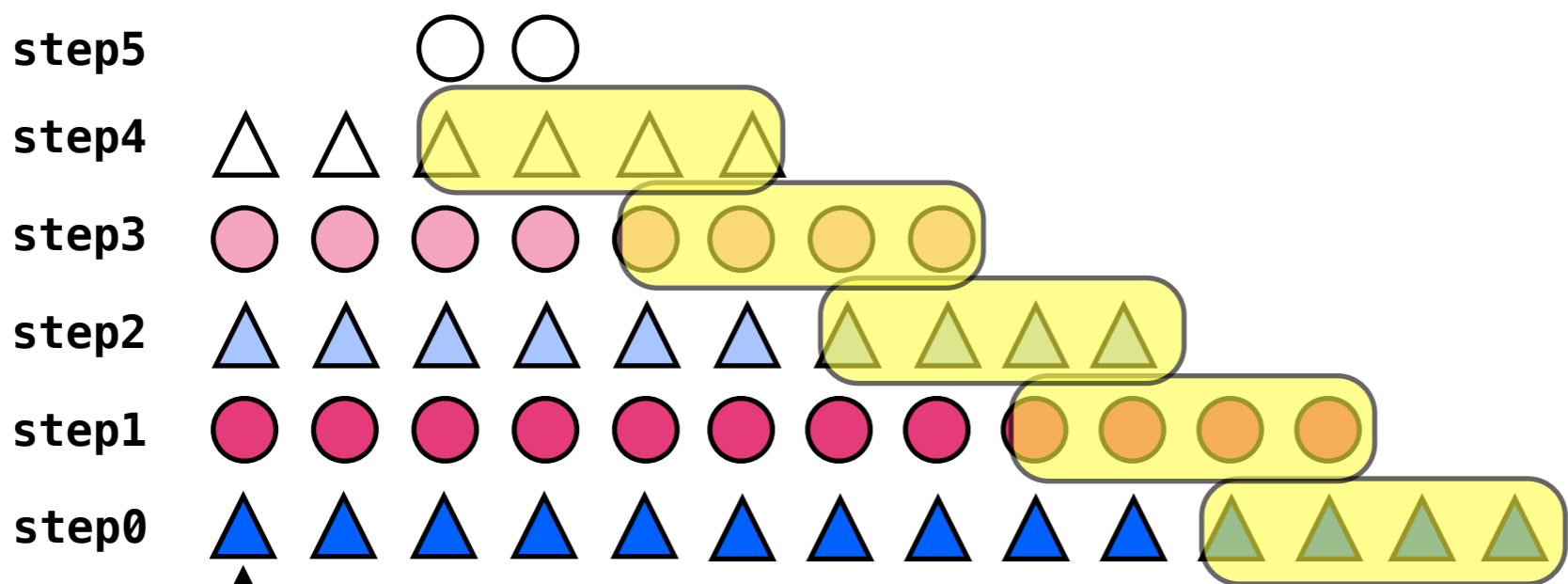
# Time-Skewing Approach Description (5 steps, tile size = 4)

●  $U_{out}[k][][[]]$      ▲  $U_{in}[k][][[]]$



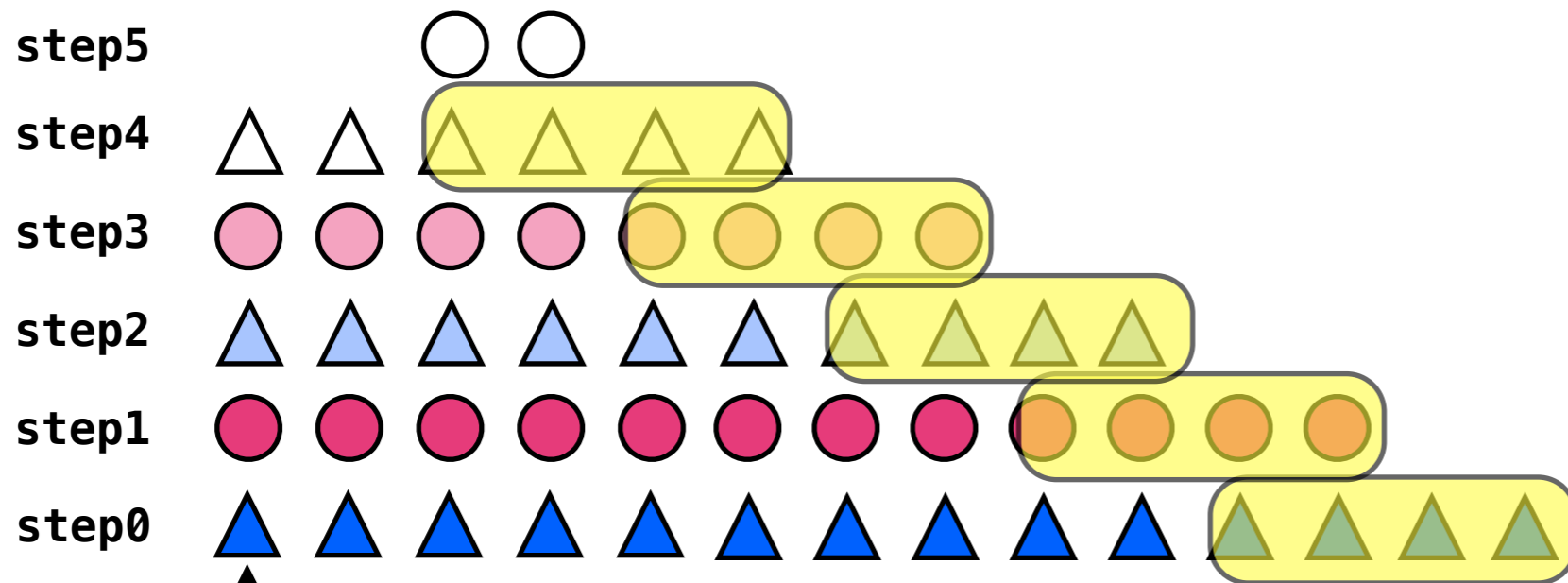
# Time-Skewing Approach Description (5 steps, tile size = 4)

●  $U_{out}[k][][[]]$      ▲  $U_{in}[k][][[]]$

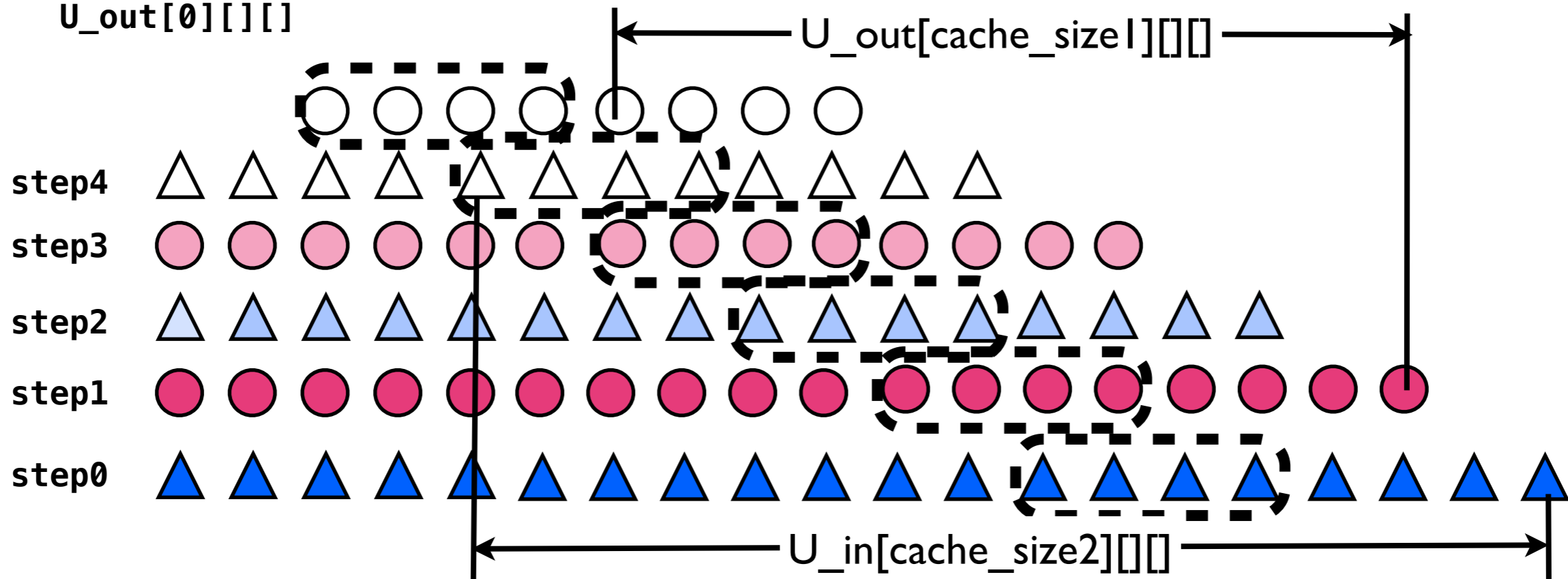


# Time-Skewing Approach Description(5 steps, tile size = 4)

●  $U_{out}[k][][[]]$     ▲  $U_{in}[k][][[]]$



$U_{out}[0][][[]]$



## Time-Skewing Approach Analysis

TS denotes the number of time steps performed in one iteration described in the previous slide

The number of planes expected in cache (cache\_size1 + cache\_size2):  $4*TS + 8$

$(4*TS + 8)*260*260*4 \leq 12*10^6$  implies  $TS \leq 9.0947$

## Comparing with the naive code

Time-skewing: 2 loads + 2 stores produces TS iterations

Naive:  $2*TS$  loads +  $2*TS$  stores produces TS iterations

## Results

Run on DAVinCI(exclusive node)

Grid size:  $260*260*260$

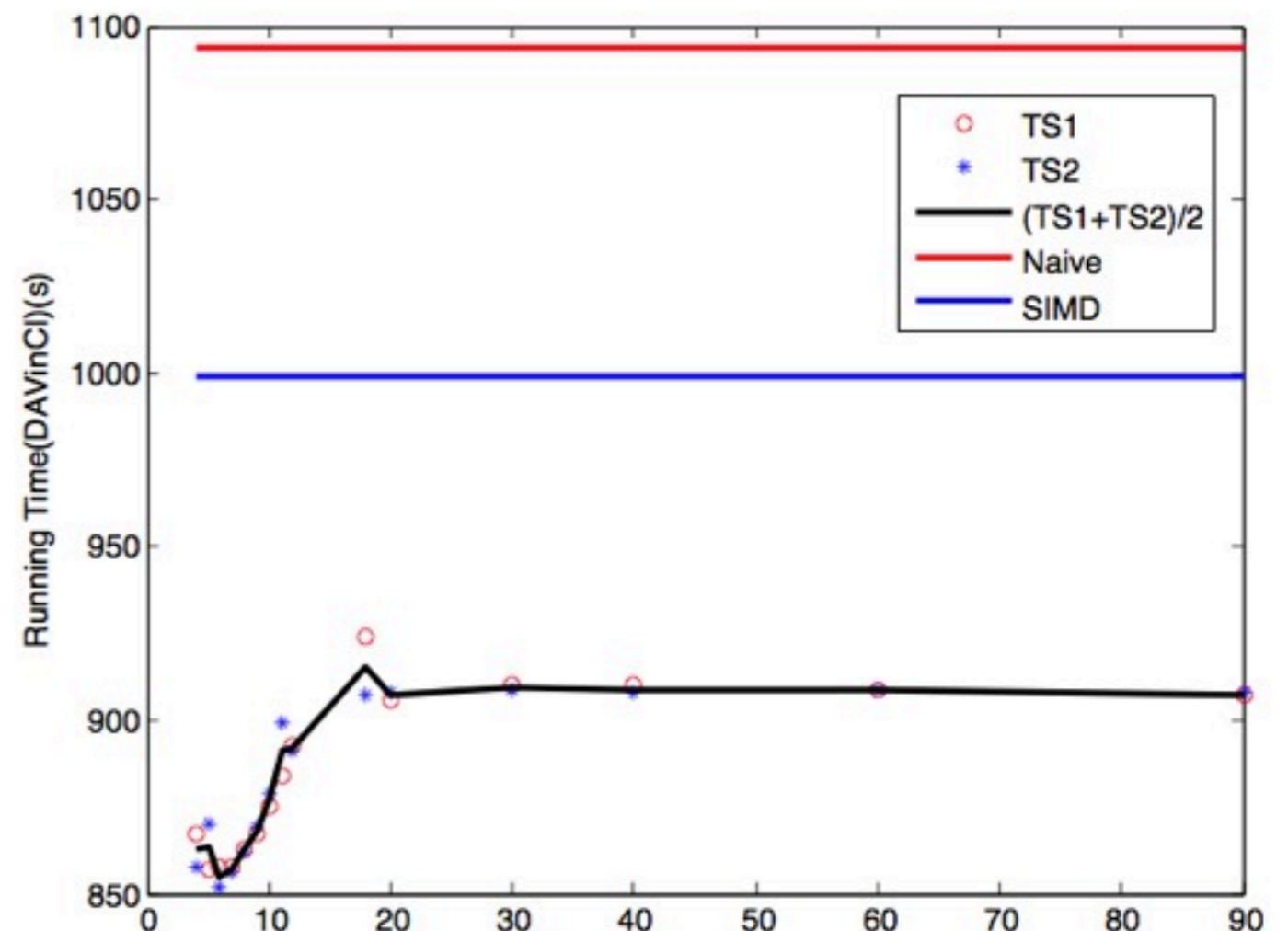
Total time steps: 27721

Data Type: float

Computing Difference:

$TS \sim 2.6e-8$ ,  $SIMD \sim 5.19e-7$

(naive: 0.0013 ~ -0.0015)





## Future Research:

1. Perform experiments with stencil codes of higher order (Finite difference scheme with higher spatial error order)
2. Work out a method to deduce the optimal tile size and time step without the need to do the experiments
3. Integrate onto IWAVE package to enhance its computation capability of the stencil kernel.
4. Modifications for the codes if the coefficients are not constant or changing between two time steps.
5. ...

Thanks! Suggestions?